

# Modal Crash Types for Intermittent Computing

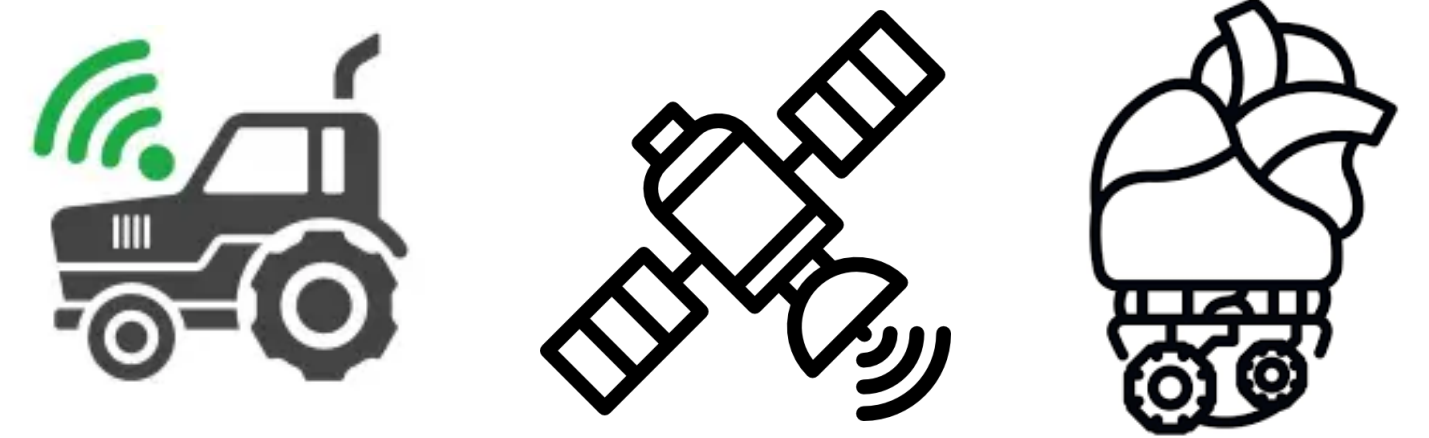
**Myra Dotzel**  
**PhD student, CSD, CMU**

**Joint work with Farzaneh Derakhshan,  
Milijana Surbatovich, and Limin Jia**



# Intermittent Computing

- tiny devices that compute in inaccessible environments



Ckpt

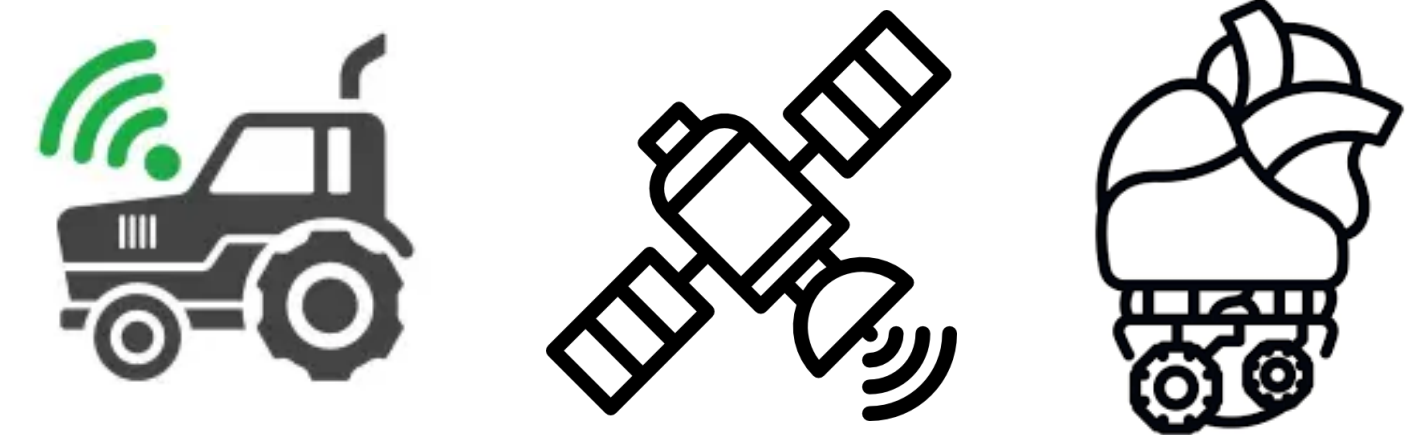
$x := y;$

$y := z;$

$w := x + y$

# Intermittent Computing

- tiny devices that compute in inaccessible environments
- cannot rely on continuous energy sources



Ckpt

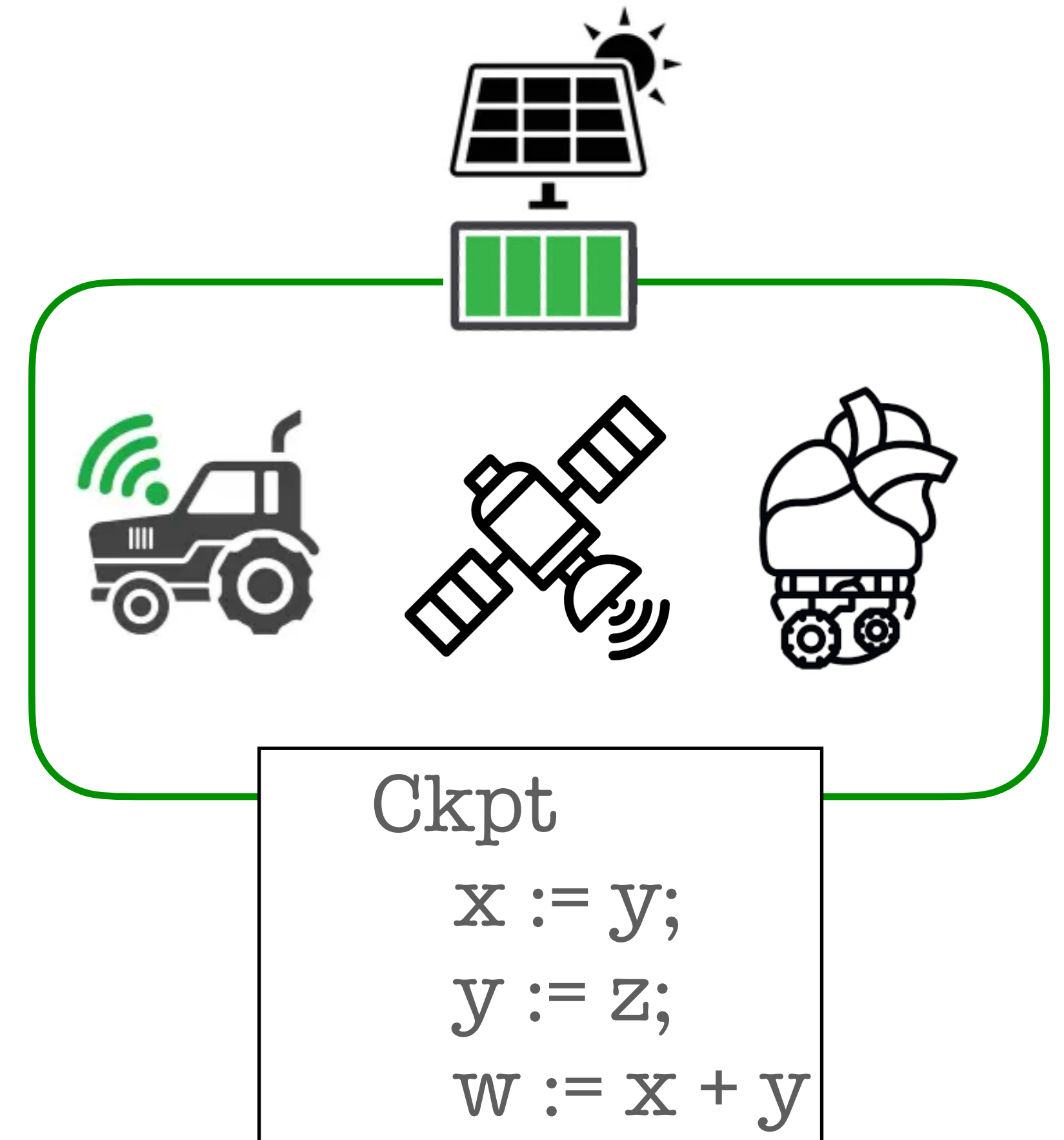
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$w := x + y$

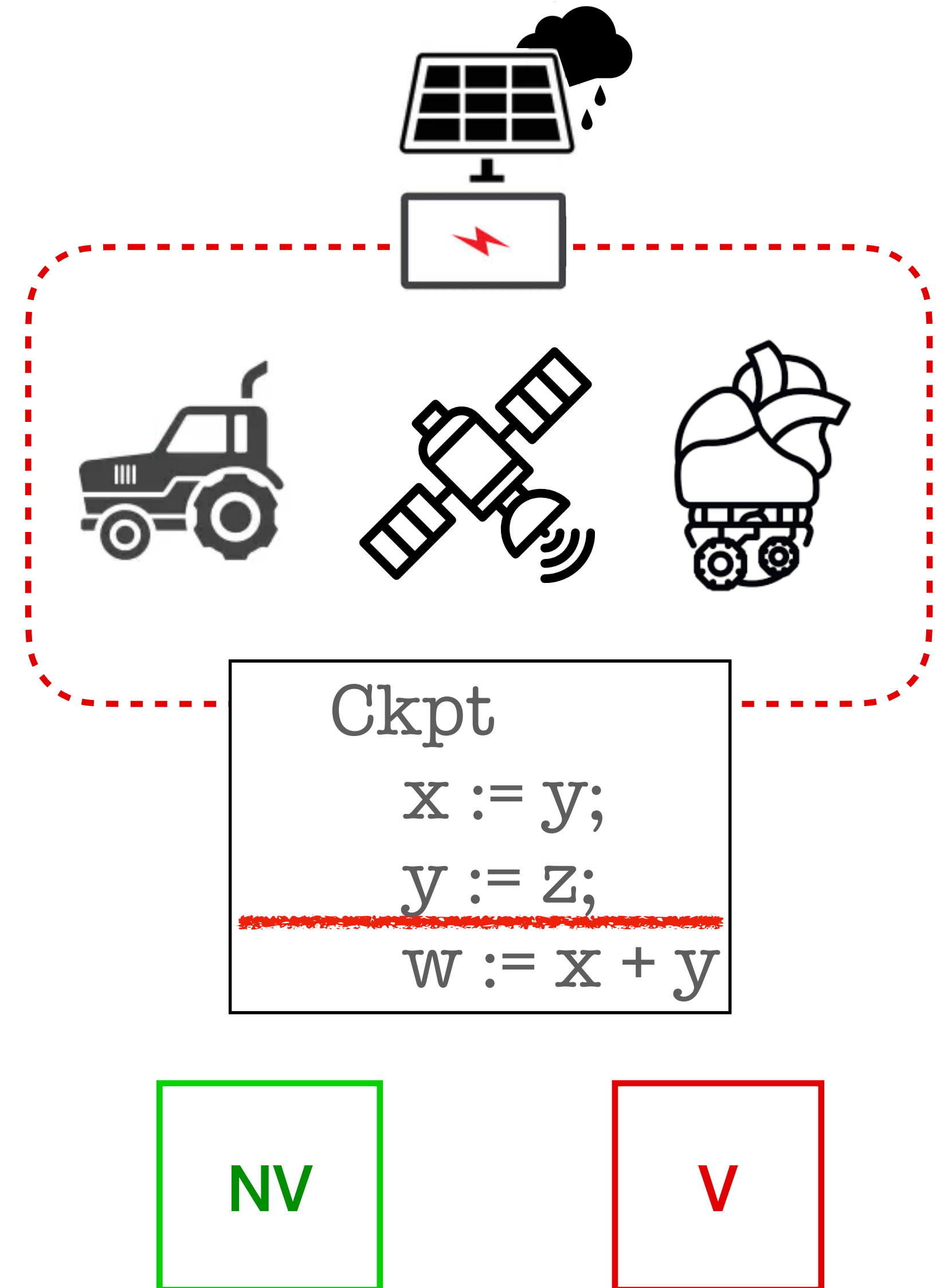
# Intermittent Computing

- tiny devices that compute in inaccessible environments
- cannot rely on continuous energy sources
- charge, compute, and crash frequently



# Intermittent Computing

- tiny devices that compute in inaccessible environments
- cannot rely on continuous energy sources
- charge, compute, and crash frequently
- rely on a combination of **NV** and **V**
- **NV** survives power failures, **V** does not
- runtime system support



# Checkpointing depends on execution mode



Ckpt

$x := y;$

$y := z;$

---

$w := x + y$

Atomic region



let  $x = 5$  in

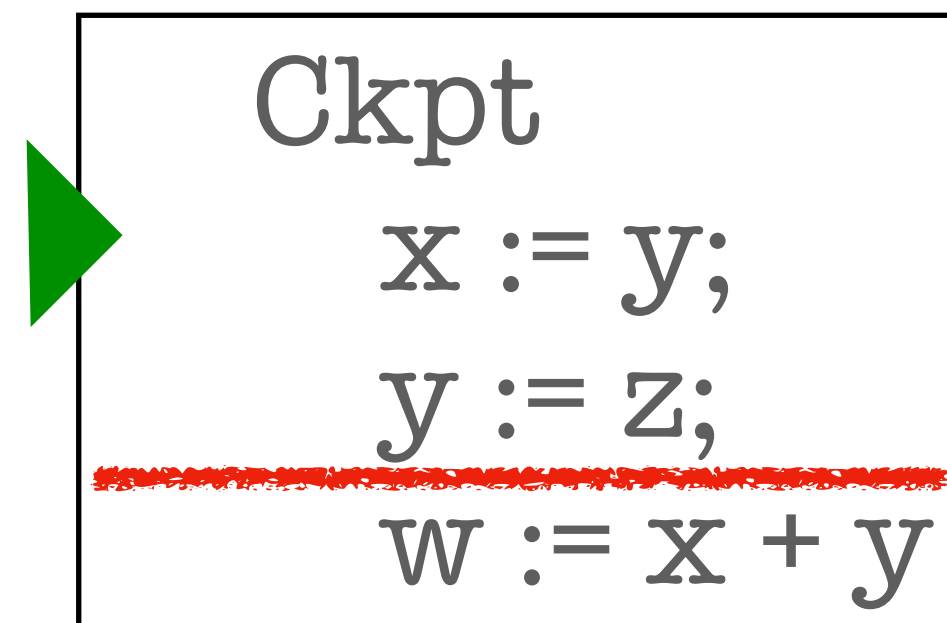
$c := x + 1;$

---

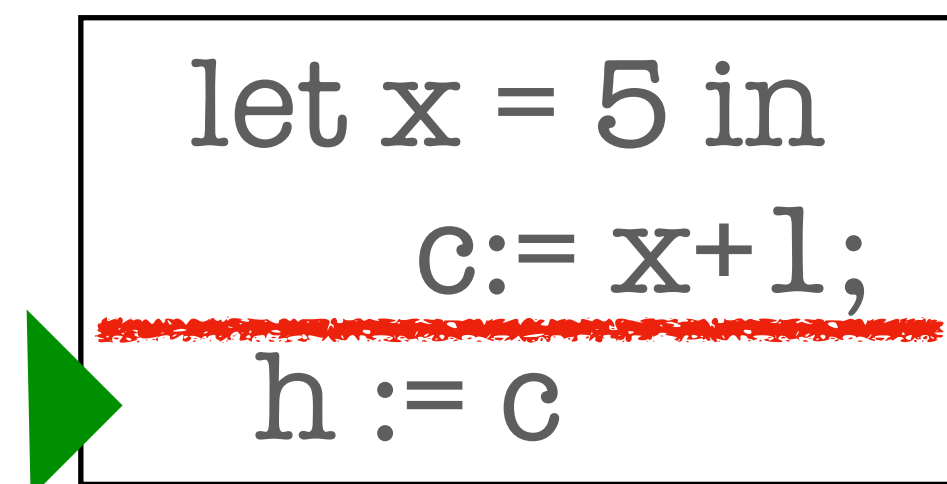
$h := c$

JIT region

# Checkpointing depends on execution mode



Atomic region

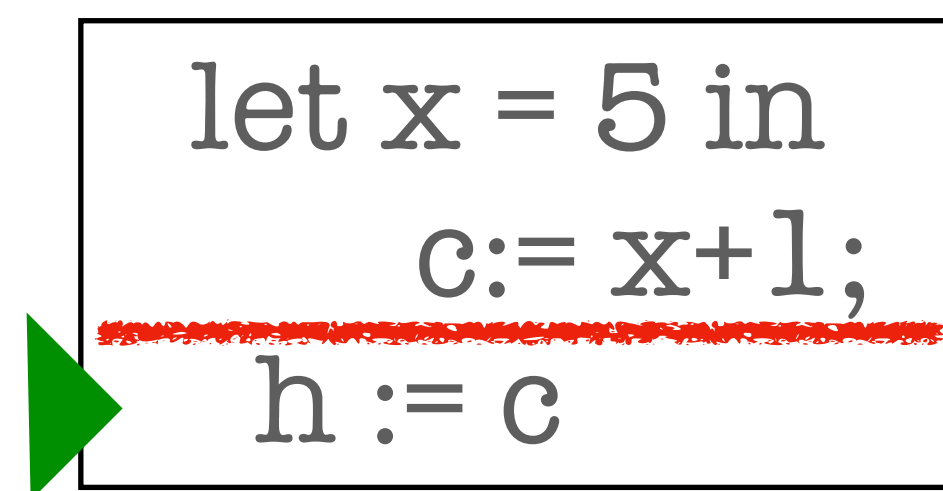
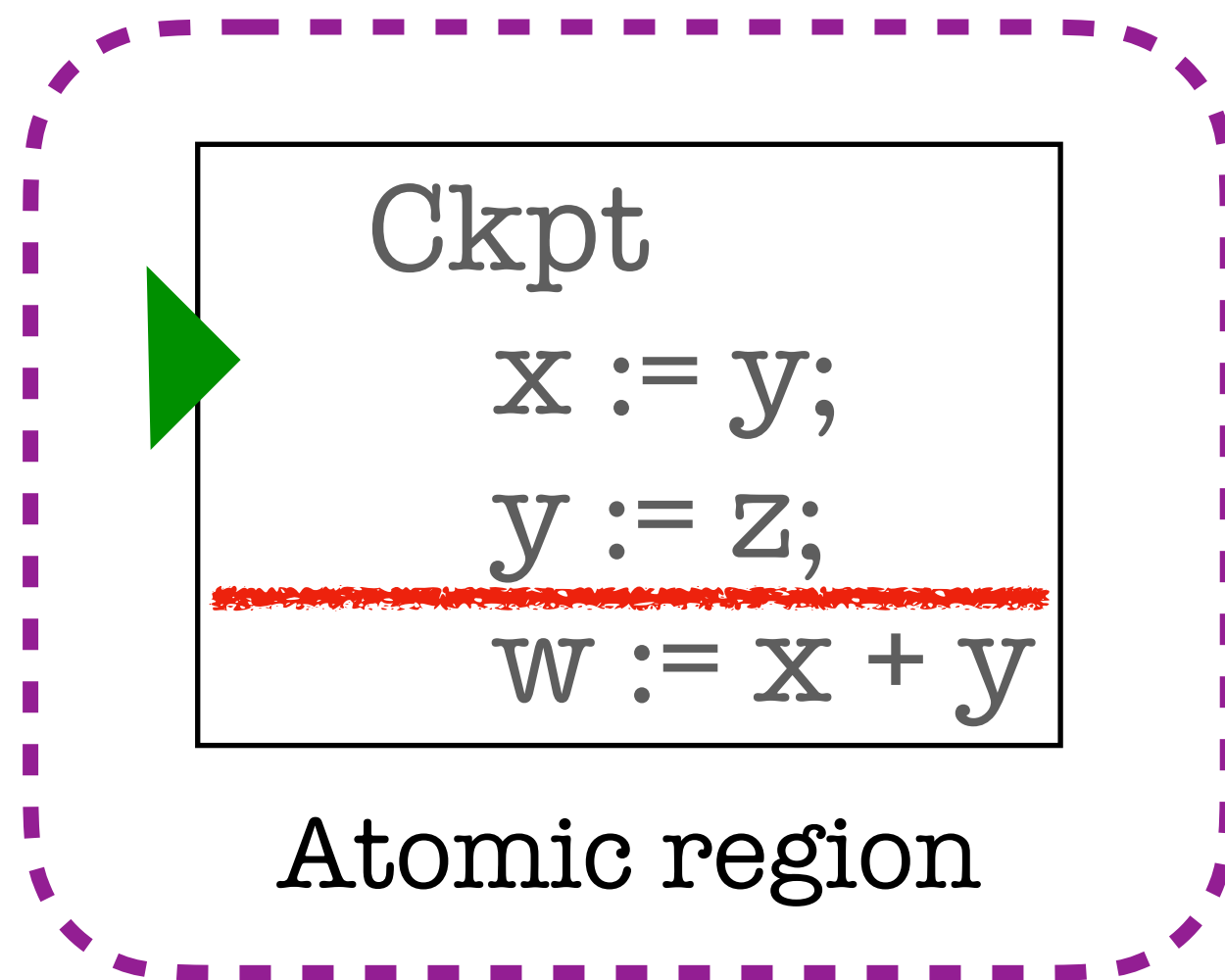


JIT region



Atomic regions checkpoint ahead of time.

# Checkpointing depends on execution mode

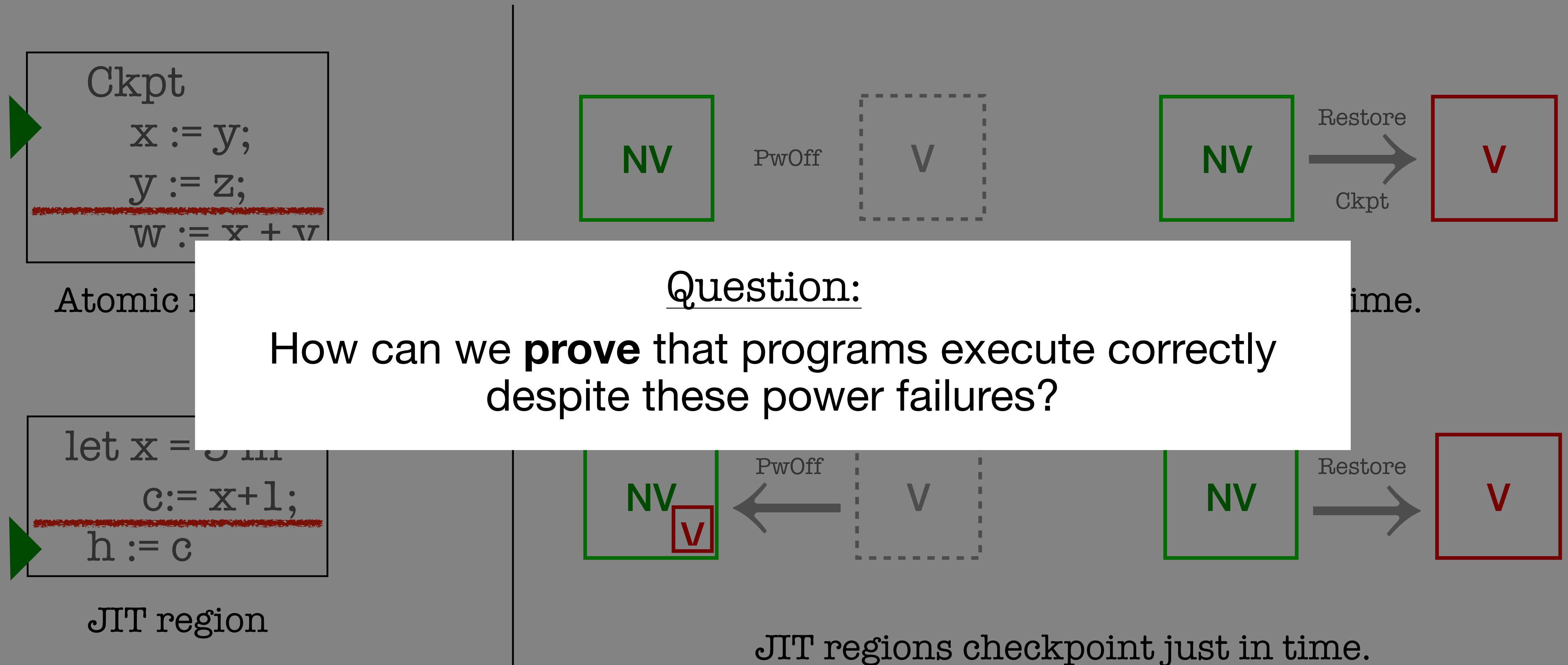


Atomic regions checkpoint ahead of time.

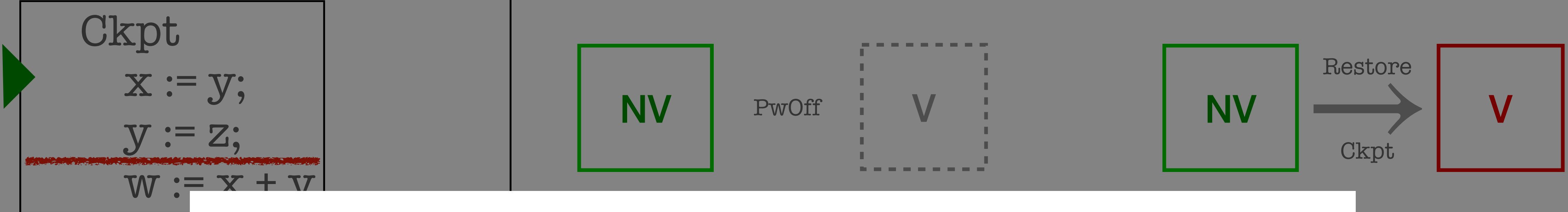


JIT regions checkpoint just in time.

# Checkpointing depends on execution mode

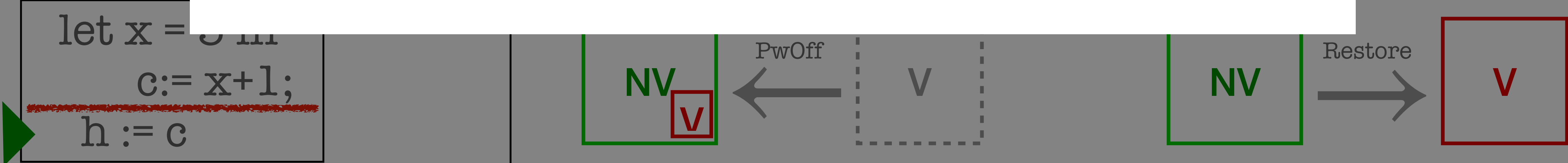


# Checkpointing depends on execution mode



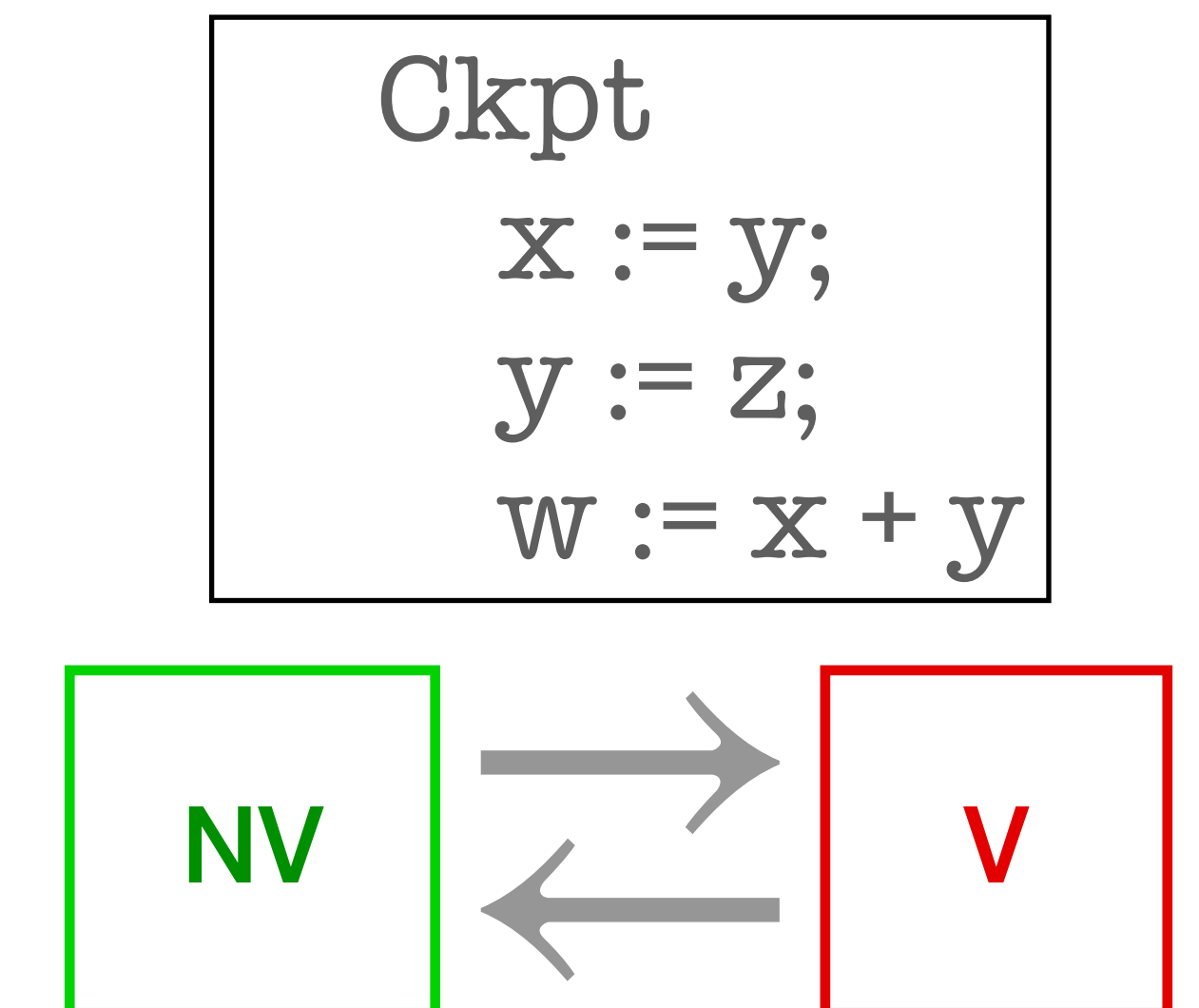
Answer:

It depends on what we checkpoint!



JIT regions checkpoint just in time.

# What do we need to checkpoint?



# Checkpoint nothing

```
1 Ckpt()  
2   x := y;  
3   y := z;  
4   w := x + y
```



|    |   |   |   |   |
|----|---|---|---|---|
| NV | x | y | z | w |
| 1  | 0 | 1 | 2 | 0 |
| 2  | 1 | 1 | 2 | 0 |
| 3  | 1 | 2 | 2 | 0 |



|    |   |   |   |   |
|----|---|---|---|---|
| NV | x | y | z | w |
| 1  | 0 | 1 | 2 | 0 |
| 2  | 1 | 1 | 2 | 0 |
| 3  | 1 | 2 | 2 | 0 |
| 4  | 1 | 2 | 2 | 3 |

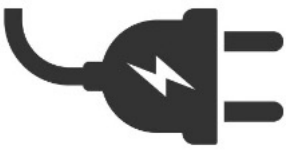
nothing

# Checkpoint nothing

```
1 Ckpt()  
2   x := y;  
3   y := z;  
4   w := x + y
```



| NV      |  | x | y | z | w |
|---------|--|---|---|---|---|
| 1       |  | 0 | 1 | 2 | 0 |
| 2       |  | 1 | 1 | 2 | 0 |
| 3       |  | 1 | 2 | 2 | 0 |
| Restore |  | 1 | 2 | 2 | 0 |
| 2       |  | 2 | 2 | 2 | 0 |
| 3       |  | 2 | 2 | 2 | 0 |
| 4       |  | 2 | 2 | 2 | 4 |



| NV |  | x | y | z | w |
|----|--|---|---|---|---|
| 1  |  | 0 | 1 | 2 | 0 |
| 2  |  | 1 | 1 | 2 | 0 |
| 3  |  | 1 | 2 | 2 | 0 |
| 4  |  | 1 | 2 | 2 | 3 |

inconsistent memory!

nothing  
→ consistency bugs!

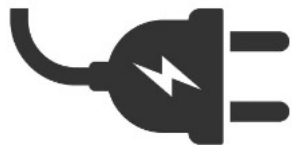
# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```



NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |



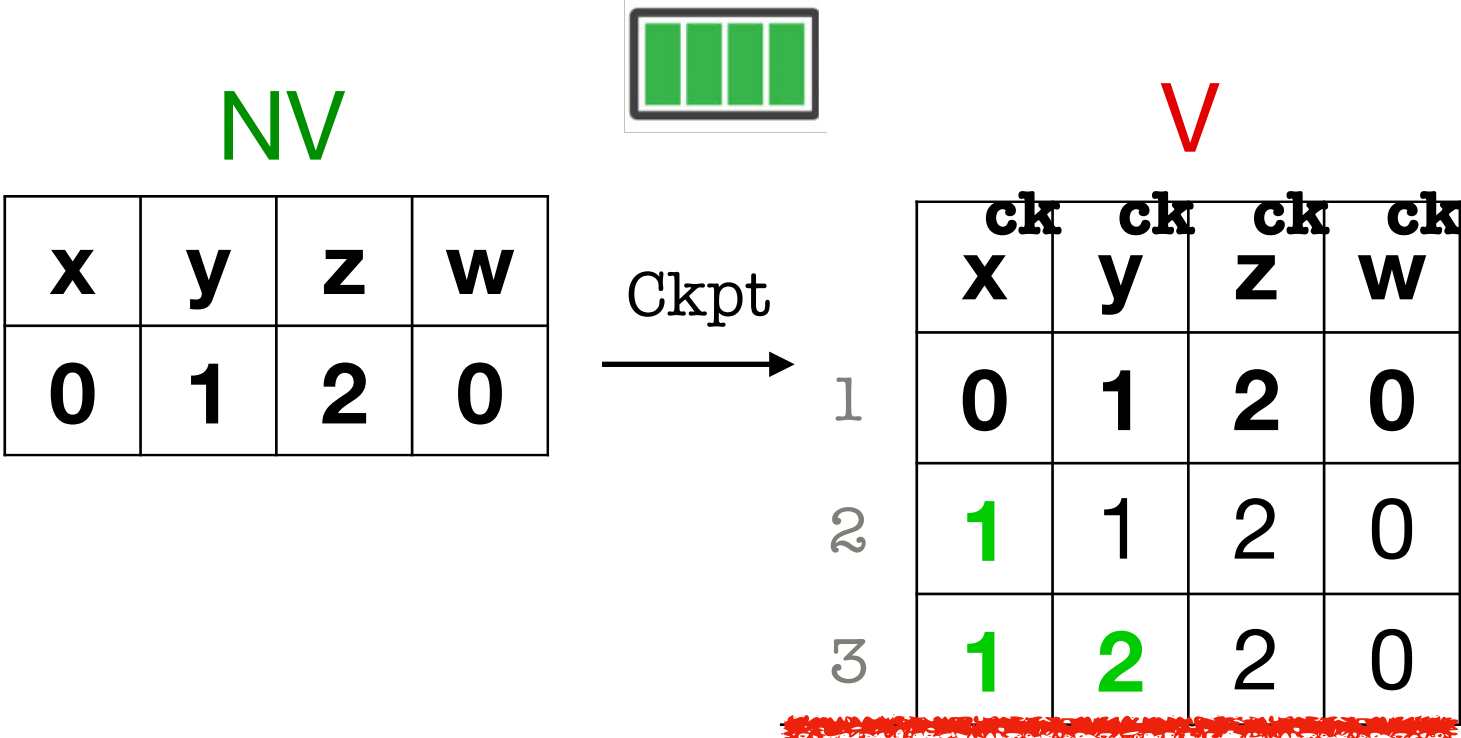
NV

|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |

nothing  
→ consistency bugs!  
everything

# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```



nothing  
→ consistency bugs!  
everything

# Checkpoint everything!

```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```

NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |



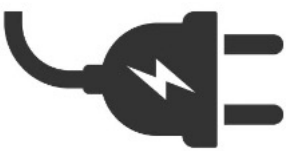
V

| <del>ck</del> x | <del>ck</del> y | <del>ck</del> z | <del>ck</del> w |
|-----------------|-----------------|-----------------|-----------------|
|                 |                 |                 |                 |

pwOff

NV

|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |



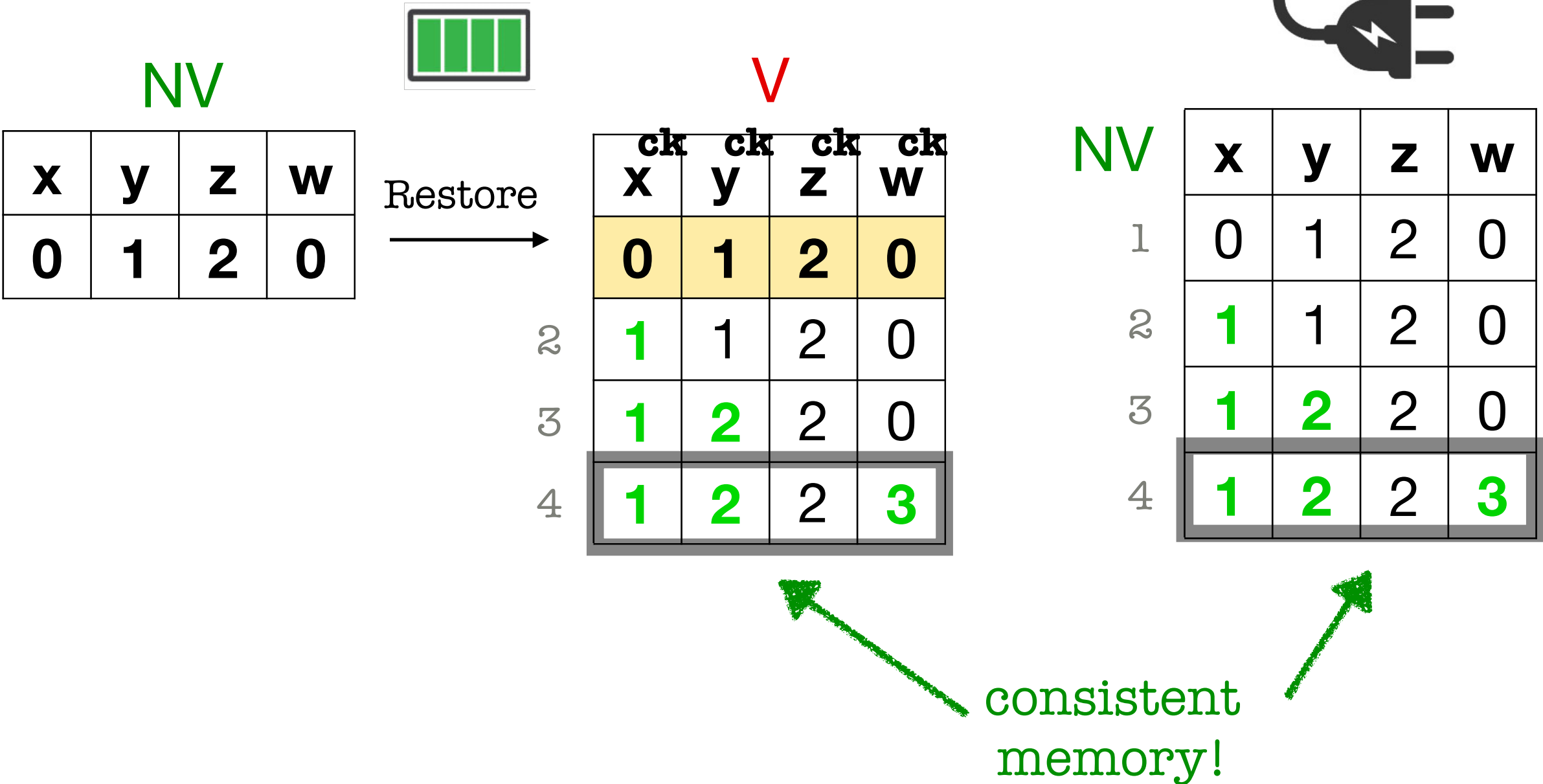
nothing

→ consistency bugs!

everything

# Checkpoint everything!

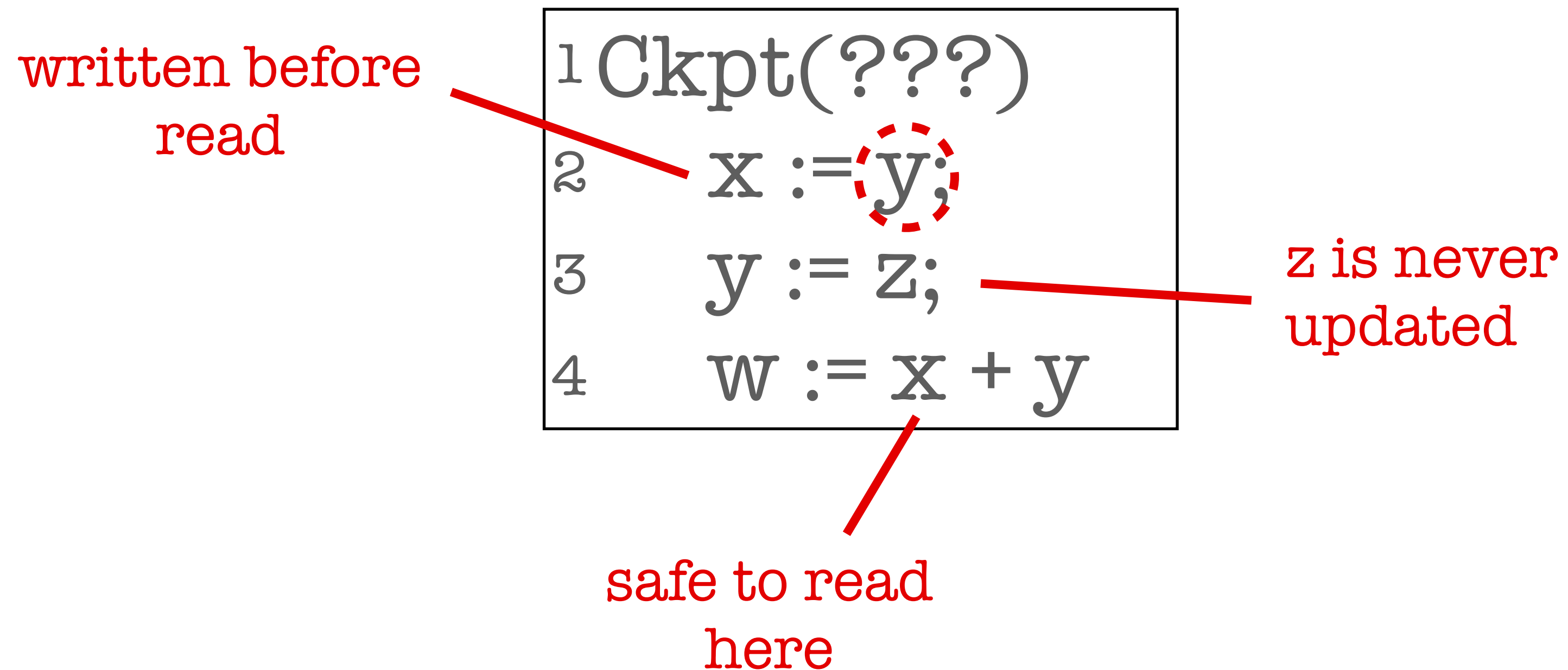
```
1 Ckpt(x,y,w,z)
2   x := y;
3   y := z;
4   w := x + y
```



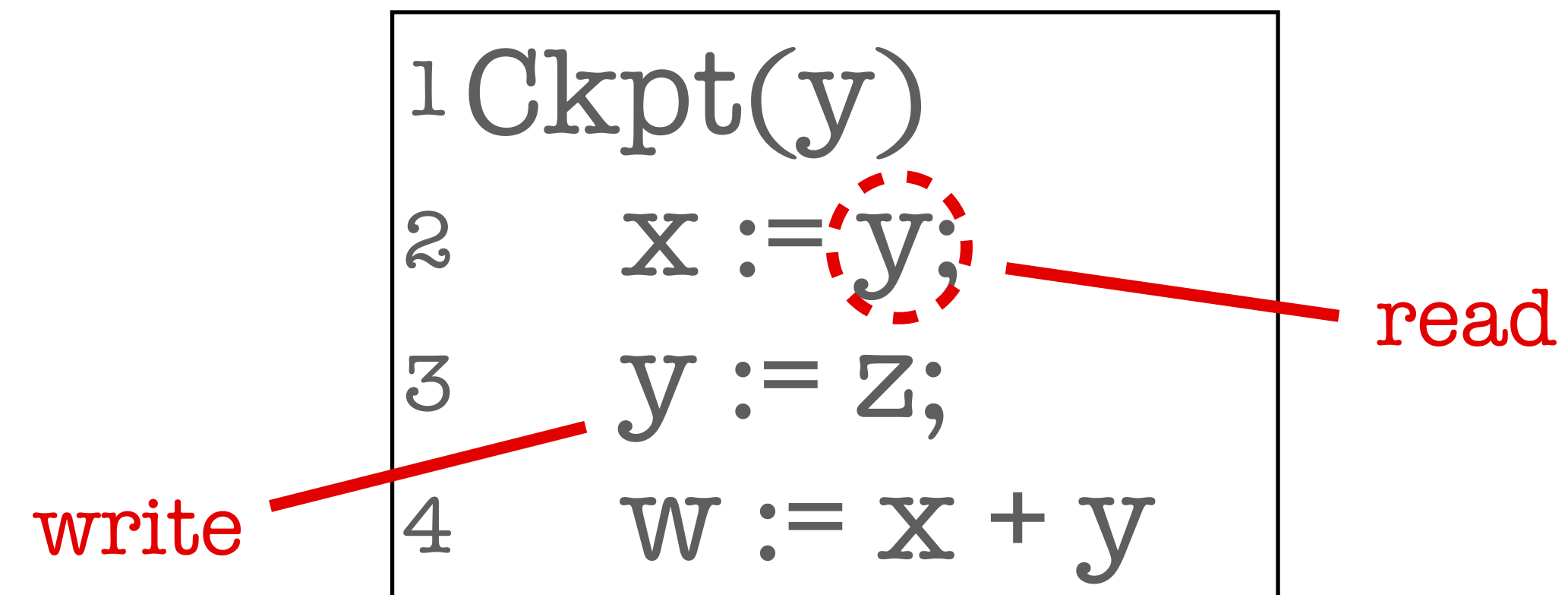
nothing  
→ consistency bugs!

everything  
→ inefficient!

# Do we really need to checkpoint everything?



# No, only the write-after-read variables [Lucia et al. '15]



y is a write-after-read (WAR) variable.

# Checkpoint write-after-read variables

1

Ckpt(y)

2

x := y;

3

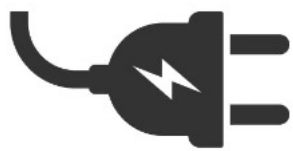
y := z;

4

w := x + y



|    |   |   |   |   |
|----|---|---|---|---|
| NV | x | y | z | w |
|    | 0 | 1 | 2 | 0 |

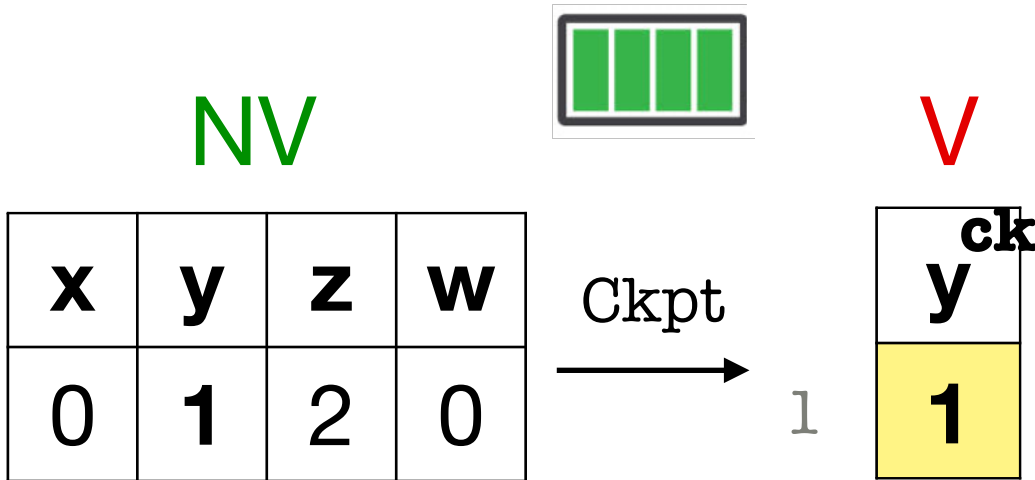


|    |   |   |   |   |
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| 1  | 0 | 1 | 2 | 0 |
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| 3  | 1 | 2 | 2 | 0 |
| 4  | 1 | 2 | 2 | 3 |

- nothing
- consistency bugs!
- everything
- inefficient!
- write-after-read variables
- ✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```

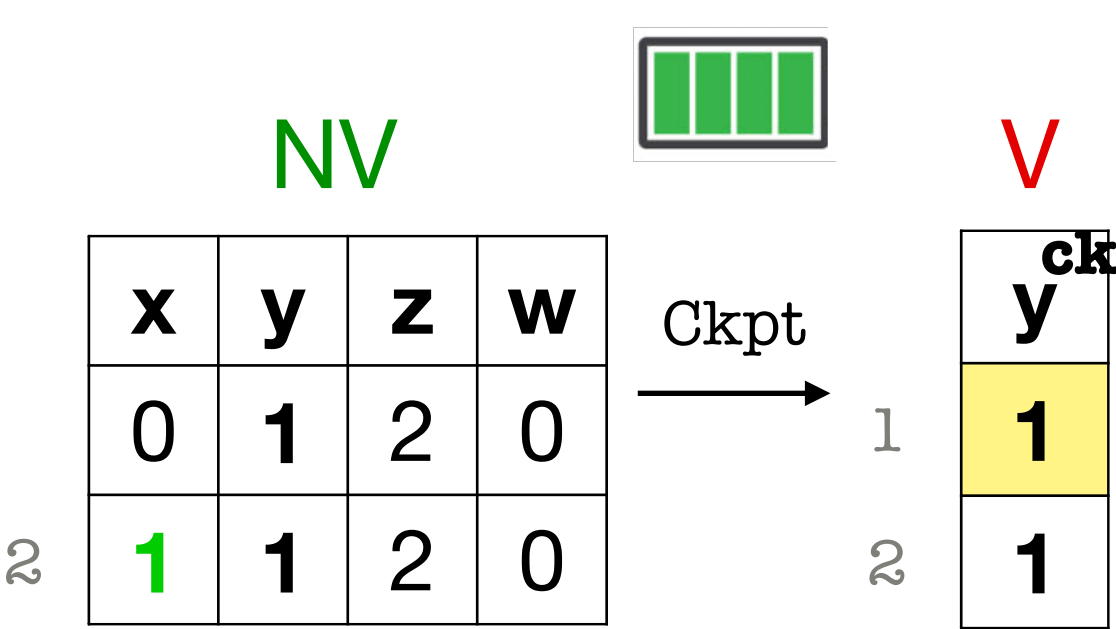


|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |

- nothing
  - consistency bugs!
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```
1 Ckpt(y)
2   x := y;
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# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```

NV

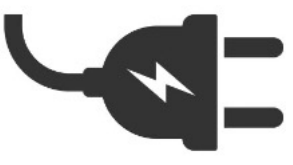


V

|   | x | y | z | w |
|---|---|---|---|---|
|   | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 1 | 2 | 0 |

|   | y <sup>ck</sup> |
|---|-----------------|
| 1 | 1               |
| 2 | 1               |
| 3 | 2               |

NV

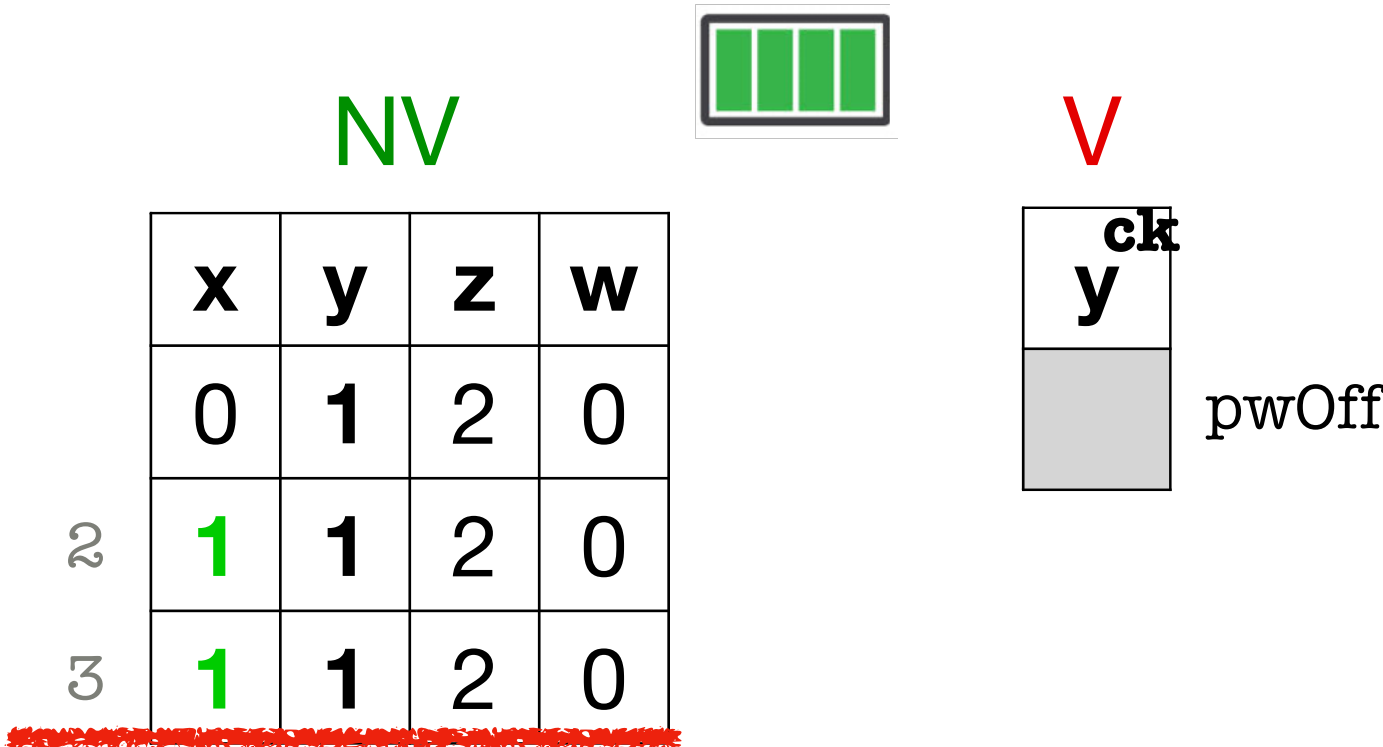


|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |

- nothing
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# Checkpoint write-after-read variables

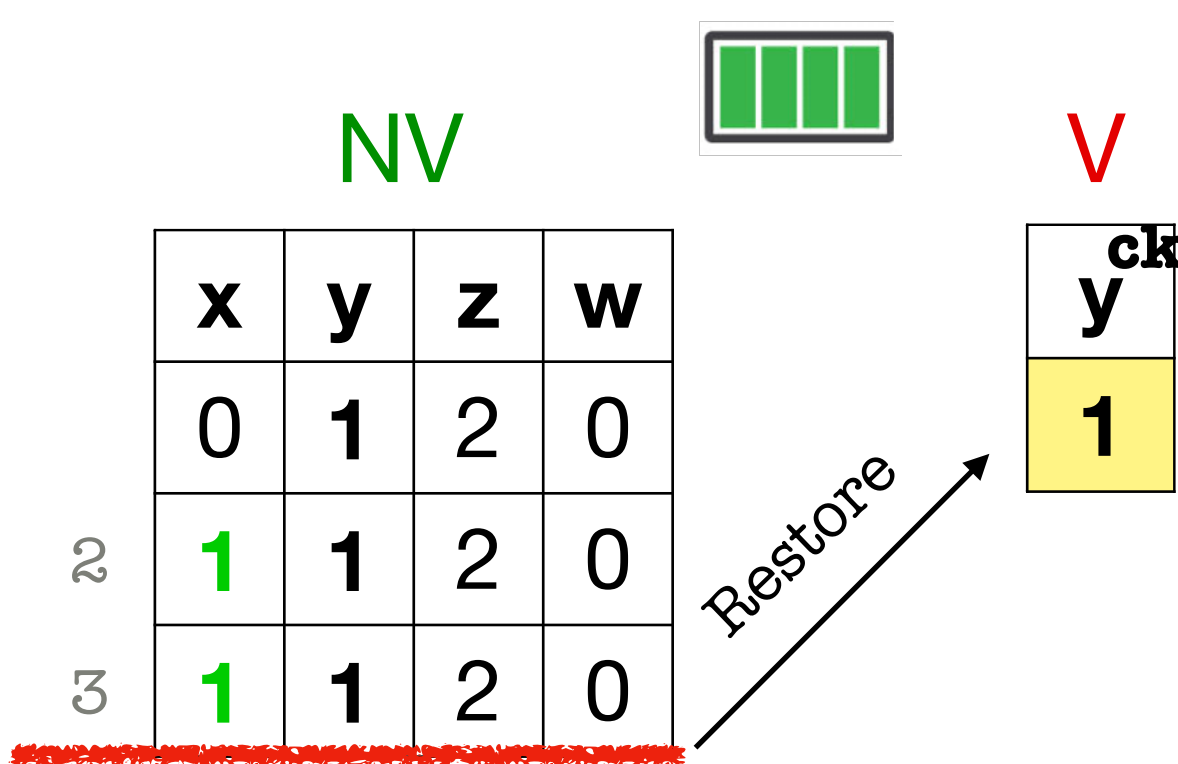
```
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```



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# Checkpoint write-after-read variables

```
1 Ckpt(y)
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```



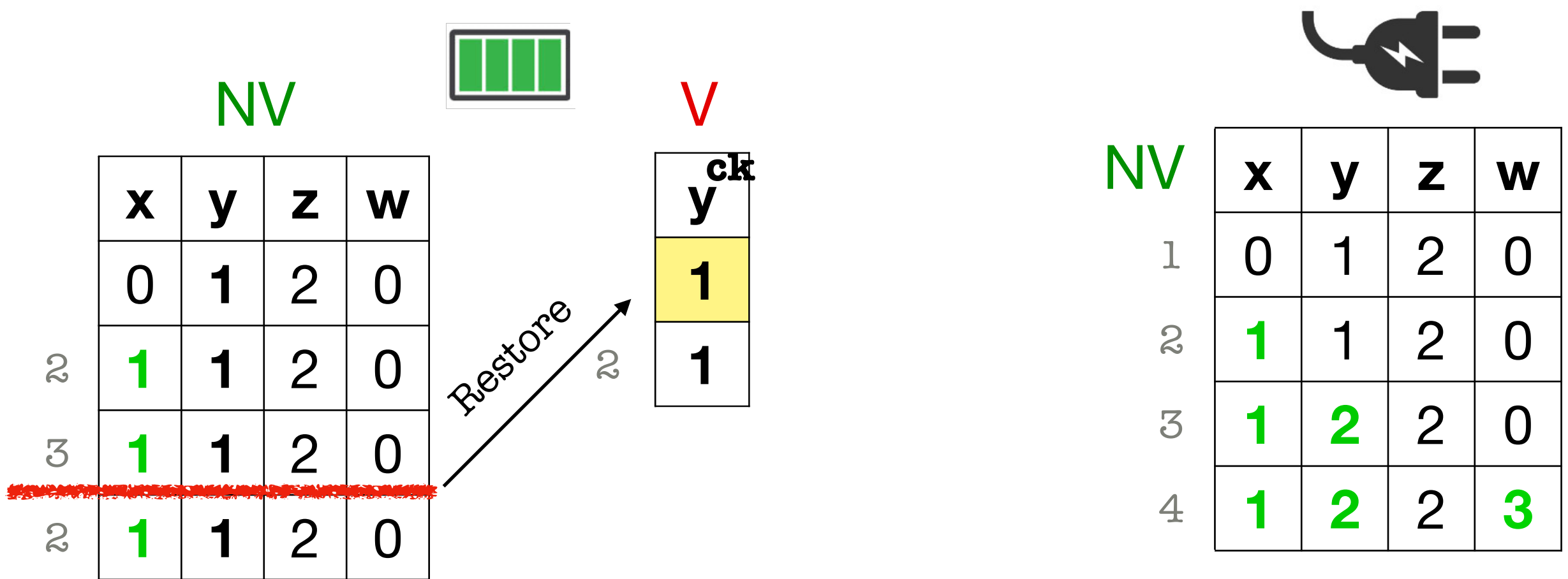
NV

|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |

- nothing
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- everything
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# Checkpoint write-after-read variables

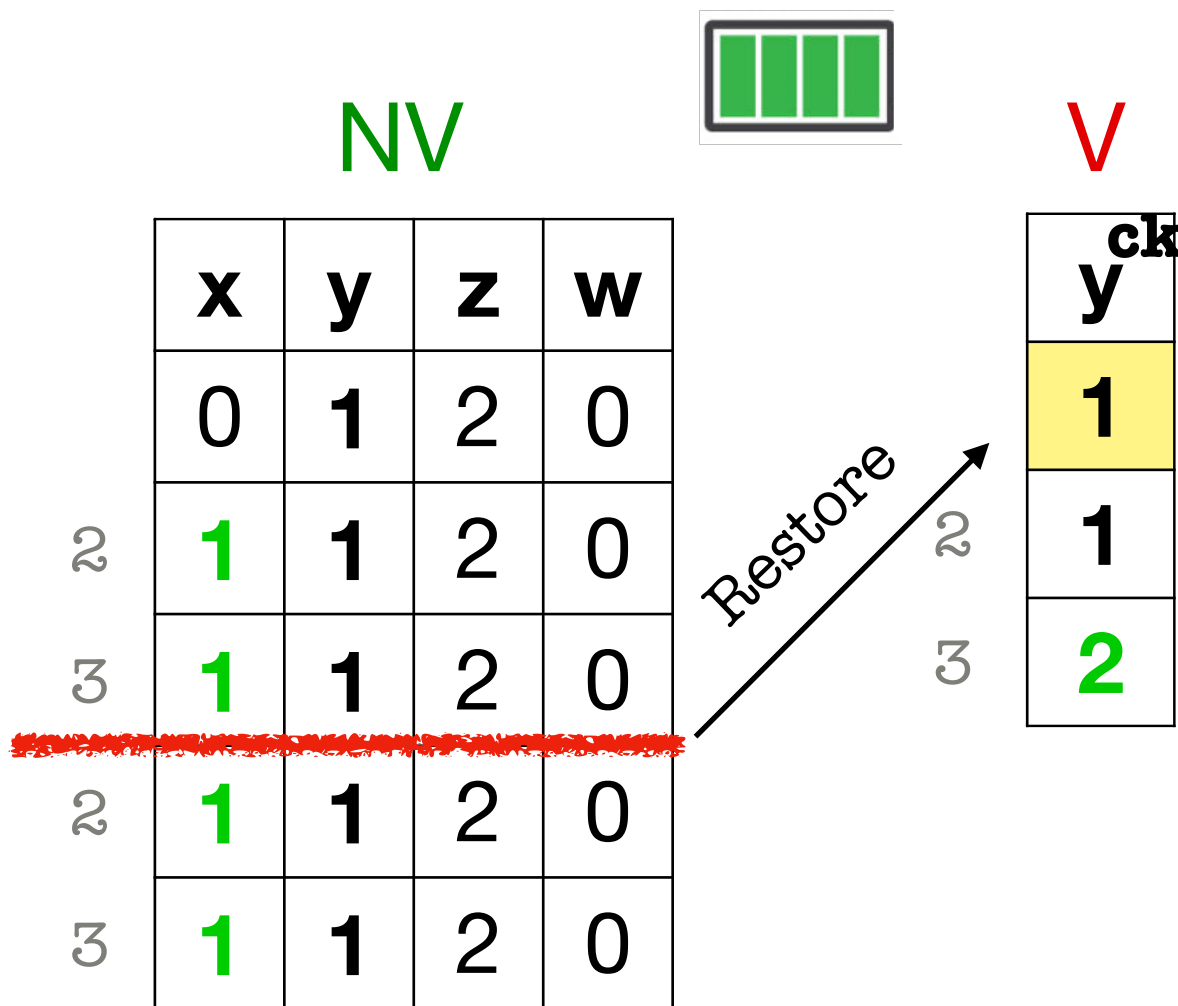
```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



- nothing
  - consistency bugs!
- everything
  - inefficient!
- write-after-read variables
  - ✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w := x + y
```



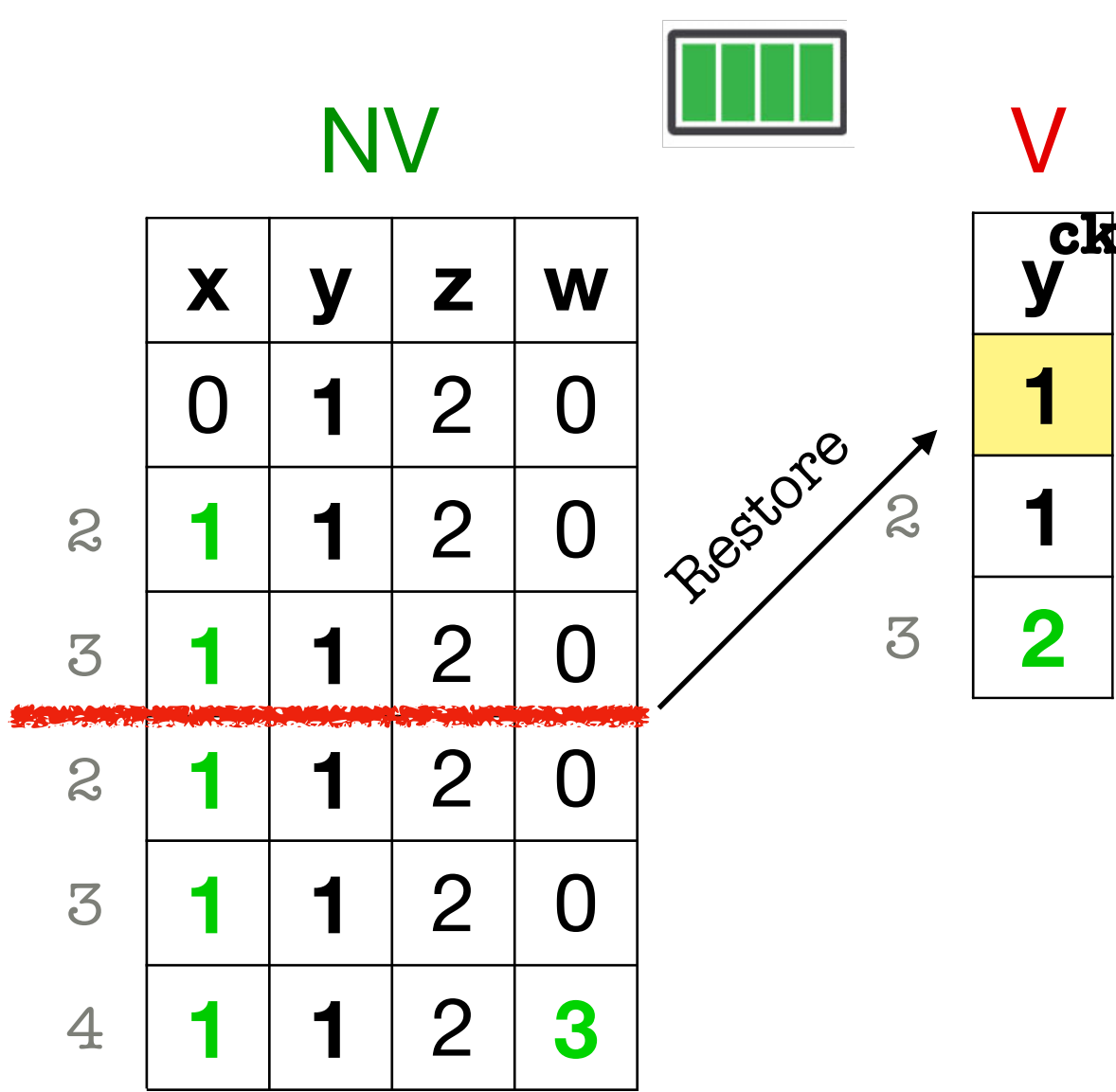
**NV**

|   | x | y | z | w |
|---|---|---|---|---|
| 1 | 0 | 1 | 2 | 0 |
| 2 | 1 | 1 | 2 | 0 |
| 3 | 1 | 2 | 2 | 0 |
| 4 | 1 | 2 | 2 | 3 |

- nothing
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# Checkpoint write-after-read variables

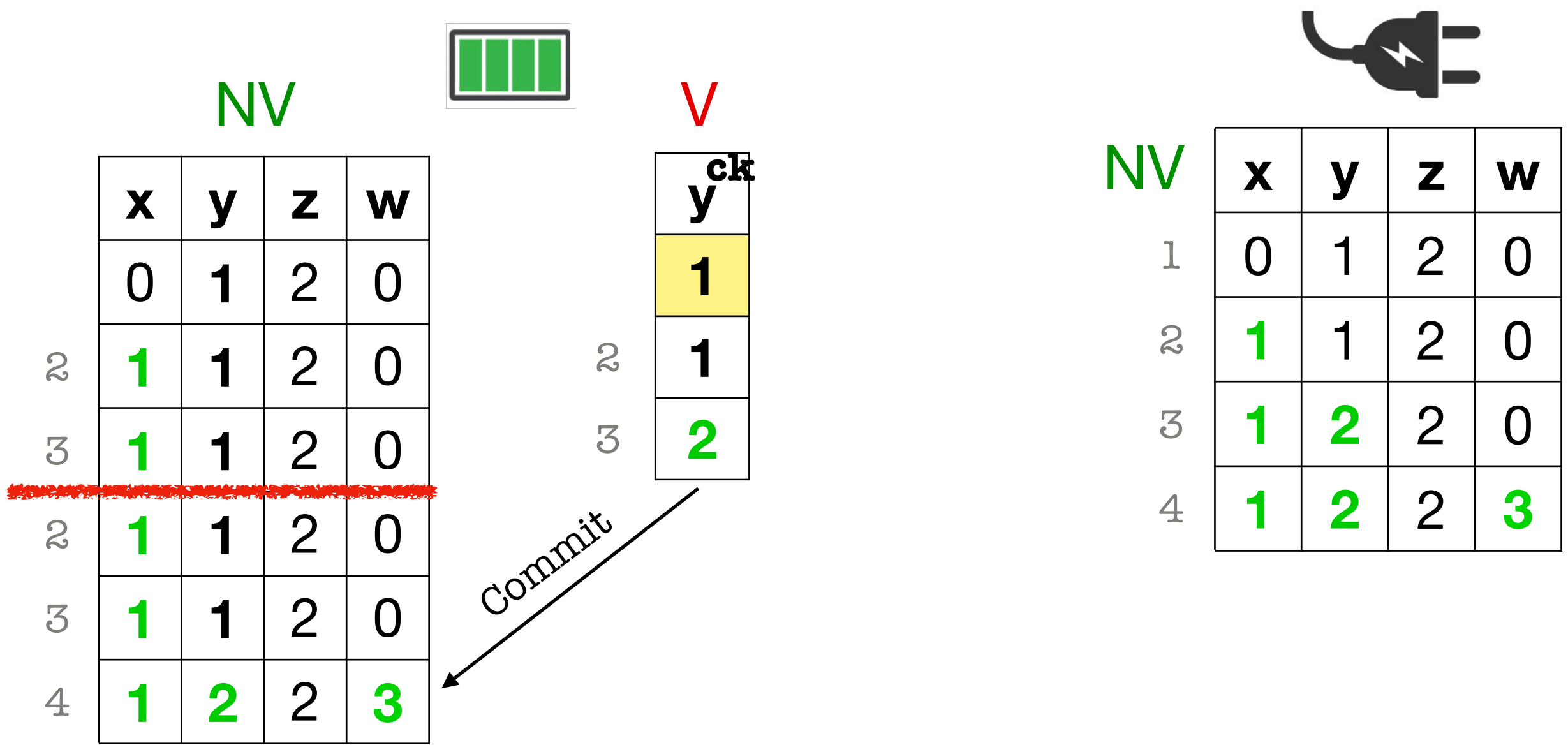
```
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# Checkpoint write-after-read variables

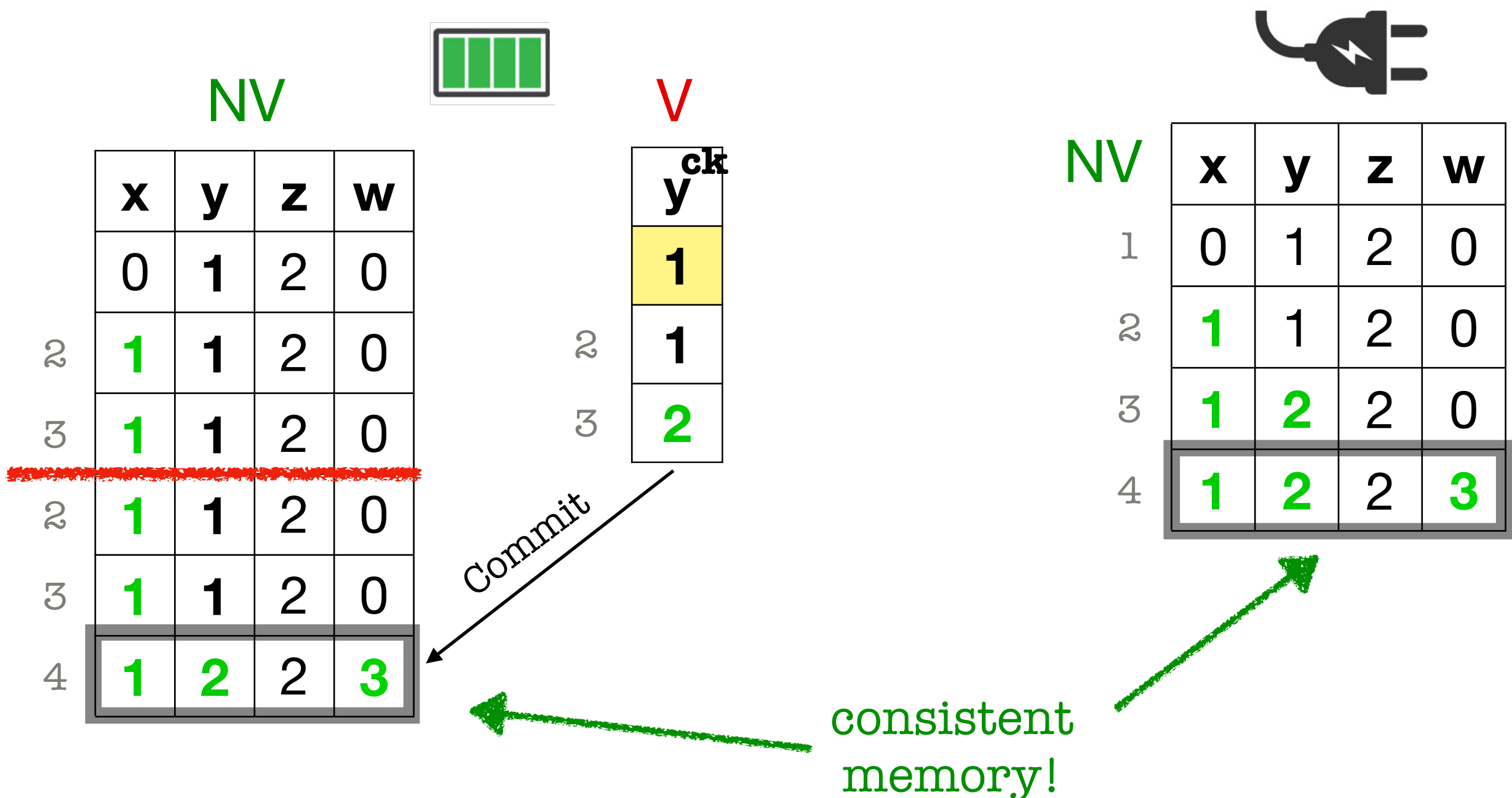
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# Checkpoint write-after-read variables

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1 Ckpt(y)
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```



- nothing
  - consistency bugs!
- everything
  - inefficient!
- write-after-read variables
  - ✓ real systems

# Checkpoint write-after-read variables

```
1 Ckpt(y)
2   x := y;
3   y := z;
4   w :=
```

NV

V

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |

2

| y <sup>ck</sup> |
|-----------------|
| 1               |
| 1               |

2

NV

| x | y | z | w |
|---|---|---|---|
| 0 | 1 | 2 | 0 |
| 1 | 1 | 2 | 0 |
| 1 | 2 | 2 | 0 |

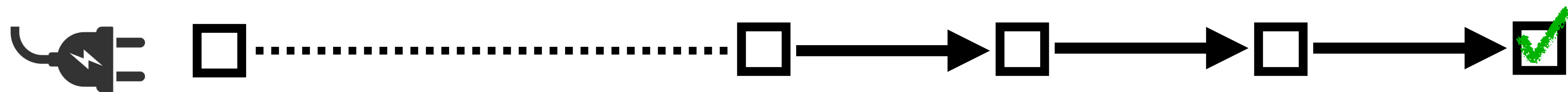
2

nothing  
→ consistency bugs!

More precisely:  
How can we **prove** that programs execute correctly intermittently when checkpointing only WAR variables?

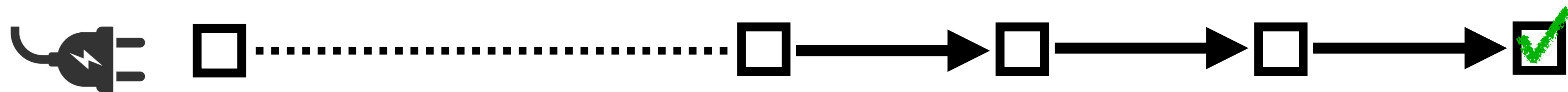
nothing  
inefficient!  
-after-read  
variables  
✓ real systems

# Ensuring correctness



- first formal framework for reasoning about intermittent execution  
[Surbatovich et al. '20]

# Ensuring correctness



- first formal framework for reasoning about intermittent execution [[Surbatovich et al. '20](#)]
- type system focused on correct variable accesses [[Surbatovich et al. '23](#)]

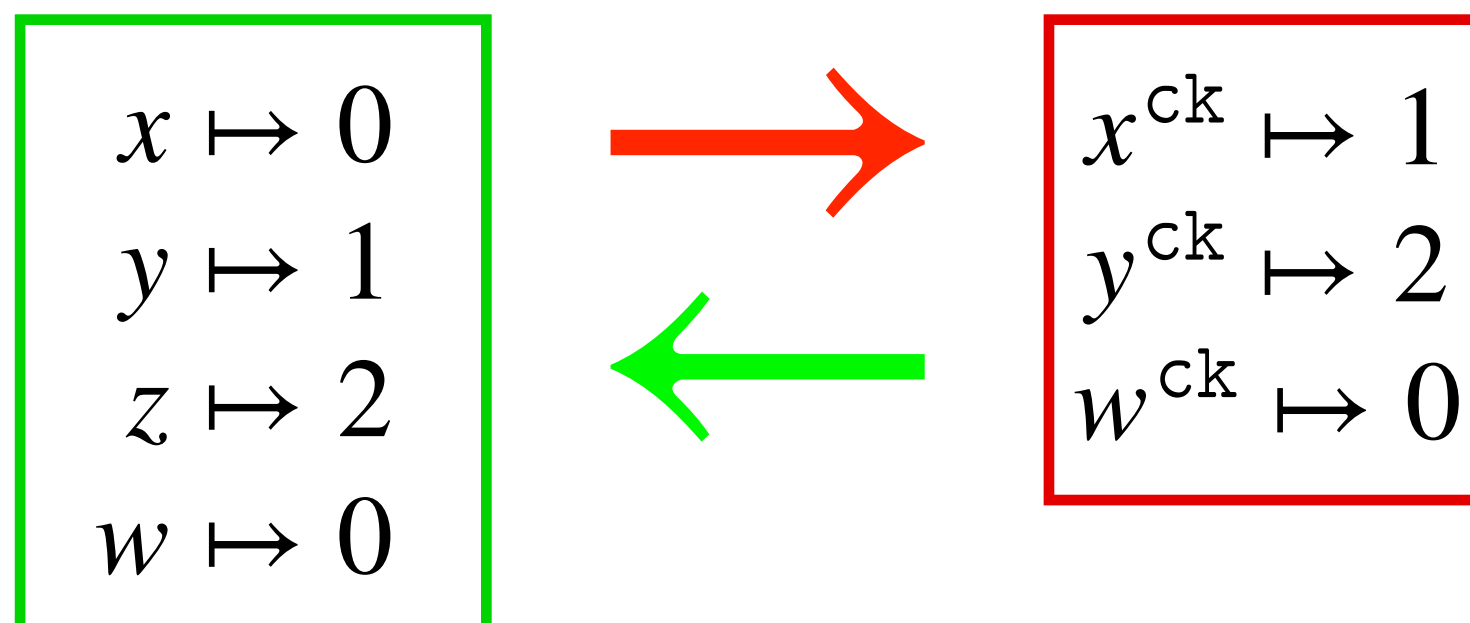
# **First logical interpretation of intermittent computing**

**power off, restore, commit.**

# First logical interpretation of intermittent computing

power off, restore, commit.

One approach: checkpoint  
everything not read-only  
[Derakhshan et al. '23]

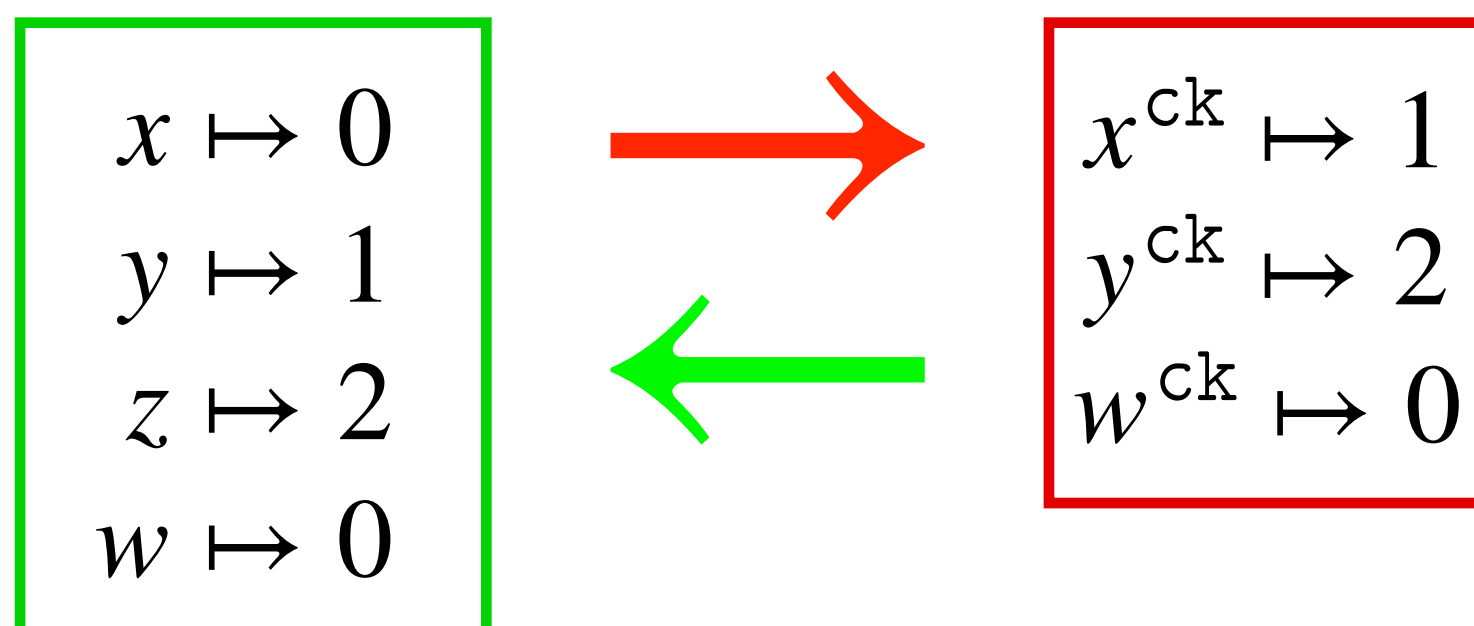


```
Ckpt(x,y,w)
  x := y;
  y := z;
  w := x + y
```

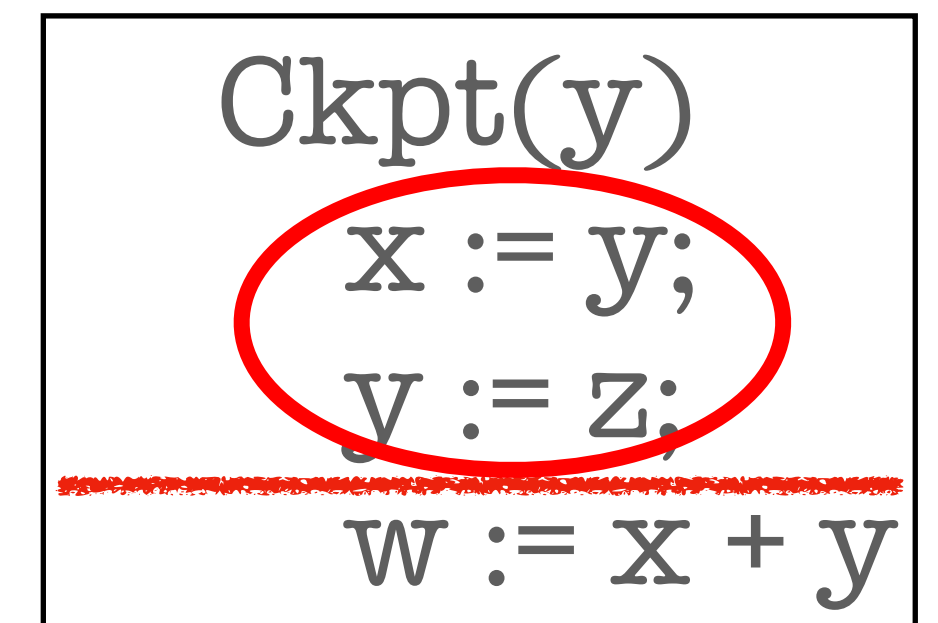
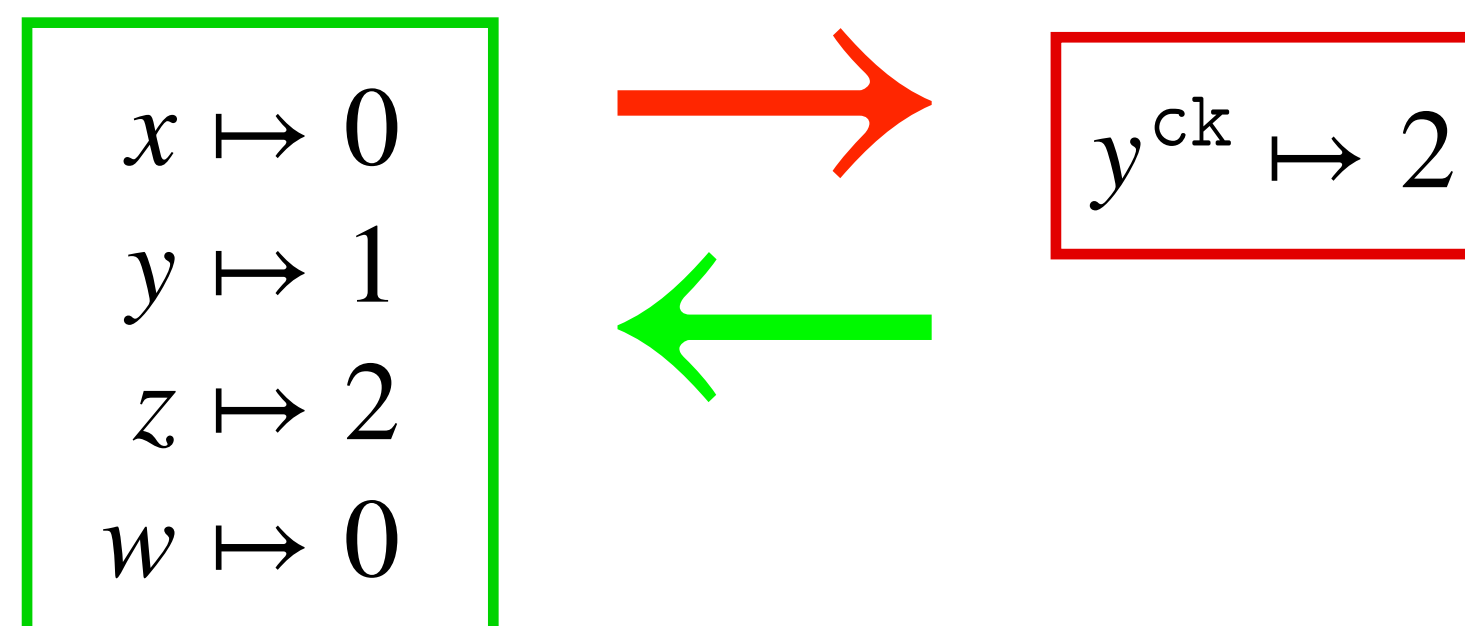
# First logical interpretation of intermittent computing

## power off, restore, commit.

One approach: checkpoint everything not read-only  
[Derakhshan et al. '23]



More efficient: checkpoint only write-after-read variables



Types allow us to automatically check that programs can execute  
**correctly intermittently.**

# Outline

- Intermittent computing
- Overview
- **Type system**
- Logical relation
- JIT mode
- Key theorems
- Conclusion

# Basic types and access qualifiers

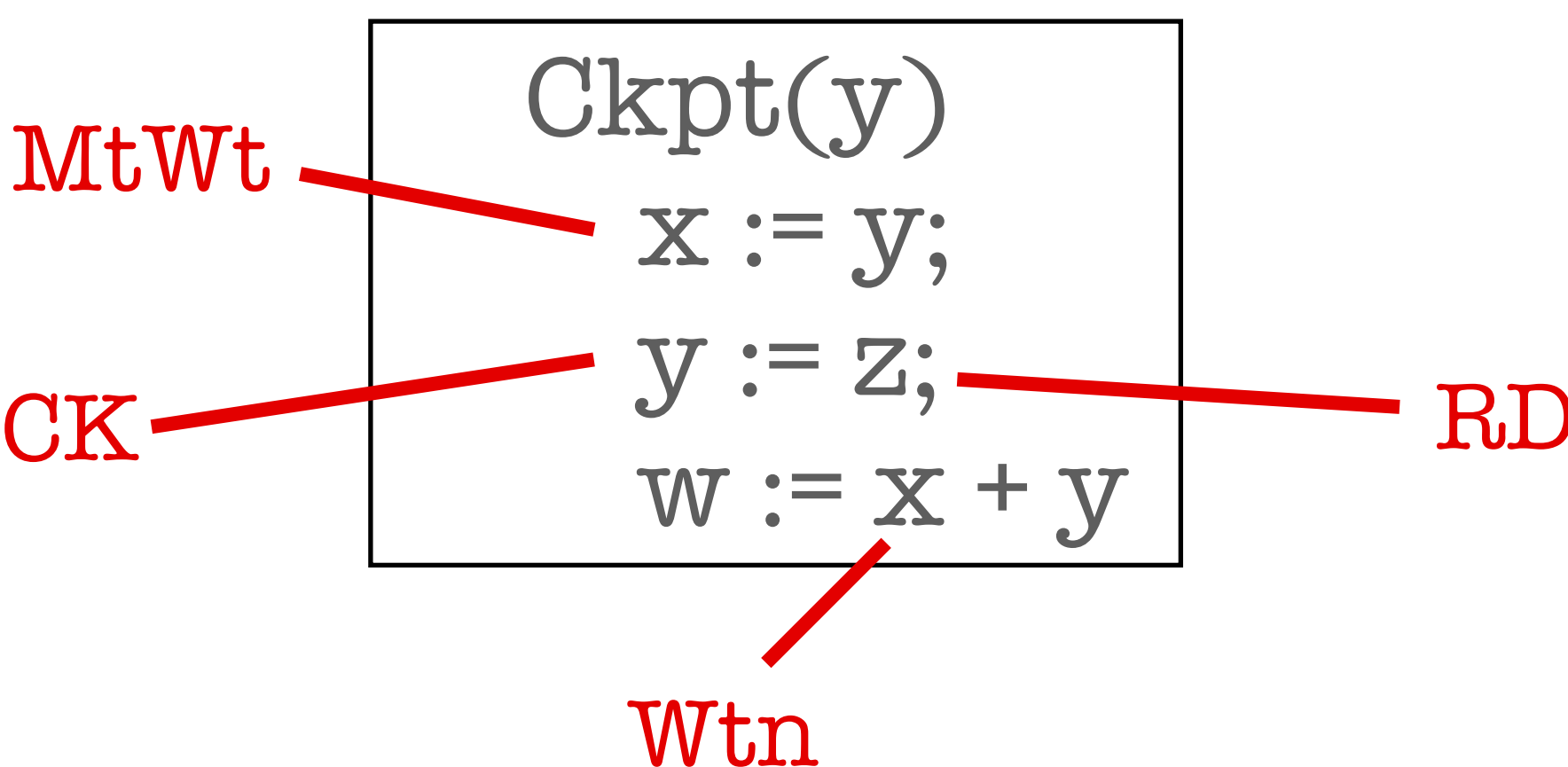
|                   |                                                                              |
|-------------------|------------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                          |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$             |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$      |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\text{    }} \rightsquigarrow \tau^s$ |

CK – checkpointed

RD – read only

MtWt – must-first-write

Wtn – written

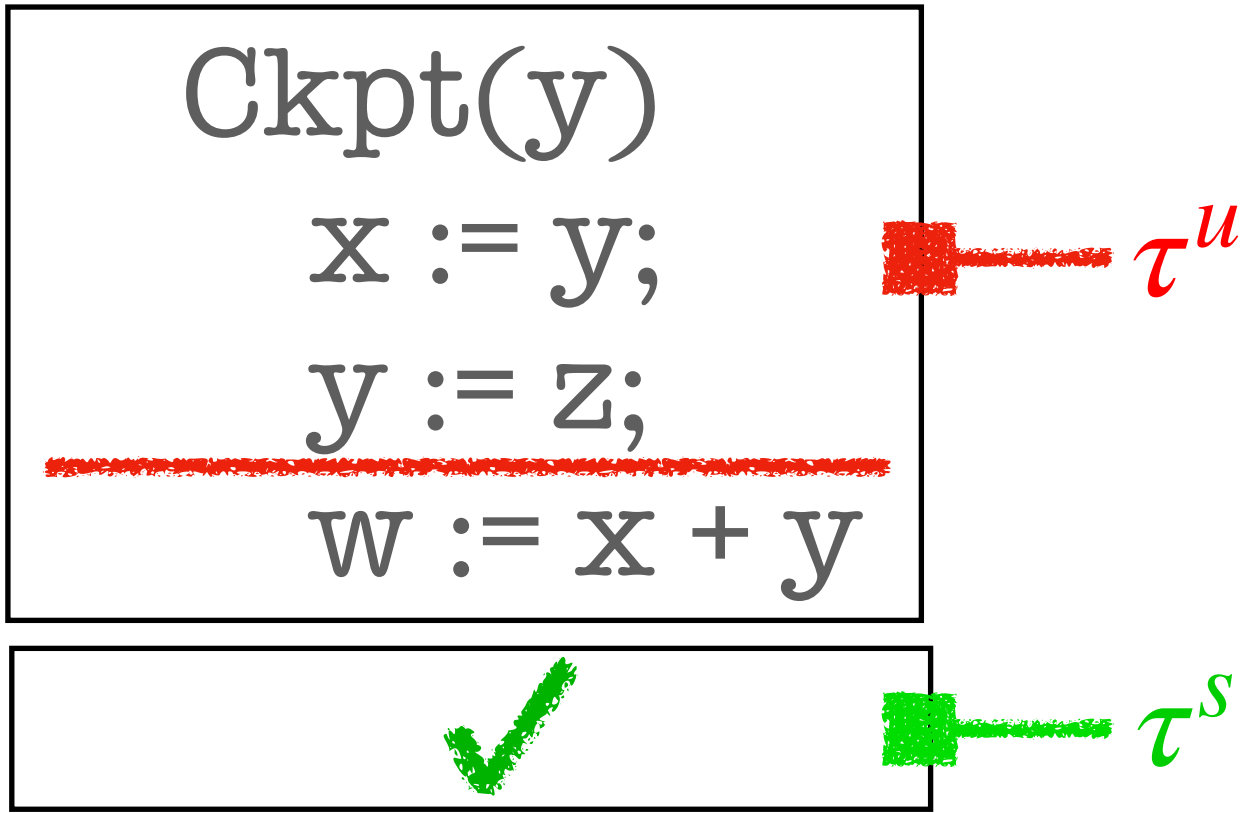


# Stable and unstable types

|                   |                                                                                   |
|-------------------|-----------------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                               |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$                  |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$           |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^s}} \rightsquigarrow \tau^s$ |

$\tau^u$  code inside of checkpoints

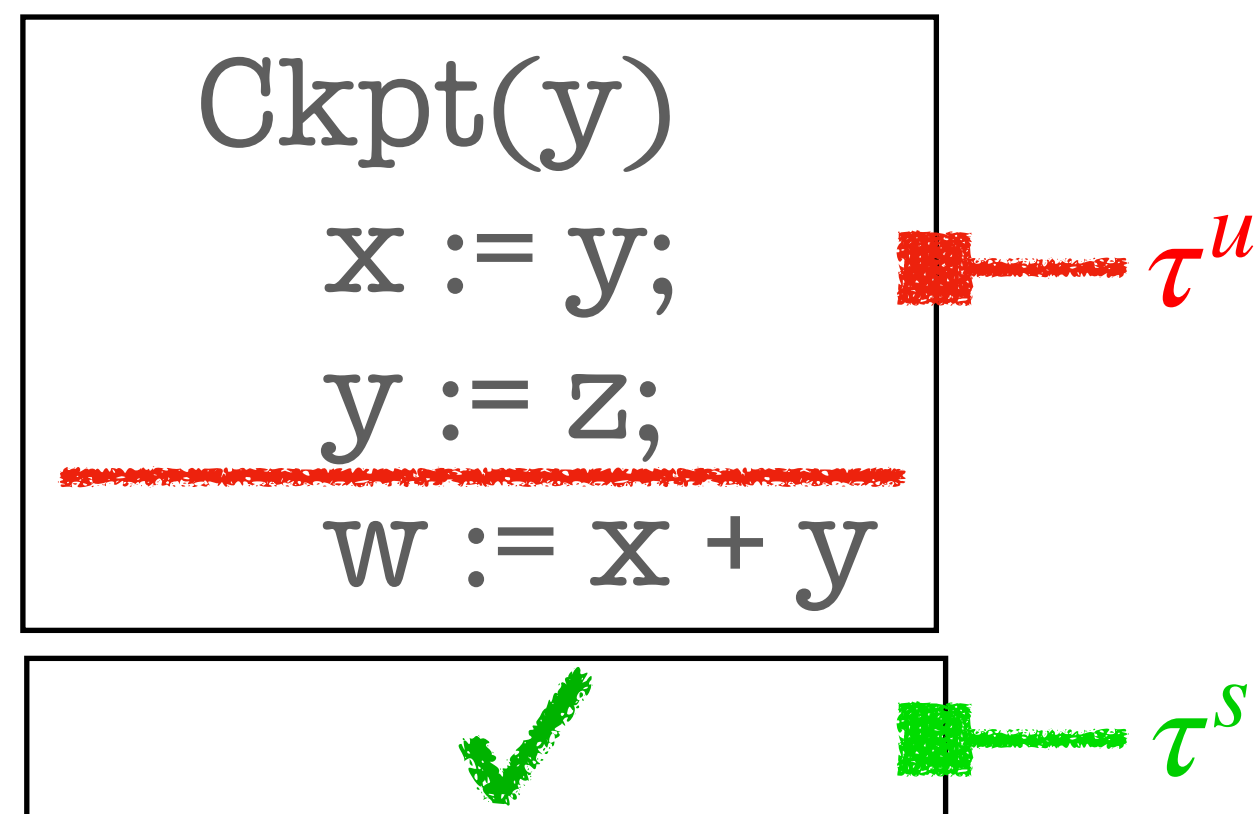
$\tau^s$  programs after commit



# Adjoint Logic\*

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
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**Independence principle:** universal truth  
does not depend on ephemeral truth.



\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

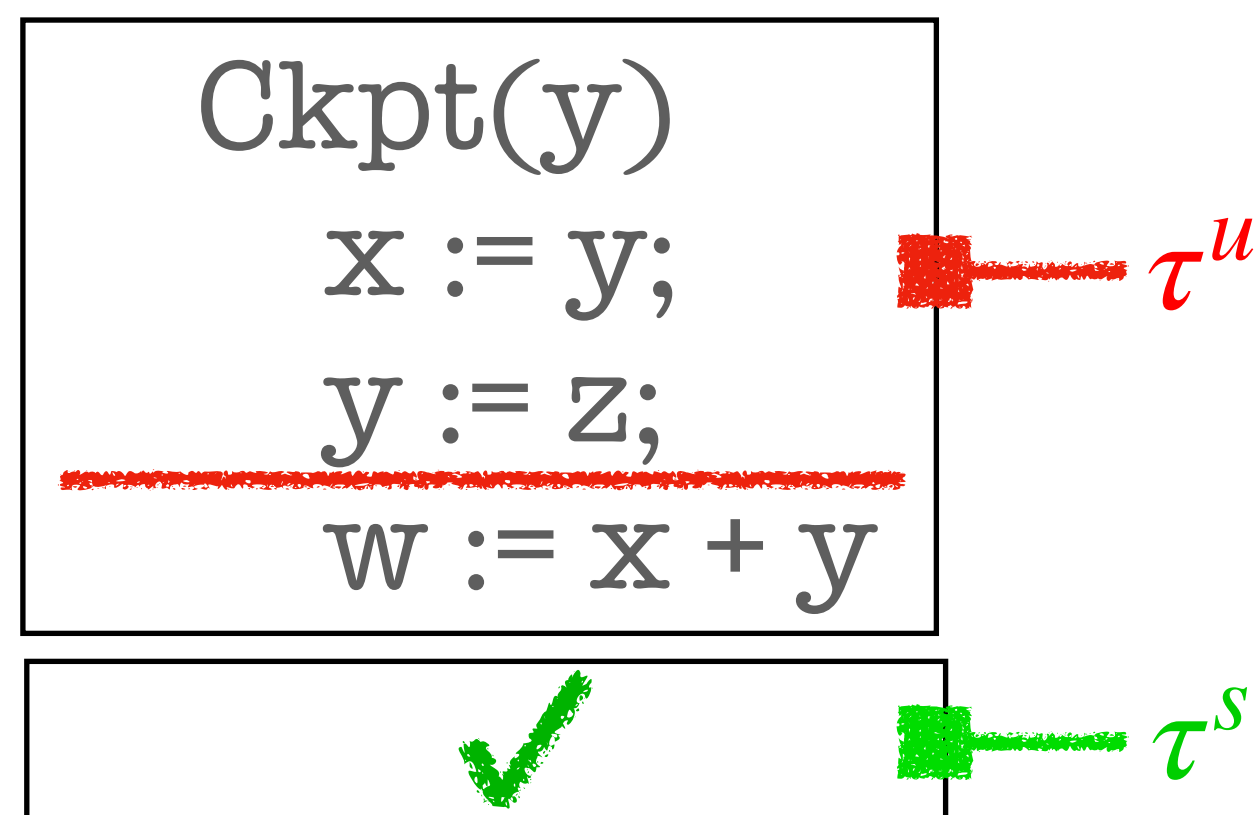
# Adjoint Logic\*

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**Independence principle:** universal truth  
does not depend on ephemeral truth.

“It is *always* cold”

“It is cold *today*”



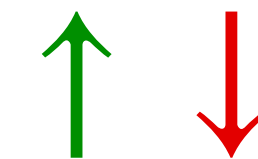
\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

# Adjoint Logic\*

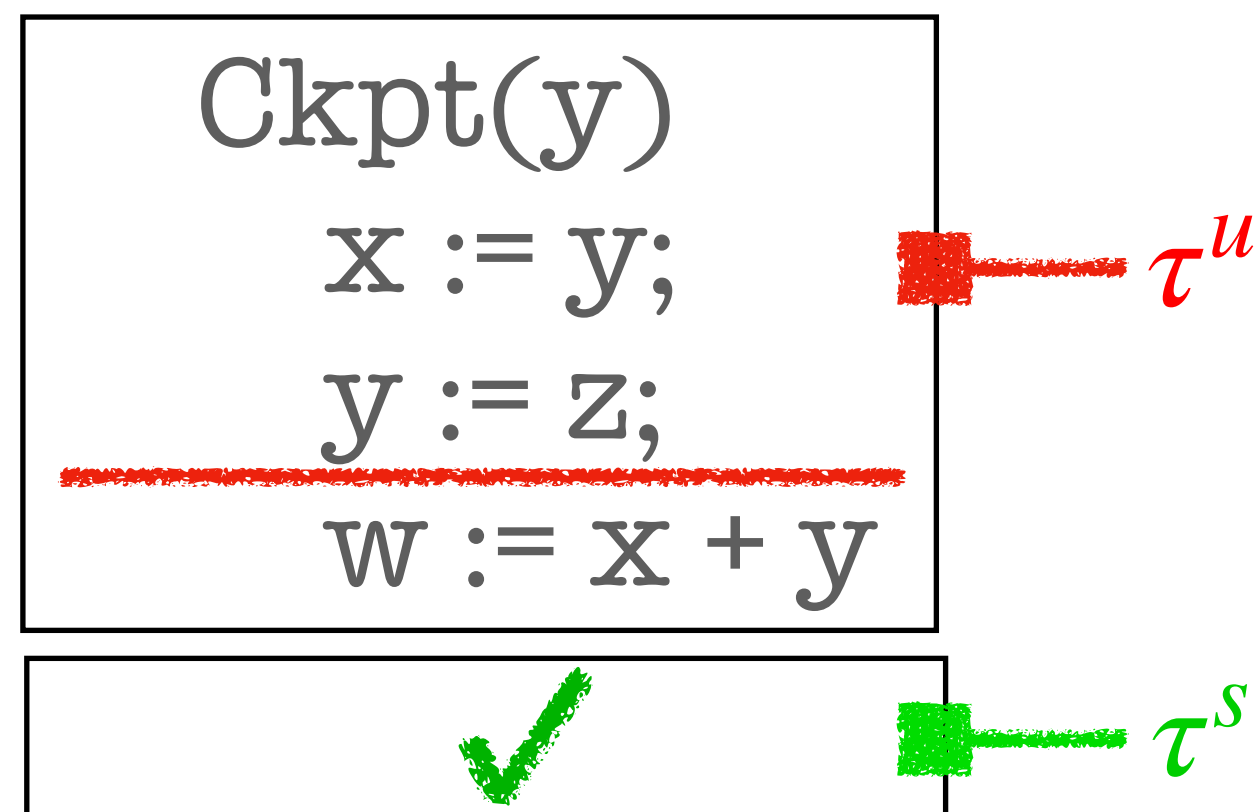
basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^s}} \leadsto \tau^s$

**Independence principle:** universal truth  
does not depend on ephemeral truth.

“It is *always* cold”



“It is cold *today*”



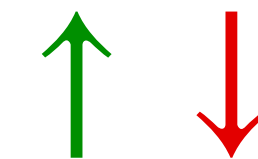
\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

# Adjoint Logic\*

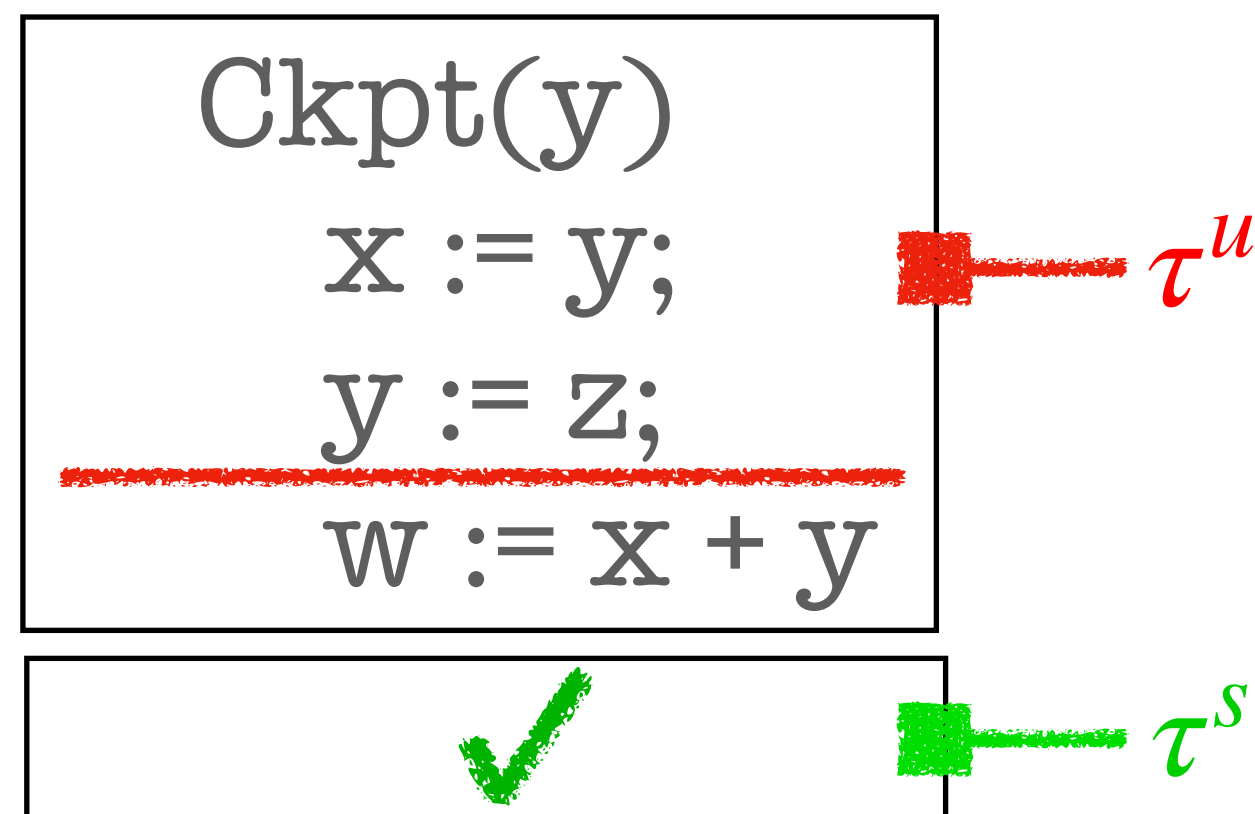
basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
 access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
 unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
 stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^s}} \rightsquigarrow \tau^s$

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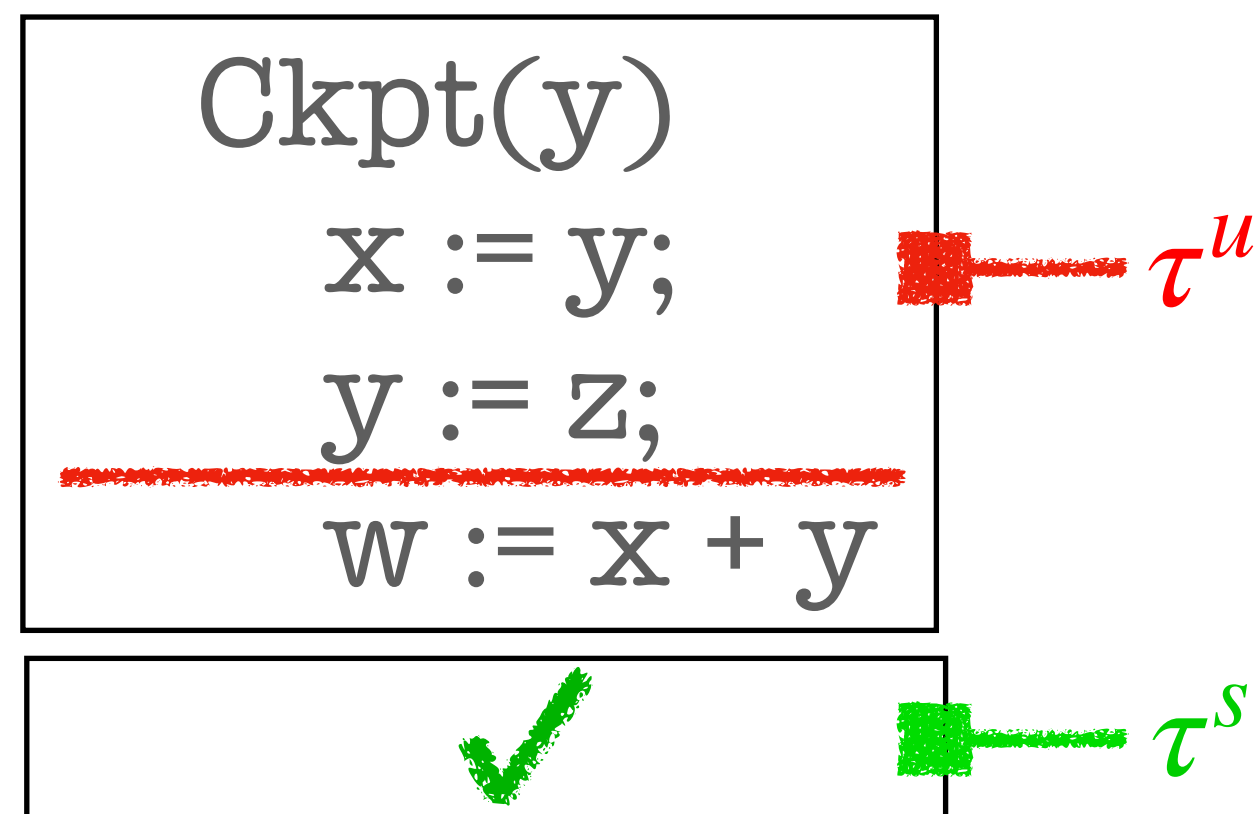


**Here:** stable values (s) do not depend on  
 unstable values (u).

\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

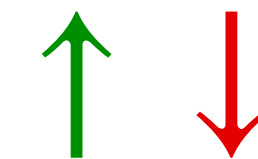
# Adjoint Logic\*

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
 access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
 unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
 stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{---}} \rightsquigarrow \tau^s$



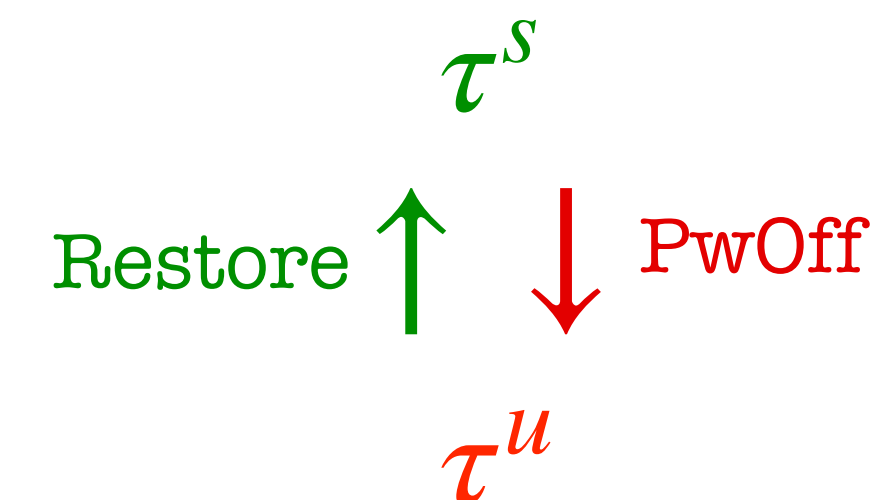
**Independence principle:** universal truth does not depend on ephemeral truth.

“It is *always* cold”



“It is cold *today*”

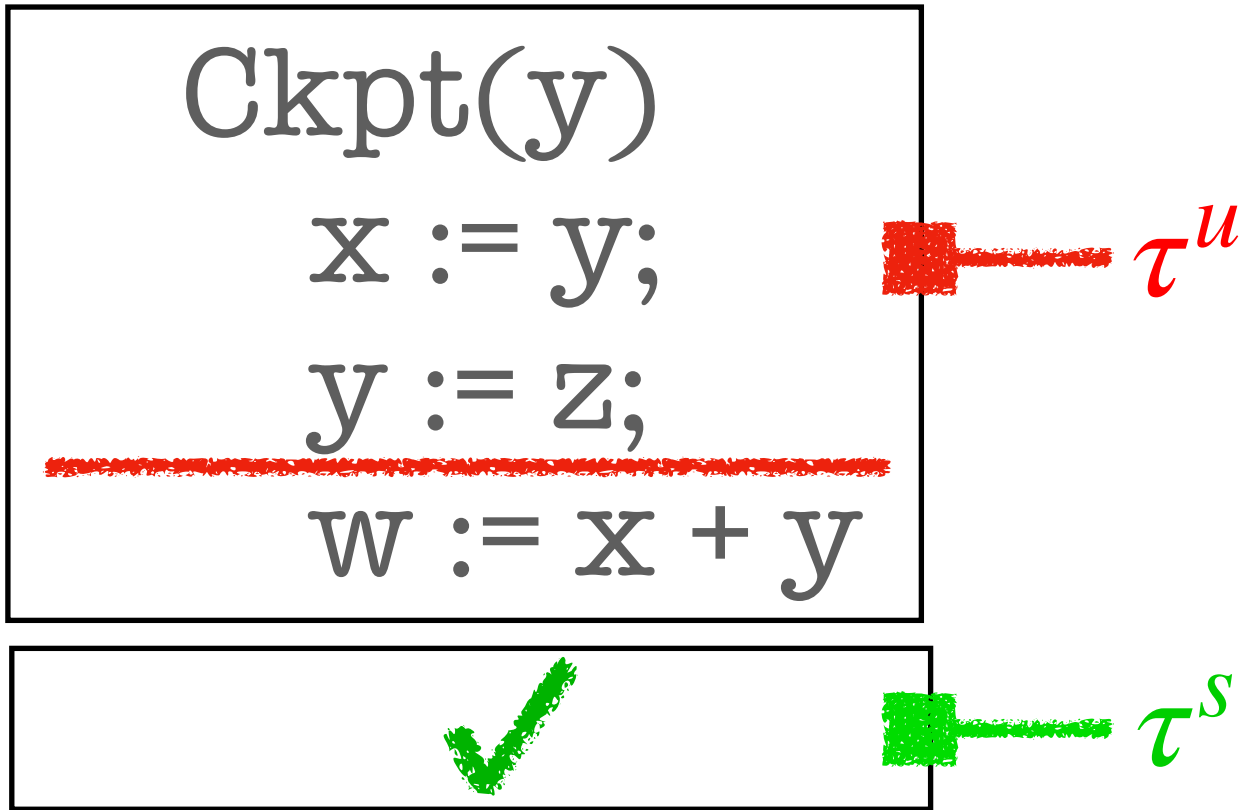
**Here:** stable values (s) do not depend on unstable values (u).



\* [Pruiksma et al. '21, Pfenning et al. '01, Benton et al. '97]

# Crash Type

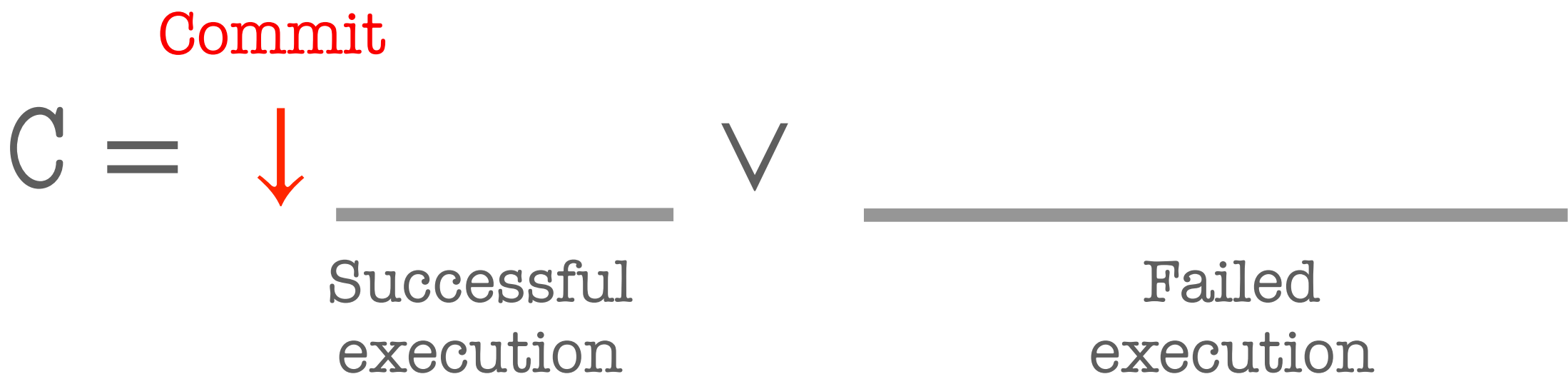
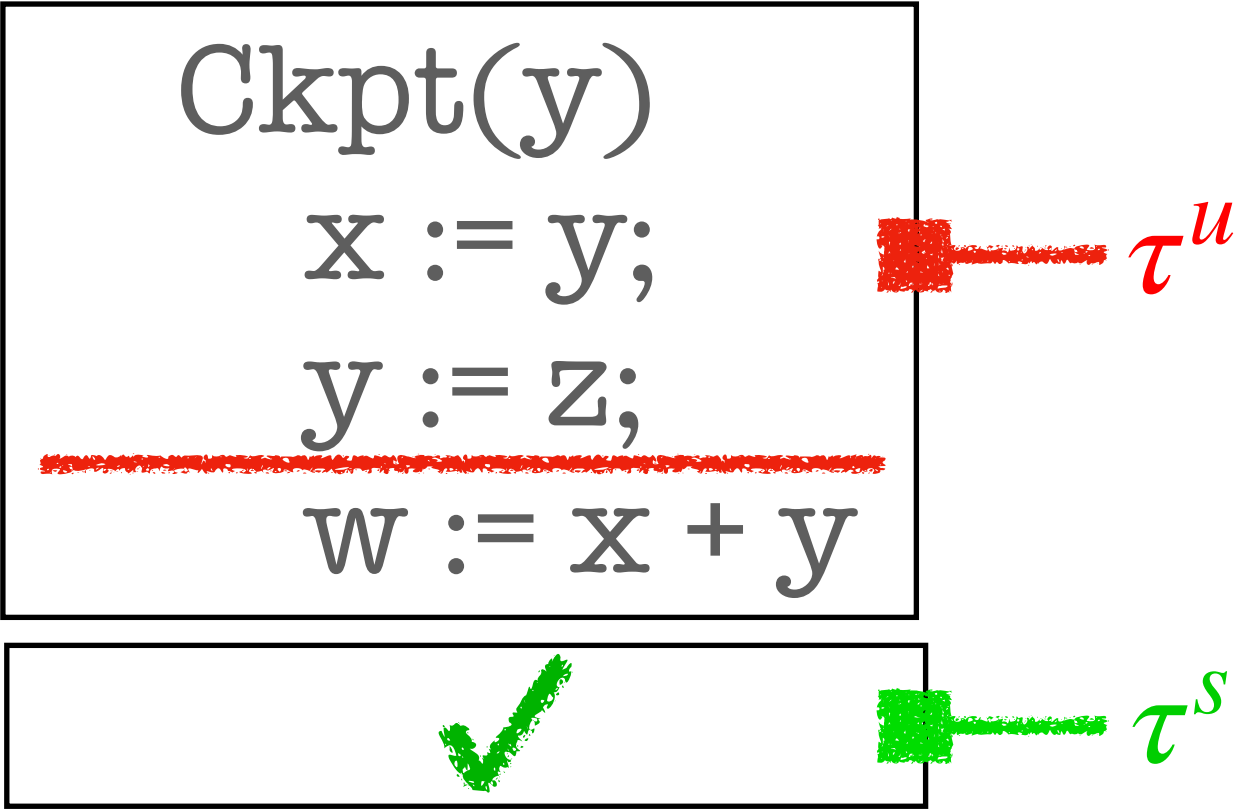
basic types       $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers    $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types     $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$   
stable types       $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$



$$C = \frac{}{\text{Successful execution}} \vee \frac{}{\text{Failed execution}}$$

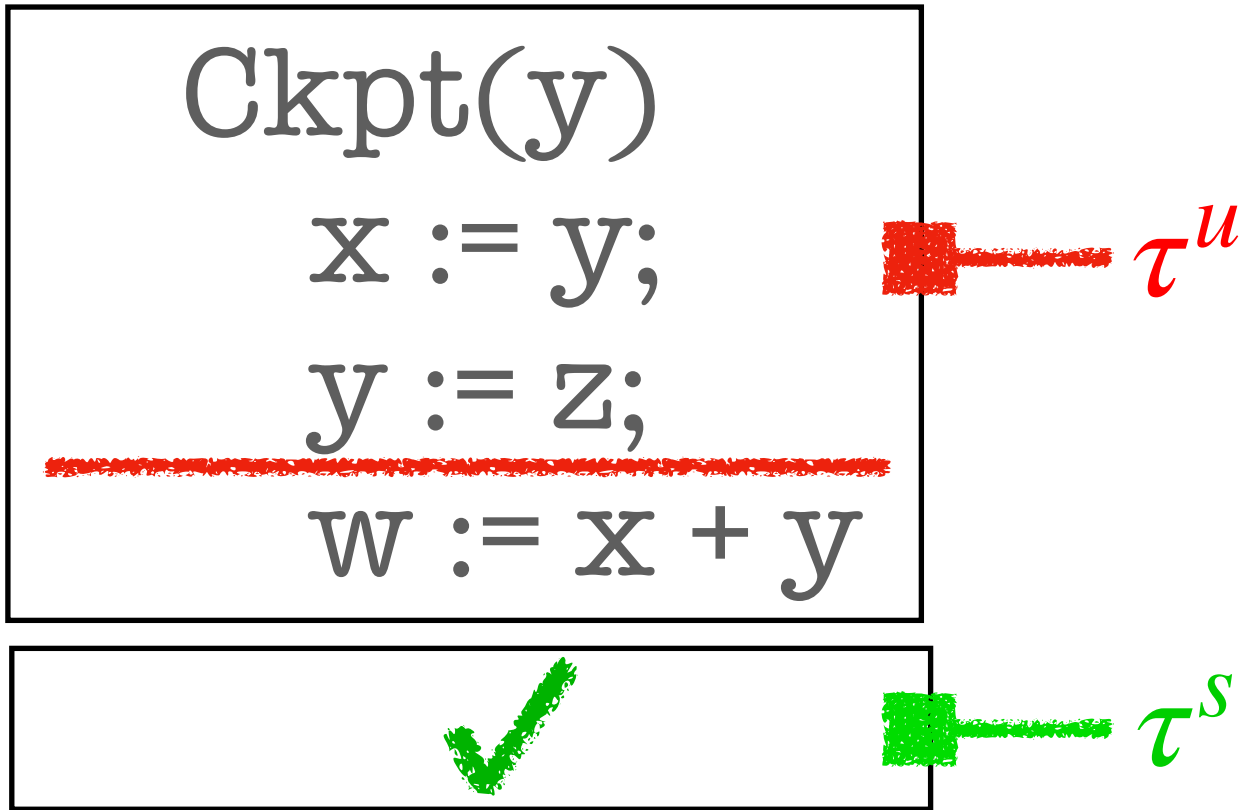
# Crash Type

basic types       $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types     $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$   
stable types       $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$



# Crash Type

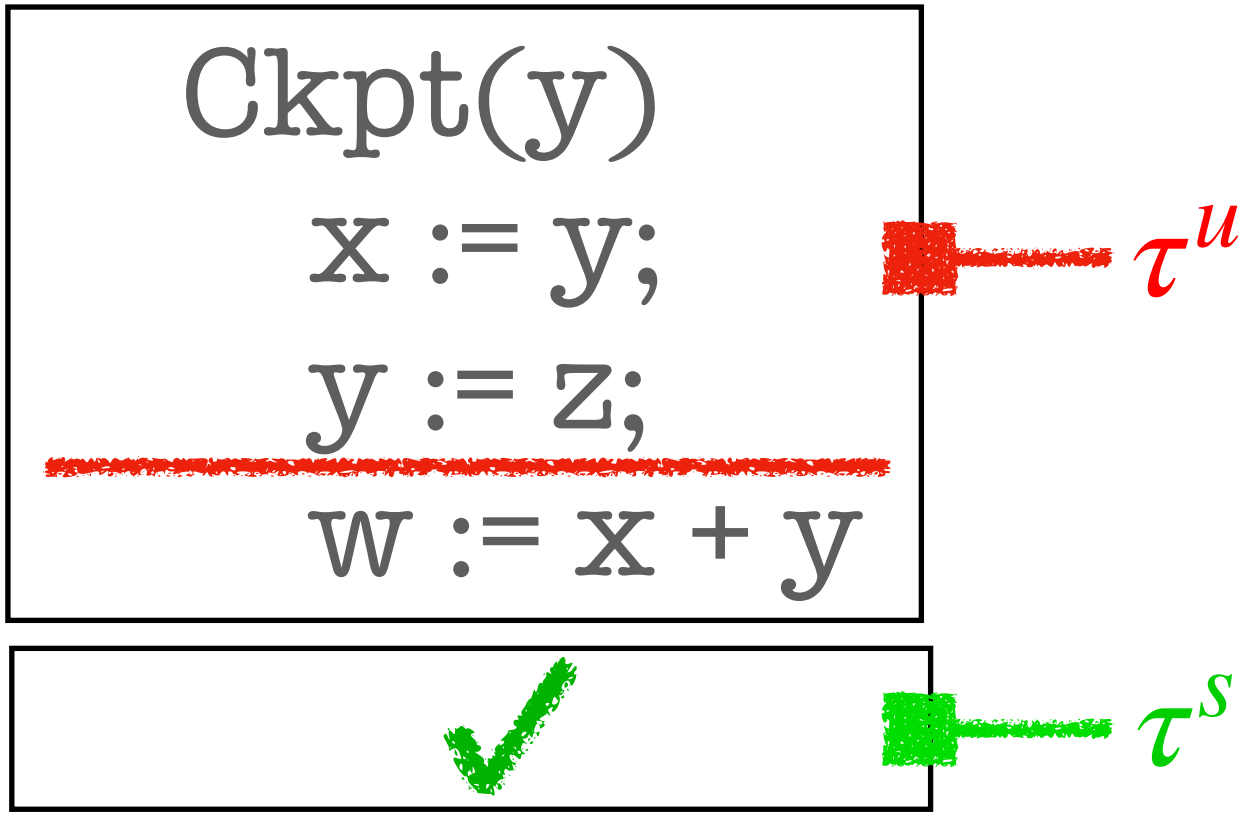
basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$   
stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{---}} \rightsquigarrow \tau^s$



$$C = \begin{array}{c} \text{Success!} \\ \downarrow \uparrow \text{unit} \vee \end{array} \begin{array}{c} \text{Successful} \\ \text{execution} \end{array} \quad \begin{array}{c} \text{Failed} \\ \text{execution} \end{array}$$

# Crash Type

|                   |                                                                        |
|-------------------|------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                    |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$       |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$  |
| stable types      | $\tau^s := \uparrow \tau^u \mid \text{[icon]} \rightsquigarrow \tau^s$ |



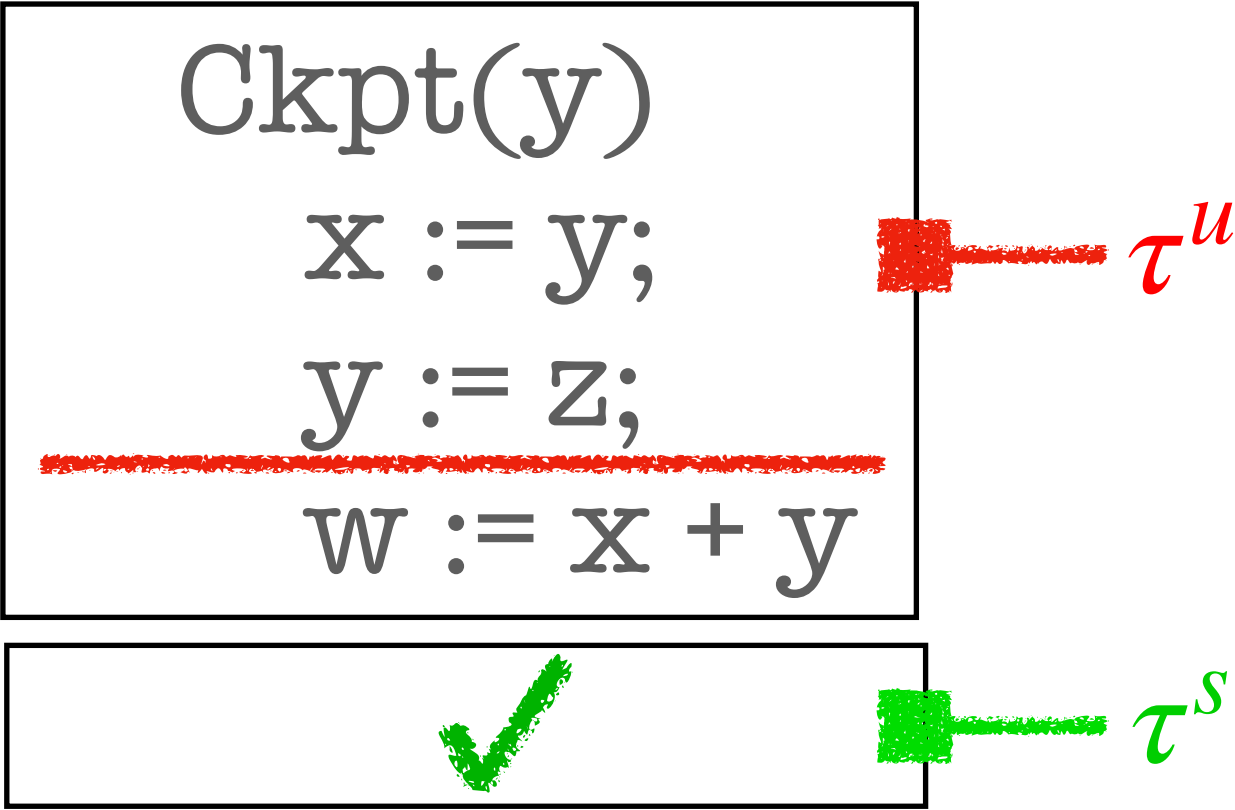
$$C = \downarrow \uparrow \text{unit} \vee \downarrow \text{PwOff}$$

Successful execution

Failed execution

# Crash Type

|                   |                                                                                                                   |
|-------------------|-------------------------------------------------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                                                               |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$                                                  |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$                                           |
| stable types      | $\tau^s := \uparrow \tau^u \mid \begin{array}{ c } \hline \text{ } \\ \hline \end{array} \rightsquigarrow \tau^s$ |



$$C = \downarrow \uparrow \text{unit} \vee \downarrow \left( \begin{array}{|c|} \hline \text{ } \\ \hline \end{array} \rightsquigarrow \text{Harvest} \right)$$

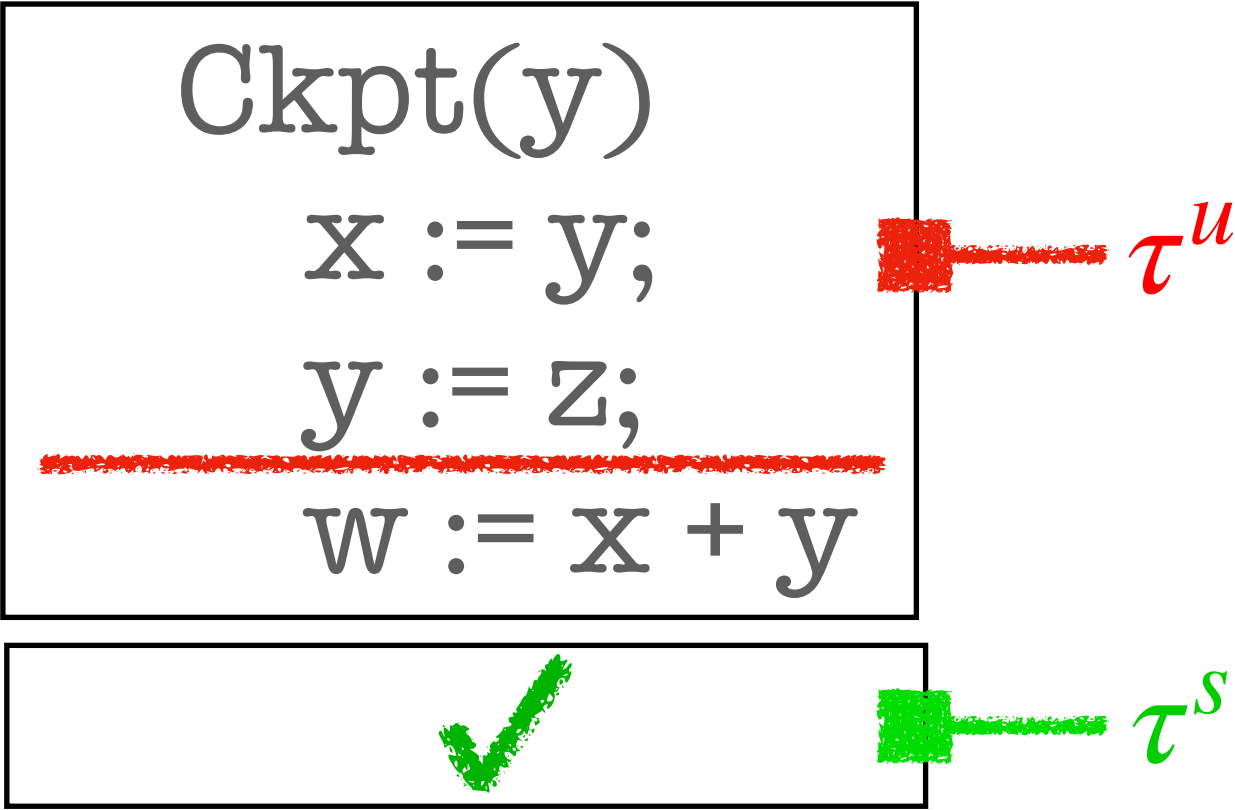
Successful execution

Failed execution



# Crash Type

basic types       $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types     $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$   
stable types       $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$



$$C = \downarrow \uparrow \text{unit} \vee \downarrow (\boxed{\text{||||}} \rightsquigarrow \uparrow C)$$

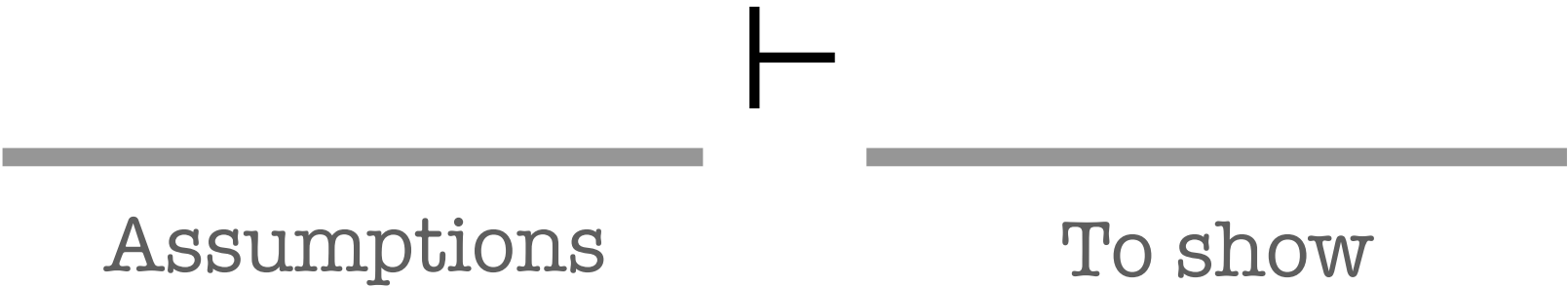
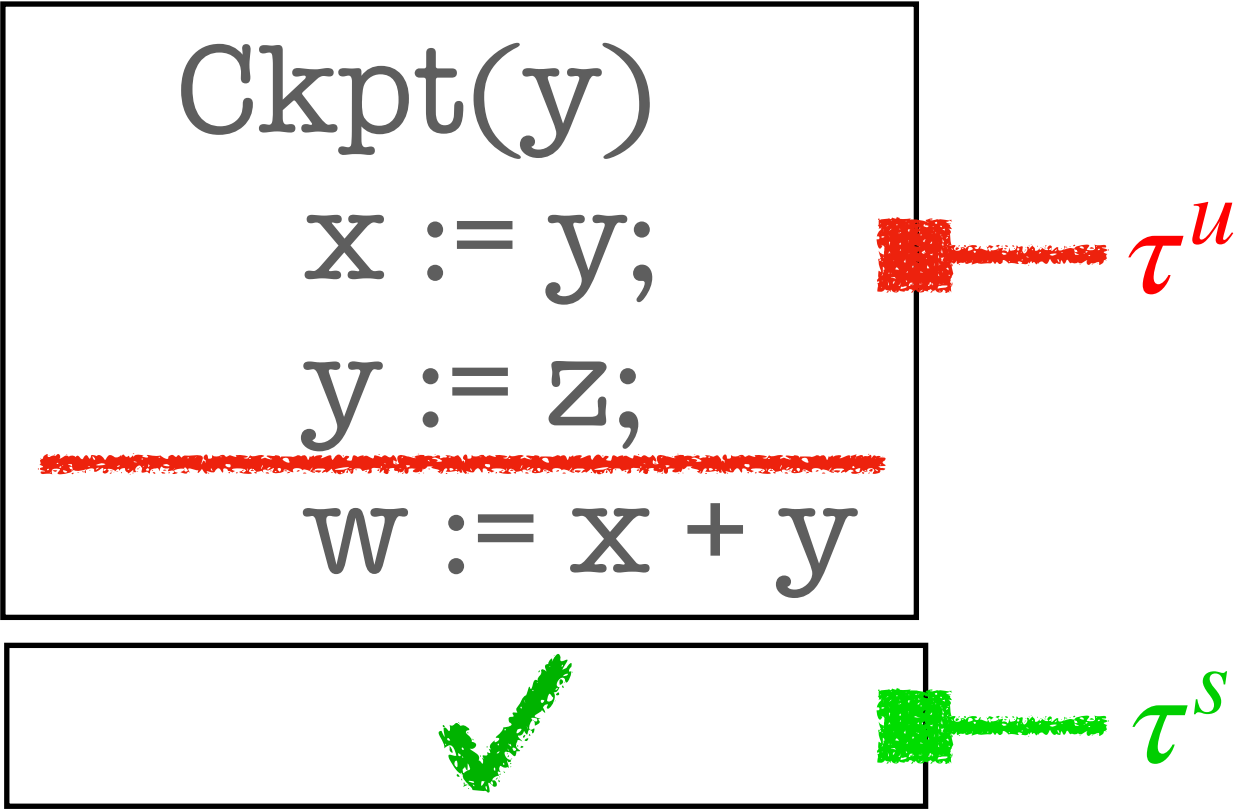
Successful execution

Failed execution

Re-execute

# Typing judgments

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^s}} \rightsquigarrow \tau^s$



# Typing judgments

basic types

$T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers

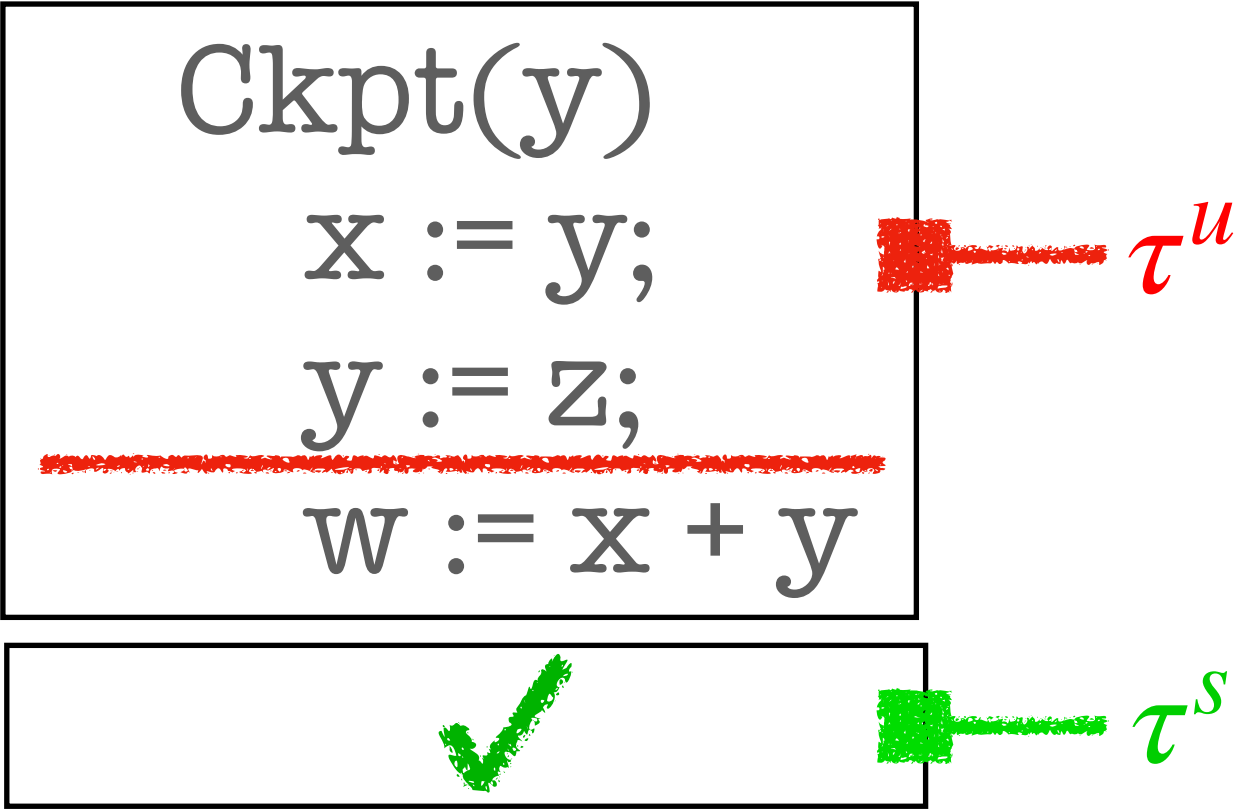
$q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types

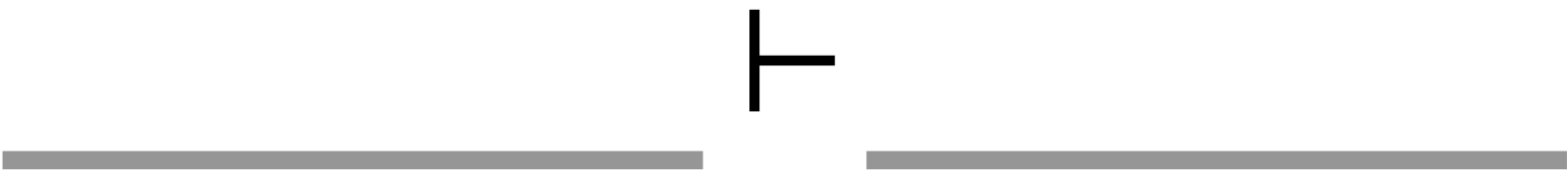
$\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid v_t$

stable types

$\tau^s := \uparrow \tau^u \mid \text{[memory icon]} \rightsquigarrow \tau^s$



Unstable typing judgment

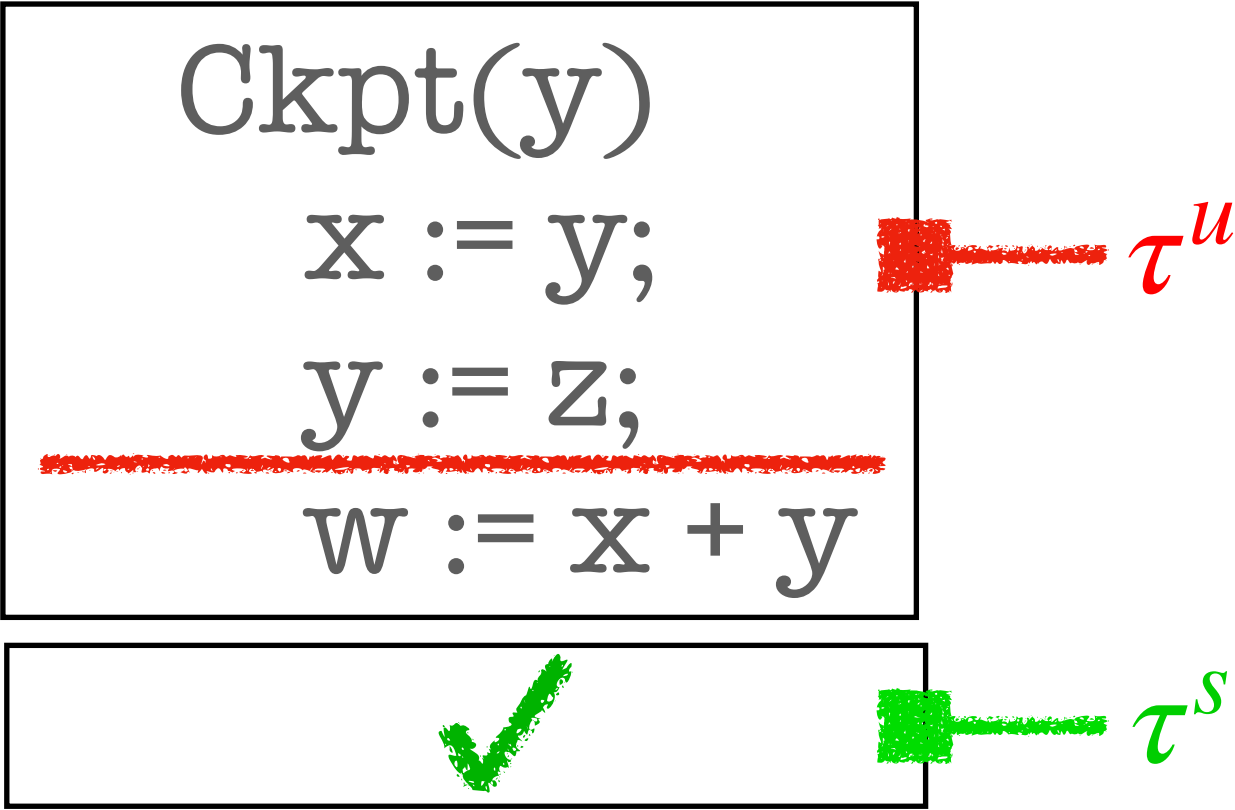


Stable typing judgment

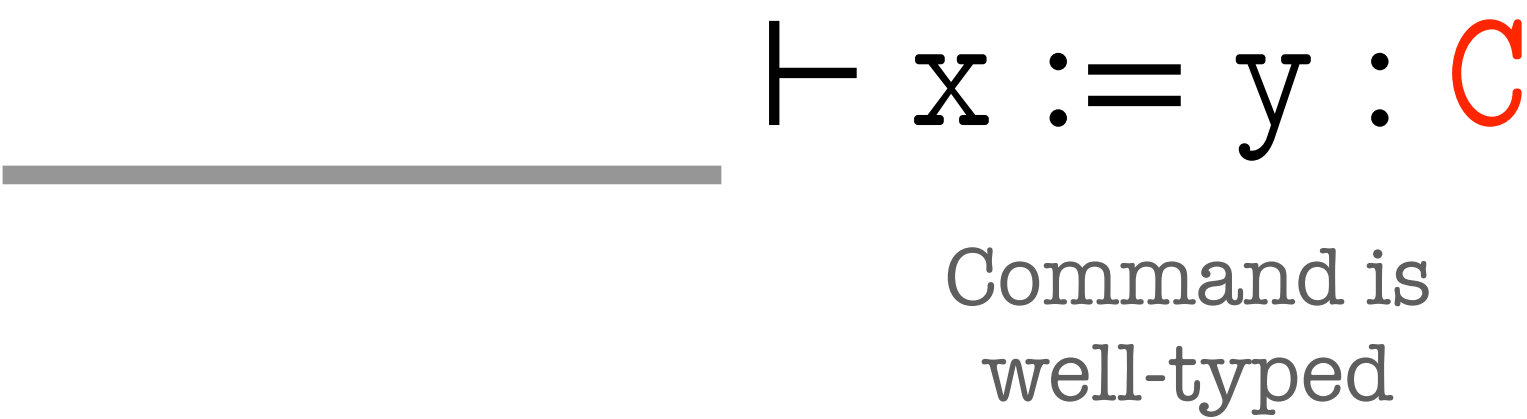


# Typing judgments

|                   |                                                                           |
|-------------------|---------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                       |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$          |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^s}} \leadsto \tau^s$ |



## Unstable typing judgment

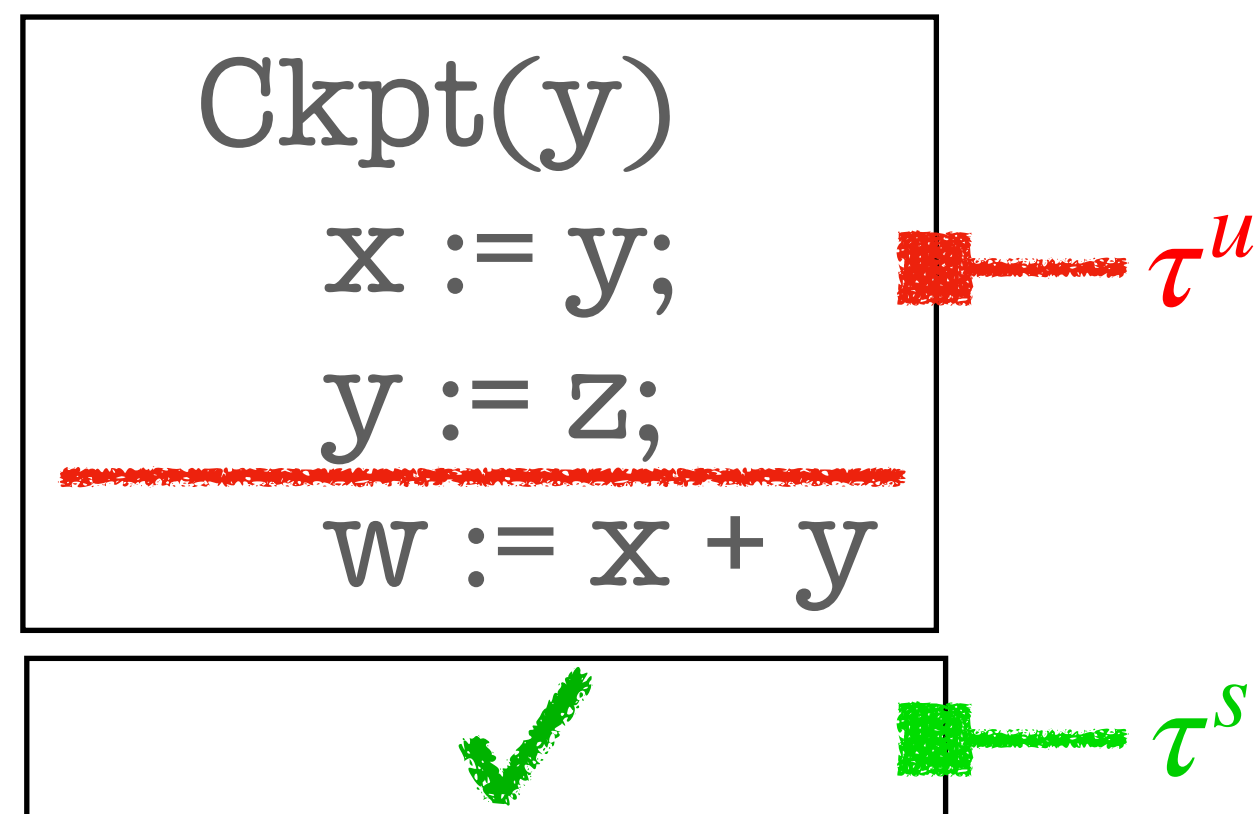


## Stable typing judgment



# Typing judgments

|                   |                                                                                   |
|-------------------|-----------------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                               |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$                  |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$           |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^u}} \rightsquigarrow \tau^s$ |



## Unstable typing judgment

Energy buffer

## Stable typing judgment

# Typing judgments

basic types

$T := \text{int} \mid \text{bool} \mid \text{unit}$

access qualifiers

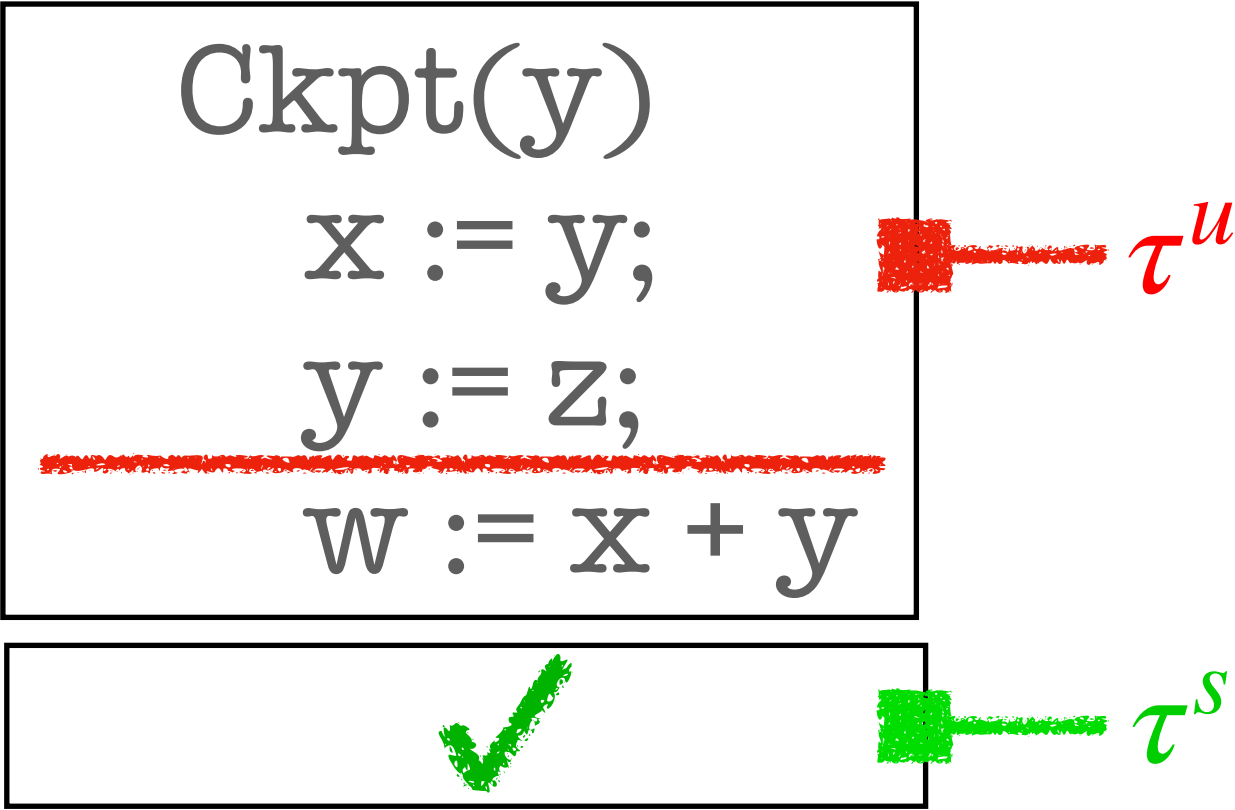
$q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$

unstable types

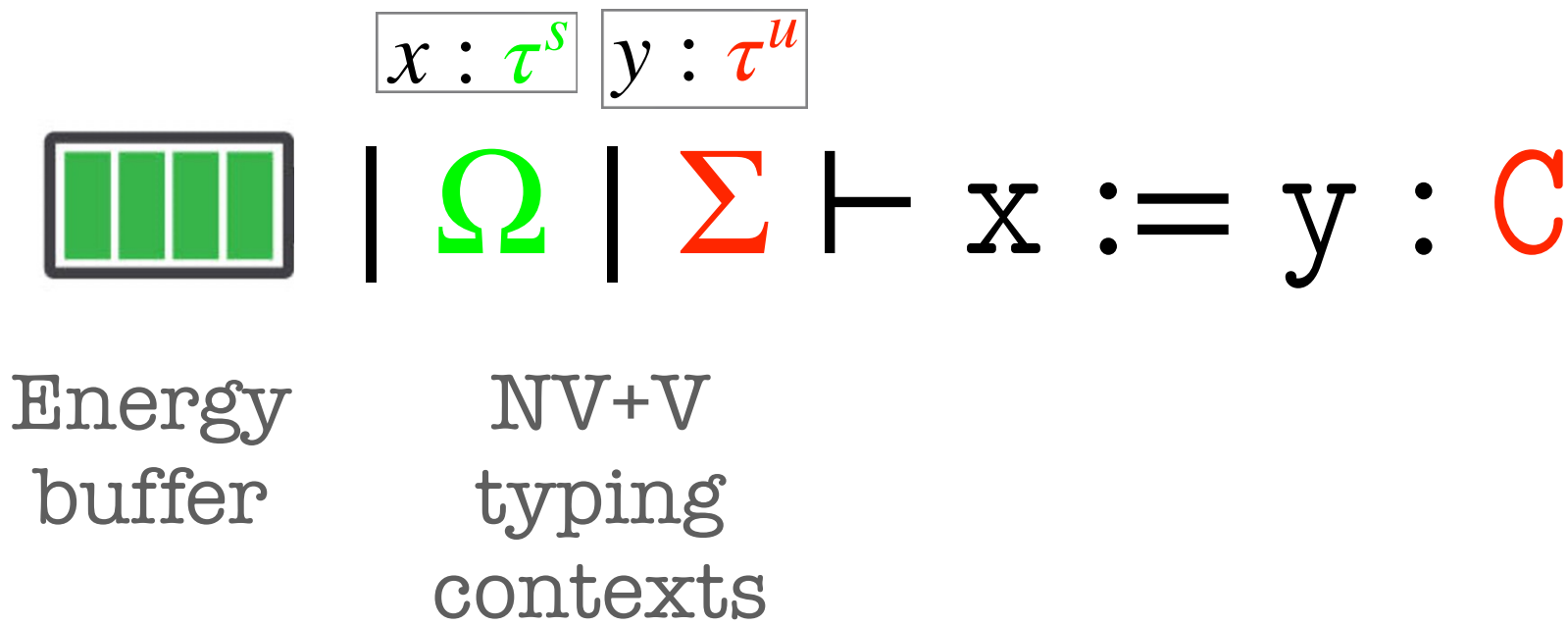
$\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$

stable types

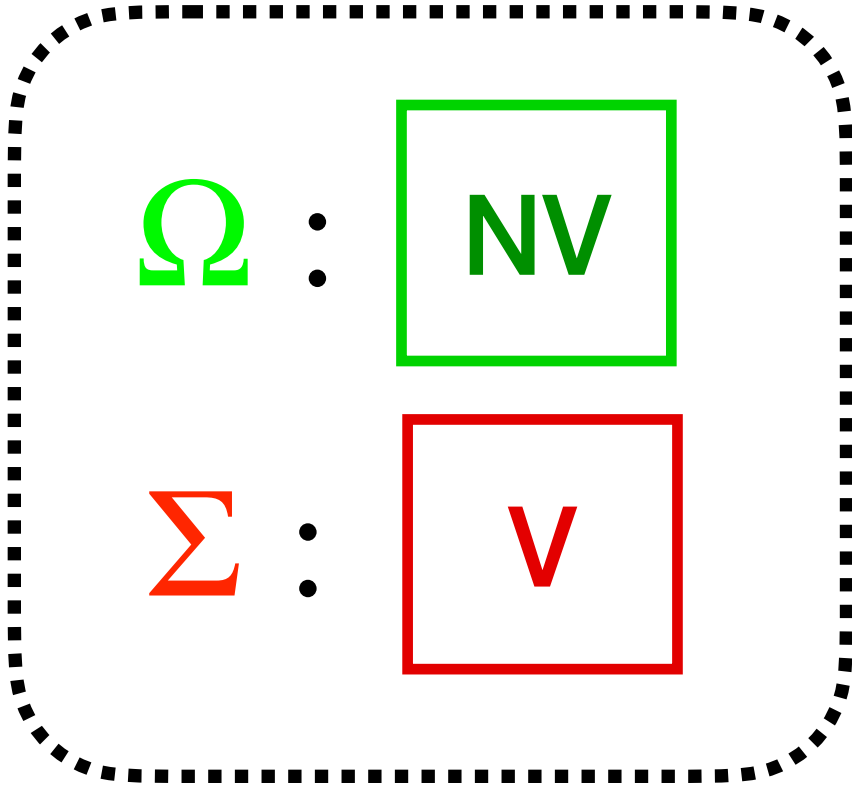
$\tau^s := \uparrow \tau^u \mid \text{Energy buffer} \rightsquigarrow \tau^s$



## Unstable typing judgment

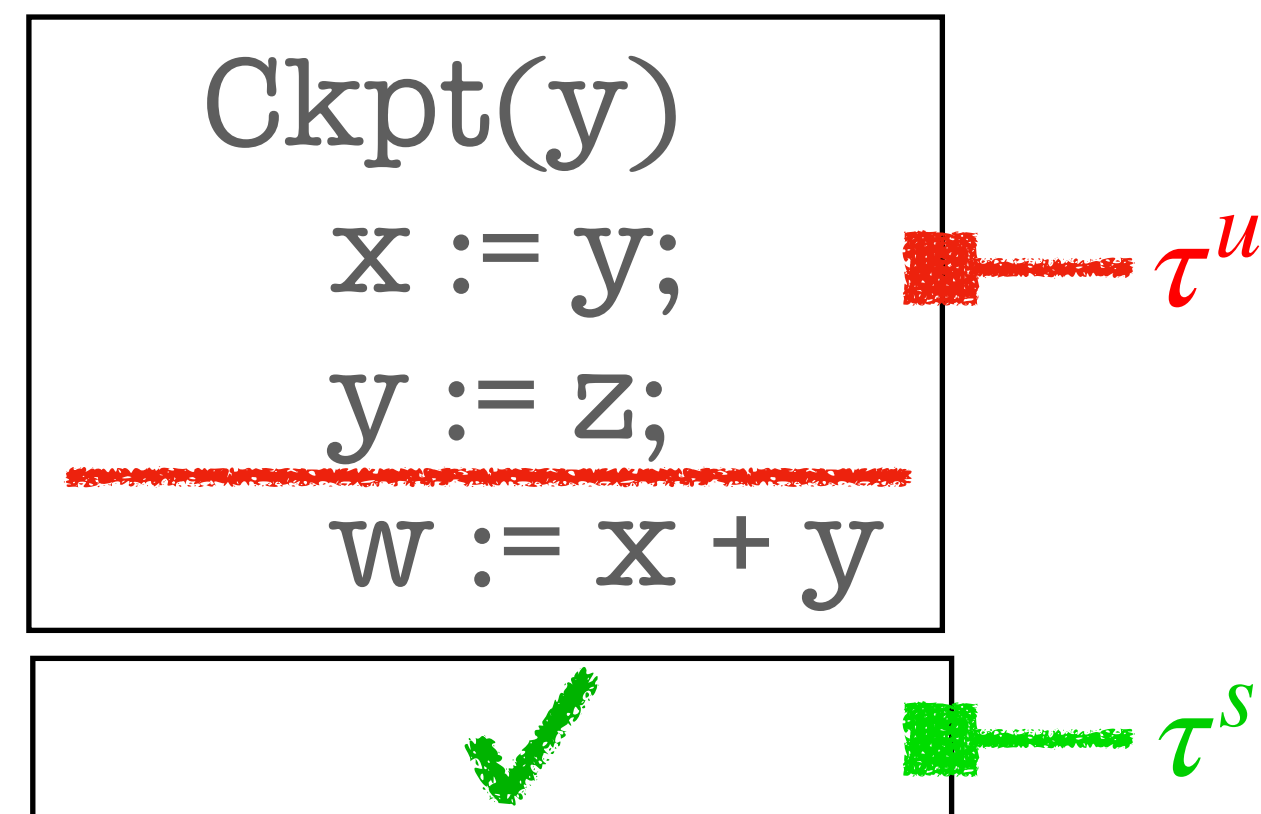


## Stable typing judgment



# Typing judgments

|                   |                                                                                   |
|-------------------|-----------------------------------------------------------------------------------|
| basic types       | $T := \text{int} \mid \text{bool} \mid \text{unit}$                               |
| access qualifiers | $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$                  |
| unstable types    | $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$           |
| stable types      | $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^u}} \rightsquigarrow \tau^s$ |



## Unstable typing judgment

Diagram illustrating the typing rule for assignment:

The rule is represented as a sequence of components separated by vertical bars:

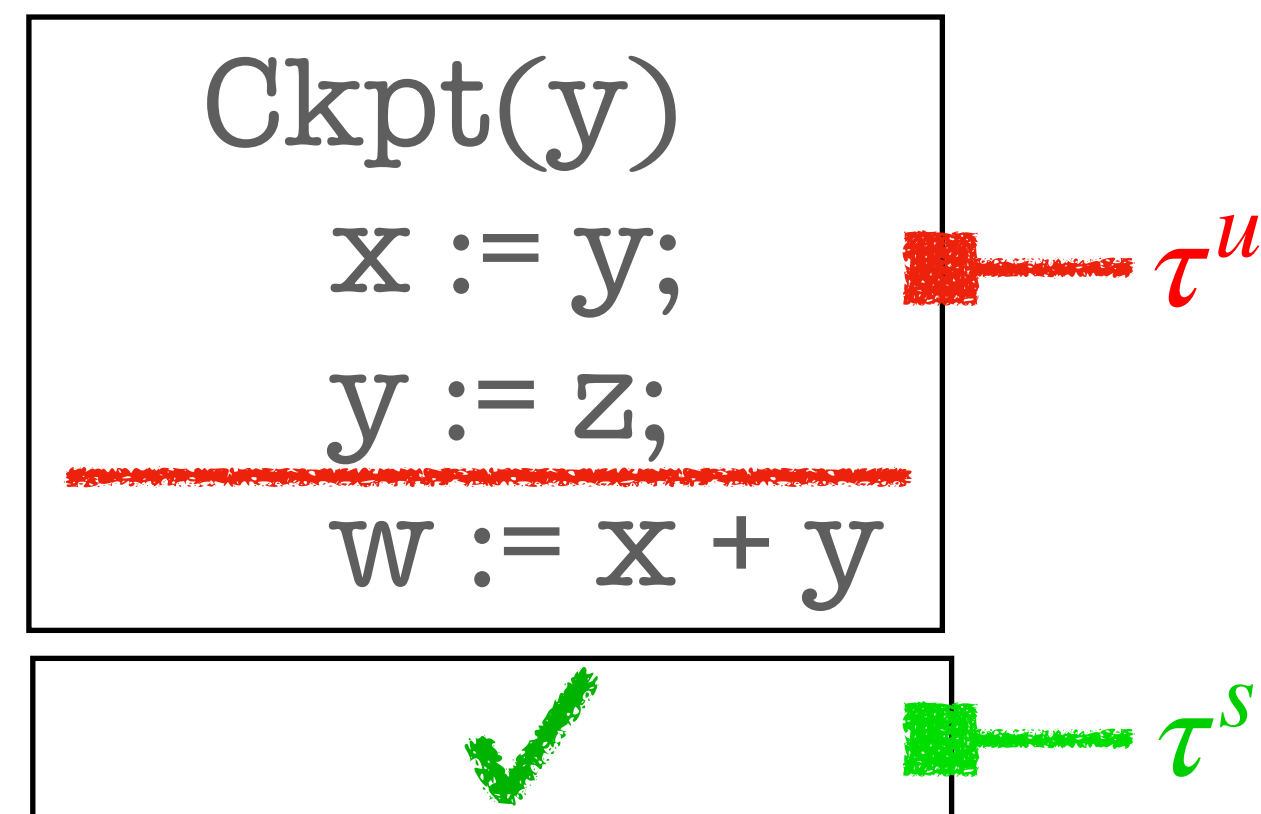
- Energy buffer:** Represented by a green icon with four vertical bars.
- NV+V typing contexts:** Two contexts,  $\Omega$  (green) and  $\Sigma$  (red), are shown. Above them are boxes containing variable annotations:  $x : \tau^s$  (green) and  $y : \tau^u$  (red).
- Assignment typing judgment:**  $x := y : \mathbb{C}$  (red).
- Post-context:**  $\Omega'$  (green).

The entire sequence is followed by a turnstile symbol  $\vdash$ .

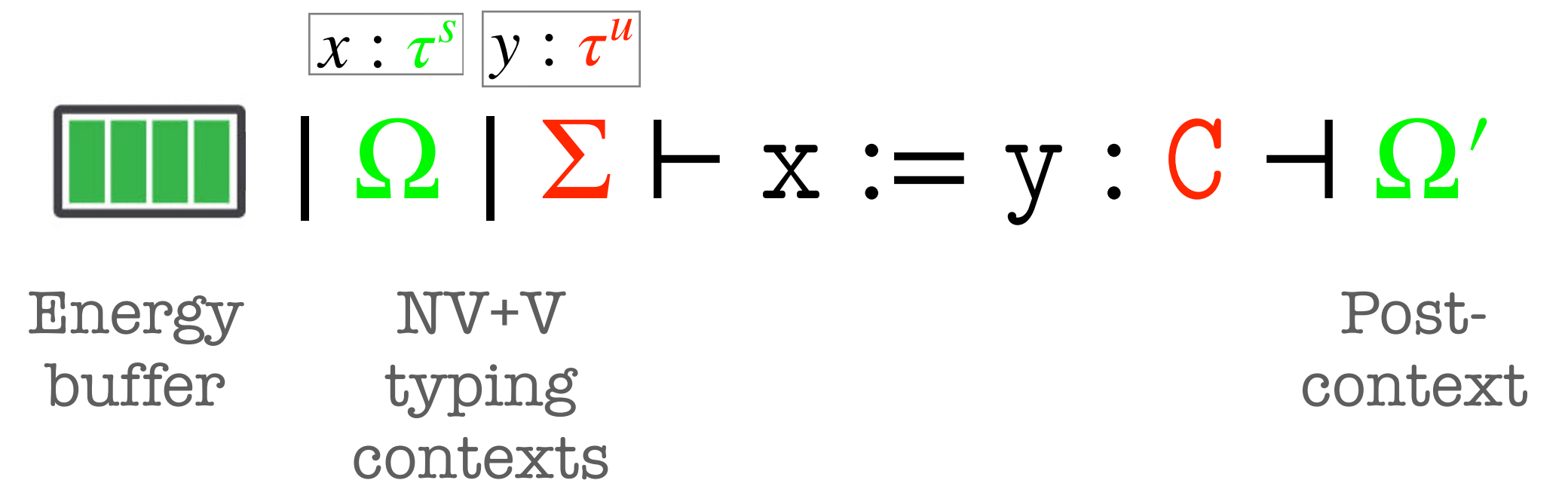
## Stable typing judgment

# Typing judgments

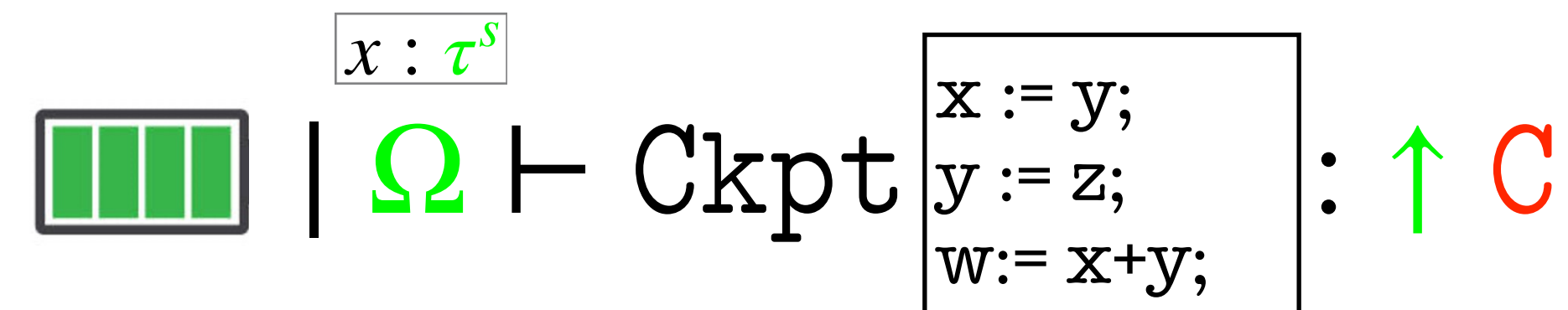
basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
 access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
 unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
 stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$



## Unstable typing judgment

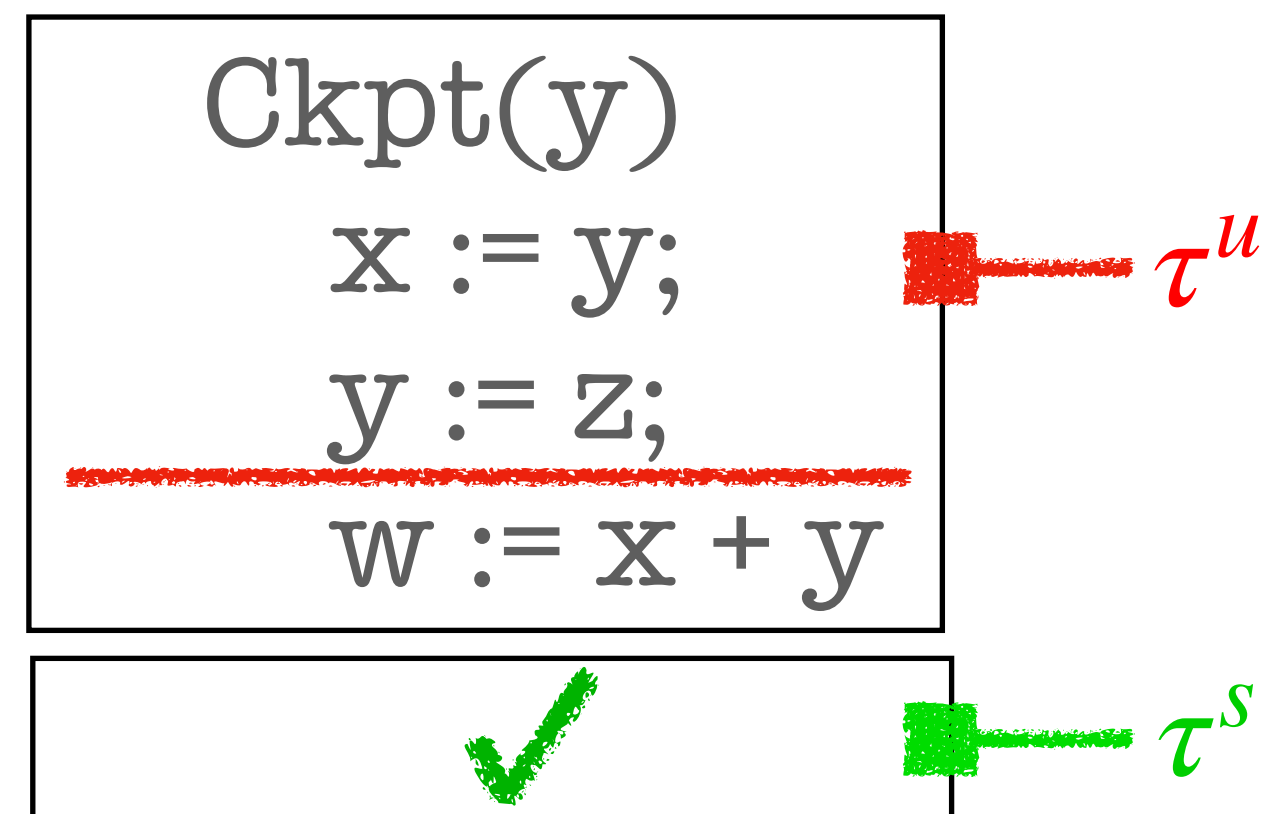


## Stable typing judgment



# Typing a program bottom-up

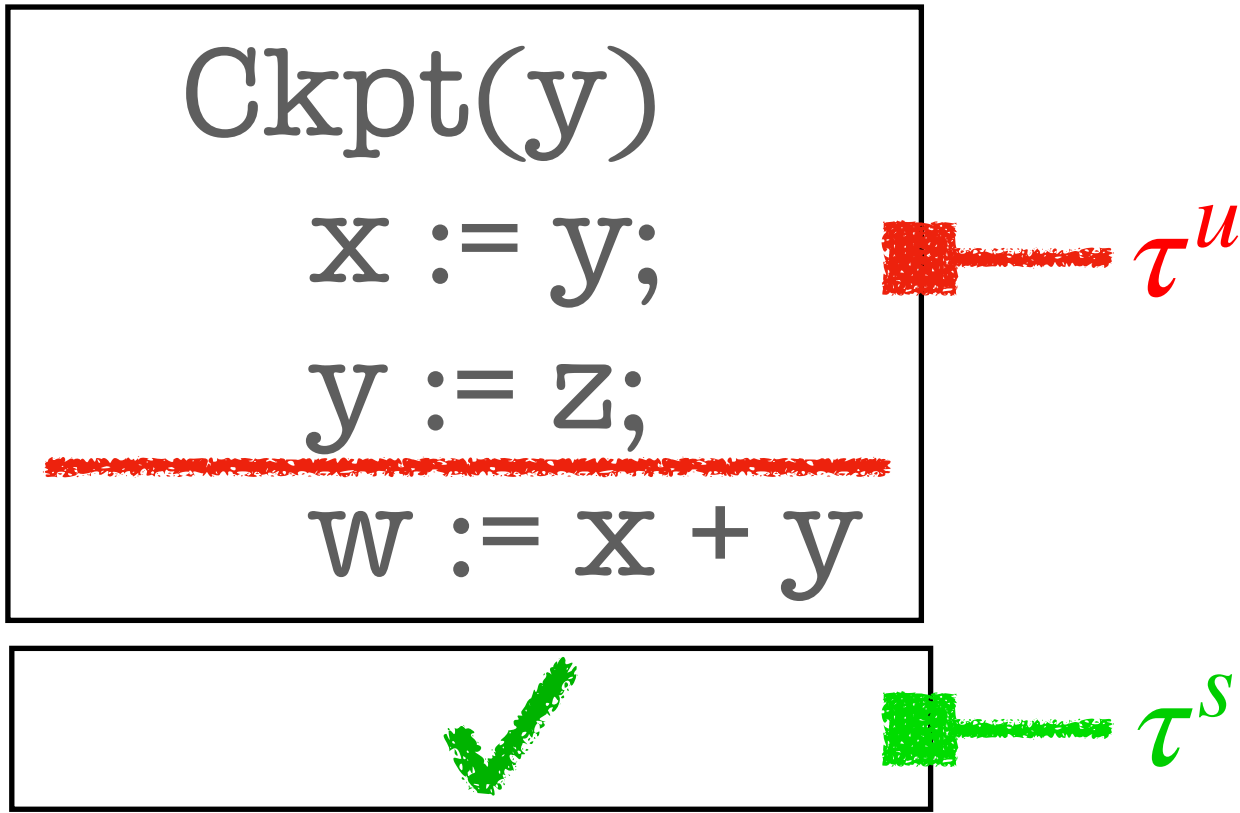
basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
 access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
 unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
 stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$



$\boxed{\text{||||}} \mid \Omega \vdash \text{Ckpt} \begin{array}{l} x := y; \\ y := z; \\ w := x+y; \end{array} : \uparrow C$

# Typing a command

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$

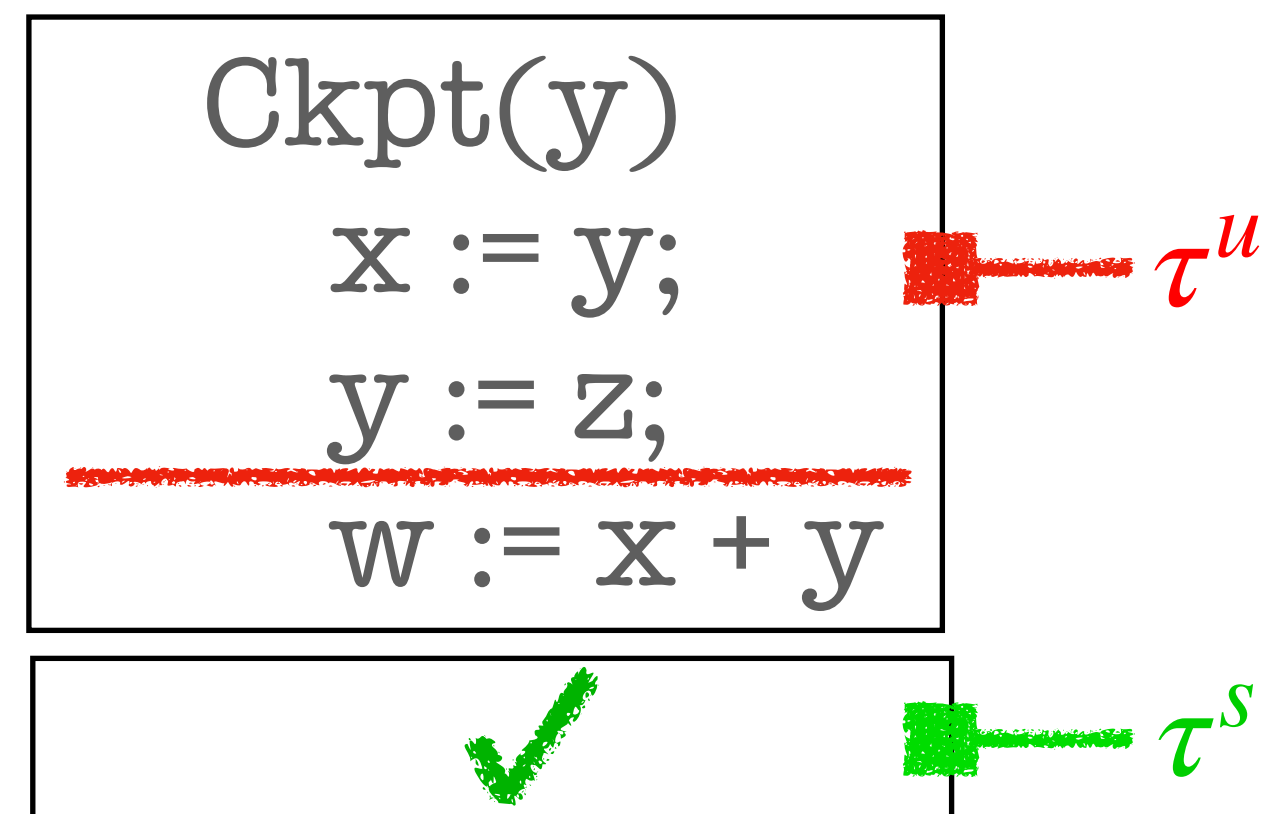


$\boxed{\text{||||}} \mid \Omega \mid \Sigma \vdash x := y;$   
 $y := z;$   
 $w := x + y : C \dashv \Omega'''$

$\boxed{\text{||||}} \mid \Omega \vdash \text{Ckpt} \begin{matrix} x := y; \\ y := z; \\ w := x + y; \end{matrix} : \uparrow C$

# Typing a smaller command

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
 access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
 unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
 stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\text{||||}} \rightsquigarrow \tau^s$



$\boxed{\text{||||}} \mid \Omega \mid \Sigma \vdash x := y;$   
 $y := z : \text{C} \dashv \Omega'' \quad \dots$

$\boxed{\text{||||}} \mid \Omega \mid \Sigma \vdash x := y;$   
 $y := z;$   
 $w := x + y : \text{C} \dashv \Omega'''$

$\boxed{\text{||||}} \mid \Omega \vdash \text{Ckpt} \begin{array}{l} x := y; \\ y := z; \\ w := x + y; \end{array} : \uparrow \text{C}$

# Type checking $x:=y; y:=z$

basic types  $T := \text{int} \mid \text{bool} \mid \text{unit}$   
 access qualifiers  $q := \text{CK} \mid \text{RD} \mid \text{MtWt} \mid \text{Wtn}$   
 unstable types  $\tau^u := T \mid \downarrow \tau^s \mid \tau^u \vee \tau^u \mid \nu_t$   
 stable types  $\tau^s := \uparrow \tau^u \mid \boxed{\phantom{\tau^s}} \leadsto \tau^s$

$\text{MtWt}$   $\text{Ckpt}(y)$   
 $\text{CK}$   $x := y;$   
 $y := z;$   $\text{RD}$   
 $w := x + y$   $\text{Wtn}$

$x : \text{MtWt}, y : \text{CK}$   $x : \text{Wtn}, y : \text{CK}$   
 $\boxed{\phantom{\tau^s}} \mid \Omega \mid \Sigma \vdash x := y : \text{C} \dashv \Omega'$   
 $\boxed{\phantom{\tau^s}} \mid \Omega' \mid \Sigma \vdash y := z : \tau^u \dashv \Omega''$   


---

 $\boxed{\phantom{\tau^s}} \mid \Omega \mid \Sigma \vdash x := y; y := z : \tau^u \dashv \Omega''$   
 $x : \text{Wtn}, y : \text{CK}$

# Example

1

Ckpt(y)

2

x := y;

3

y := z;

4

w := x + y

NV

| x    | y  | z  | w    |
|------|----|----|------|
| MtWt | CK | RD | MtWt |
| 0    | 1  | 2  | 0    |

NV

| x    | y  | z  | w    |
|------|----|----|------|
| MtWt | CK | RD | MtWt |
| 0    | 1  | 2  | 0    |

# Example

1

Ckpt(y)

2

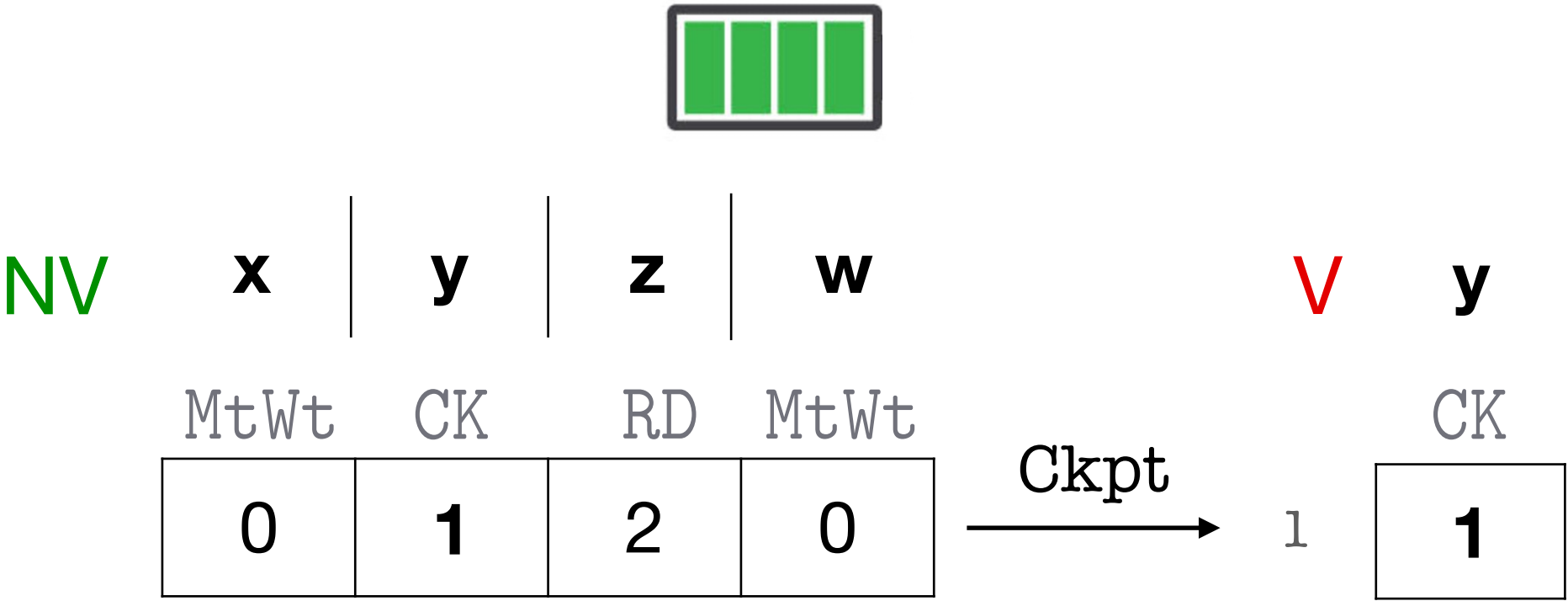
x := y;

3

y := z;

4

w := x + y



# Example

1

Ckpt(y)

2

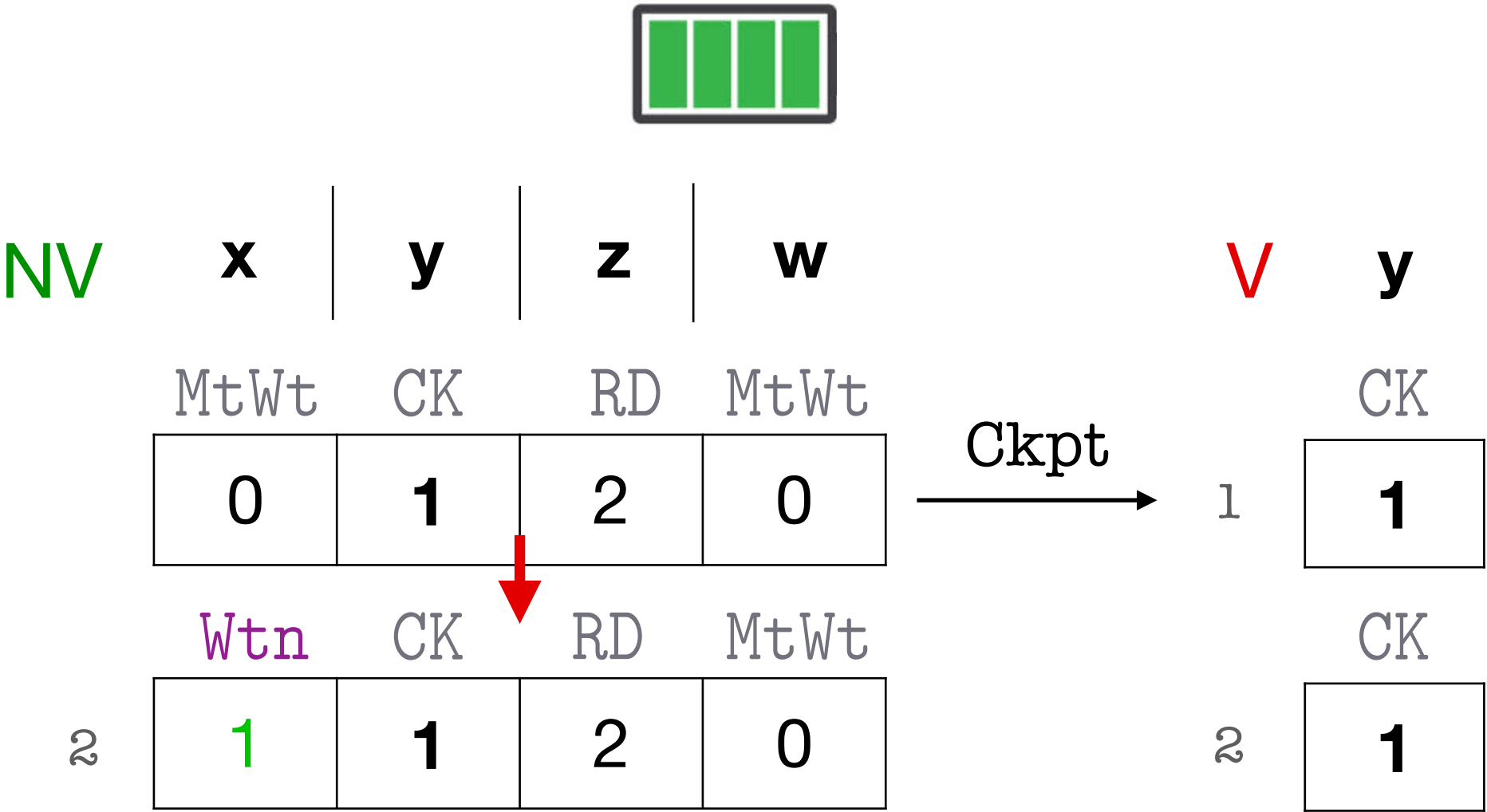
x := y;

3

y := z;

4

w := x + y



# Example

1

Ckpt(y)

2

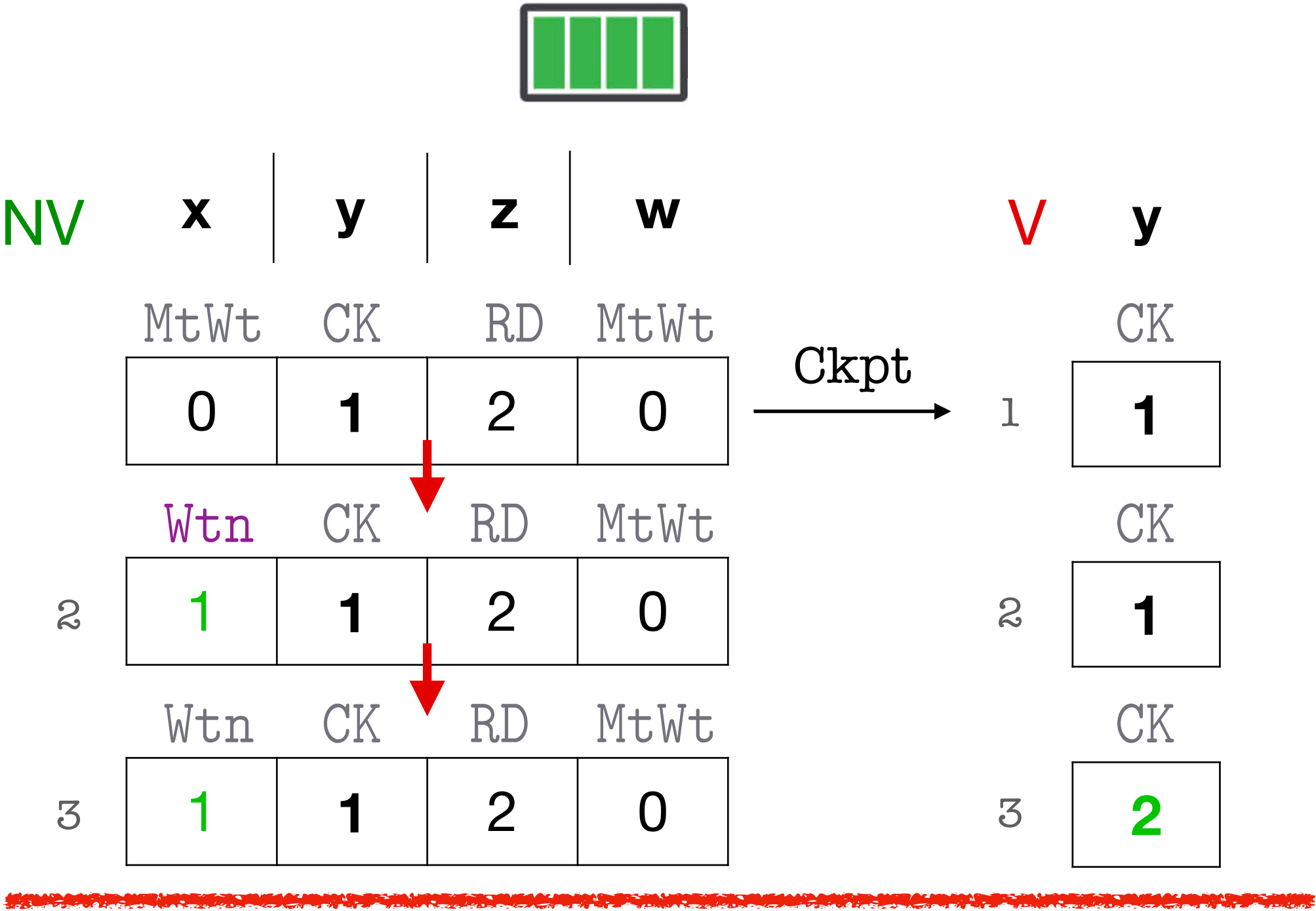
x := y;

3

y := z;

4

w := x + y



2

Wtn

CK

RD

MtWt

1

1

2

0

3

Wtn

CK

RD

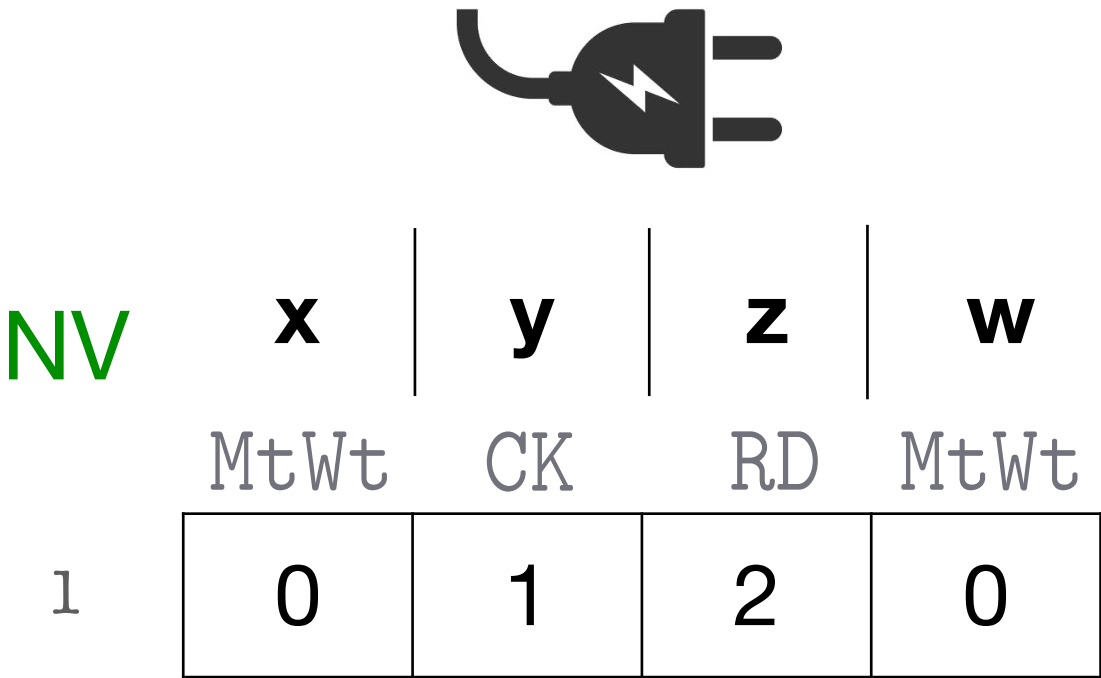
MtWt

1

1

2

0



# Example

1

Ckpt(y)

2

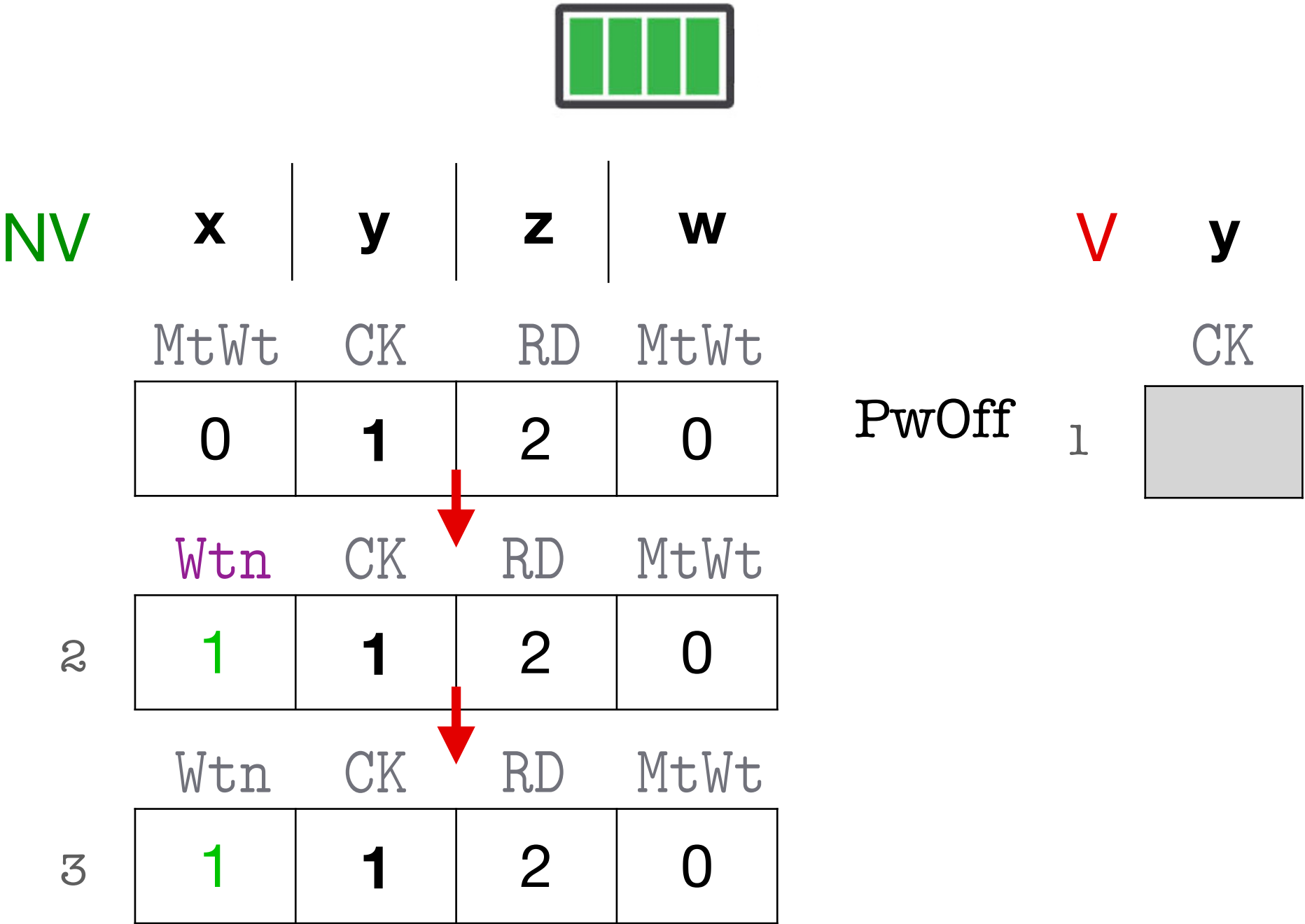
x := y;

3

y := z;

4

w := x + y



3

Wtn

CK

RD

MtWt

1

1

2

0

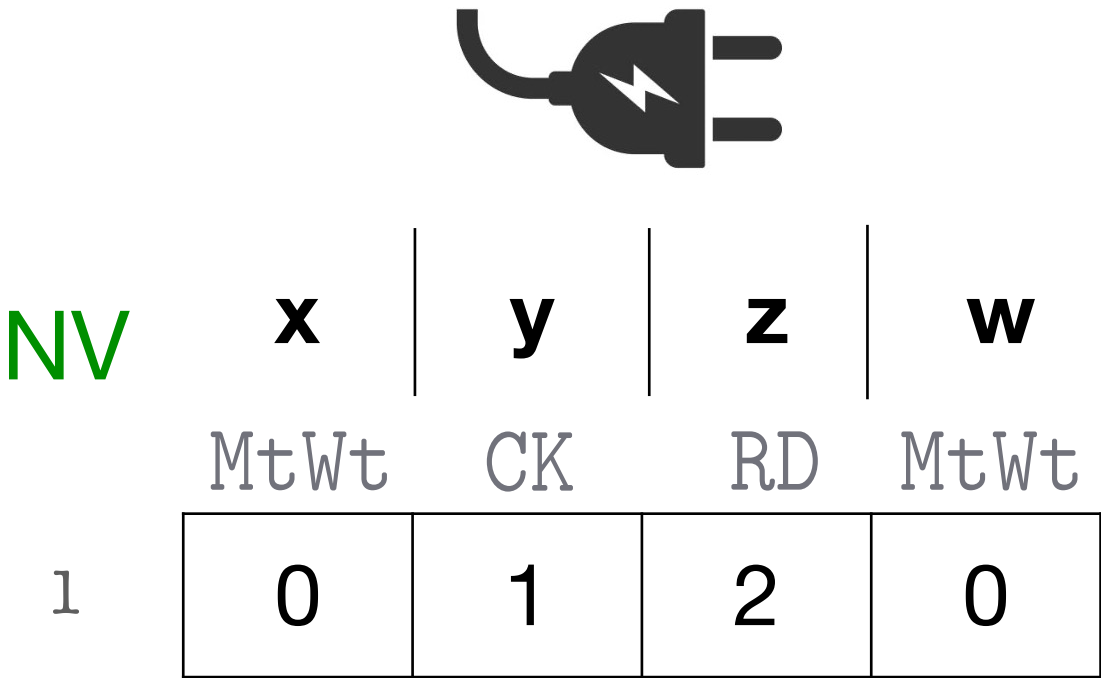
PwOff

1

CK

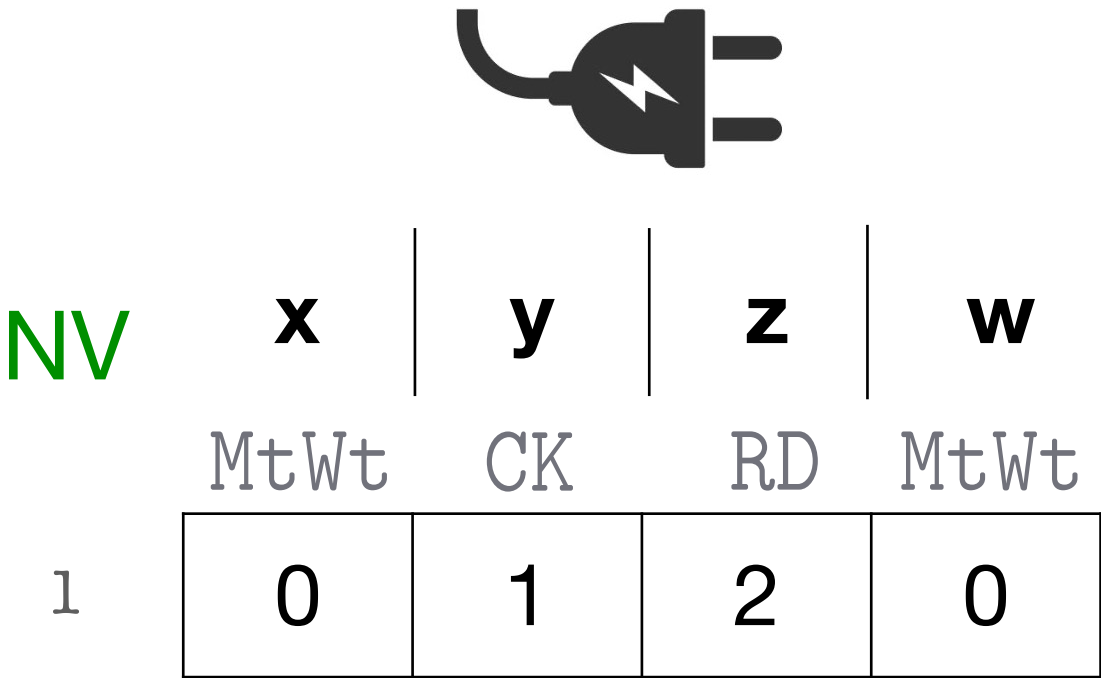
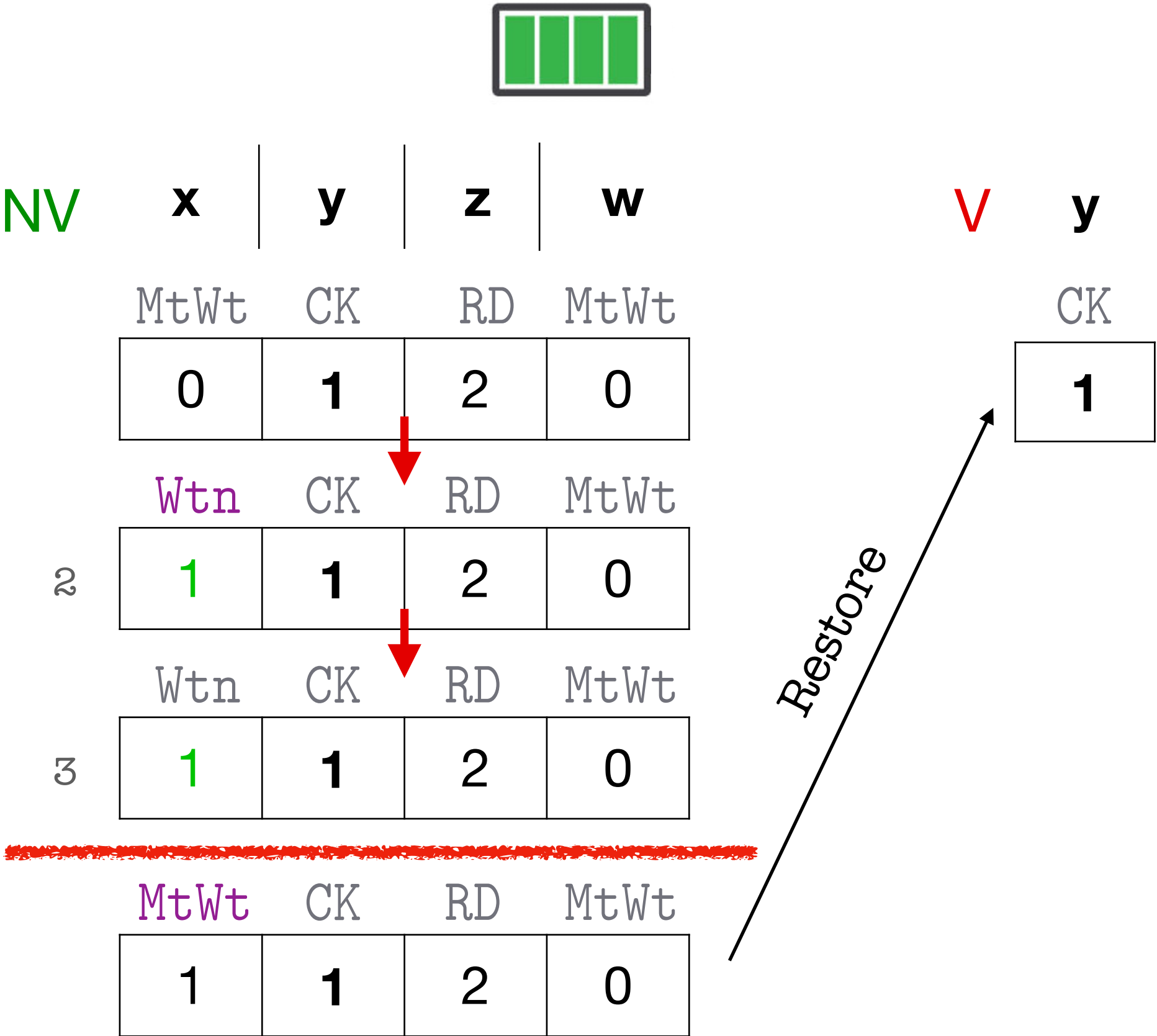
V

y



# Example

```
1 Ckpt(y)
2  x := y;
3  y := z;
4  w := x + y
```





NV

Wtn

2

MtWt

Wtn

**y**

CK

CK

1

NV

MtWt

# Example

1

Ckpt(y)

2

x := y;

3

y := z;

4

w := x + y

|    |      |    |    |      |
|----|------|----|----|------|
| NV | x    | y  | z  | w    |
|    | MtWt | CK | RD | MtWt |
|    | 0    | 1  | 2  | 0    |
|    | Wtn  | CK | RD | MtWt |
| 2  | 1    | 1  | 2  | 0    |
|    | Wtn  | CK | RD | MtWt |
| 3  | 1    | 1  | 2  | 0    |

|   |      |    |    |      |
|---|------|----|----|------|
|   | MtWt | CK | RD | MtWt |
|   | 1    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | MtWt |
| 2 | 1    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | MtWt |
| 3 | 1    | 1  | 2  | 0    |

|   |    |
|---|----|
| V | y  |
|   | CK |
|   | 1  |

|    |      |    |    |      |
|----|------|----|----|------|
| NV | x    | y  | z  | w    |
|    | MtWt | CK | RD | MtWt |
| 1  | 0    | 1  | 2  | 0    |

|   |    |
|---|----|
|   | CK |
| 2 | 1  |
|   | CK |
| 3 | 2  |



NV

Wtn

2

MtWt

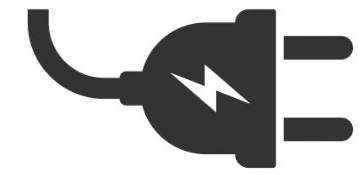
Wtn

234

**y**

CKCKCKCK

NV

1

# Example

1

Ckpt(y)

2

x := y;

3

y := z;

4

w := x + y

NV

|   | x    | y  | z  | w    |
|---|------|----|----|------|
|   | MtWt | CK | RD | MtWt |
|   | 0    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | MtWt |
| 2 | 1    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | MtWt |
| 3 | 1    | 1  | 2  | 0    |

|   | MtWt | CK | RD | MtWt |
|---|------|----|----|------|
|   | 1    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | MtWt |
| 2 | 1    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | MtWt |
| 3 | 1    | 1  | 2  | 0    |
|   | Wtn  | CK | RD | Wtn  |
| 4 | 1    | 2  | 2  | 3    |

Commit

V

y

|    |
|----|
| CK |
| 1  |

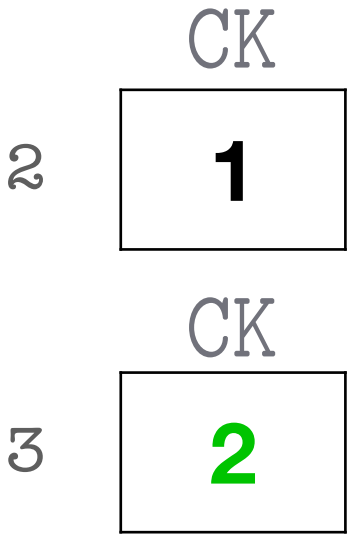
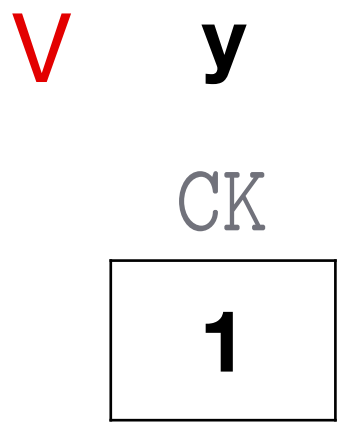
|    |
|----|
| CK |
| 1  |
| CK |
| 2  |
| CK |
| 2  |

NV

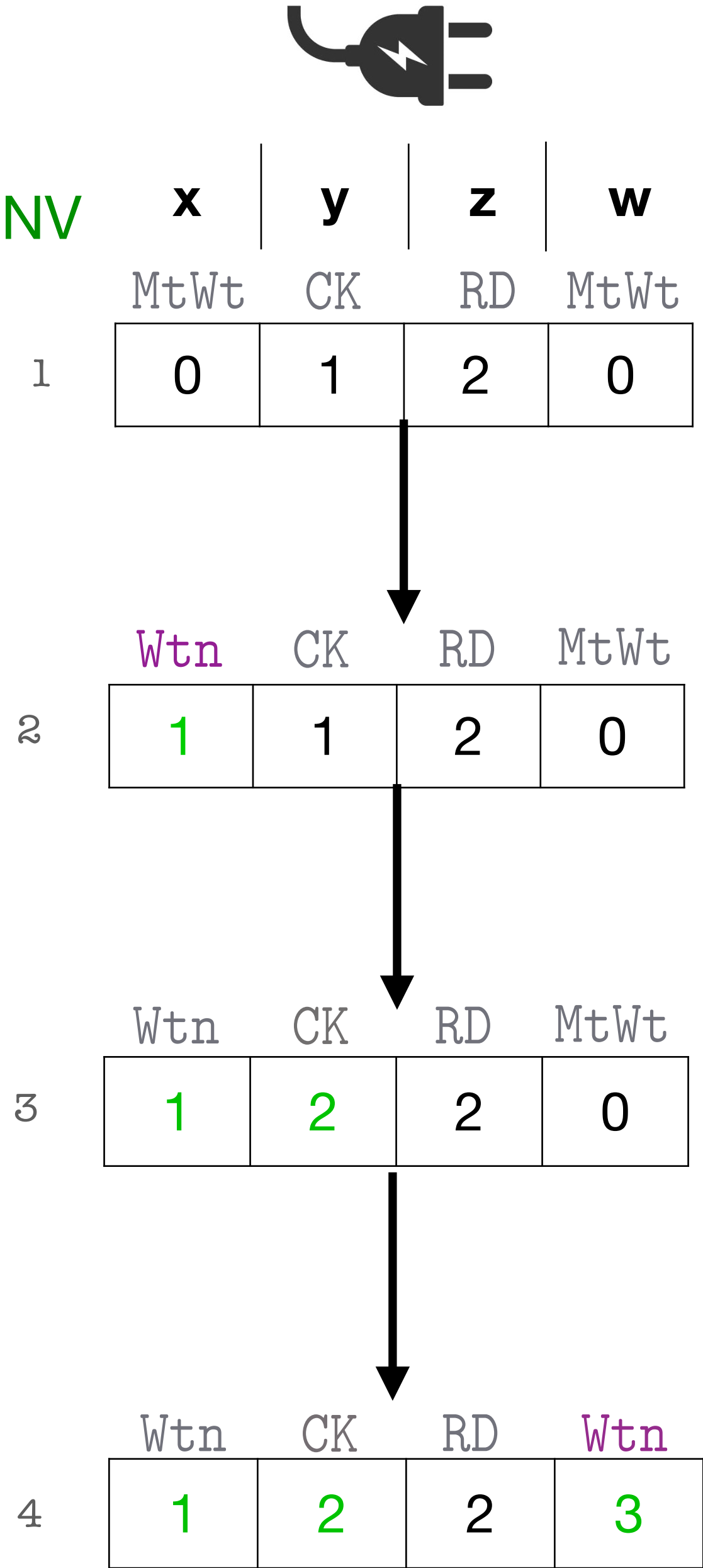
|   | x    | y  | z  | w    |
|---|------|----|----|------|
|   | MtWt | CK | RD | MtWt |
| 1 | 0    | 1  | 2  | 0    |

# Example

```
1 Ckpt(y)
2 x := y;
3 y := z;
4 w := x + y
```



=

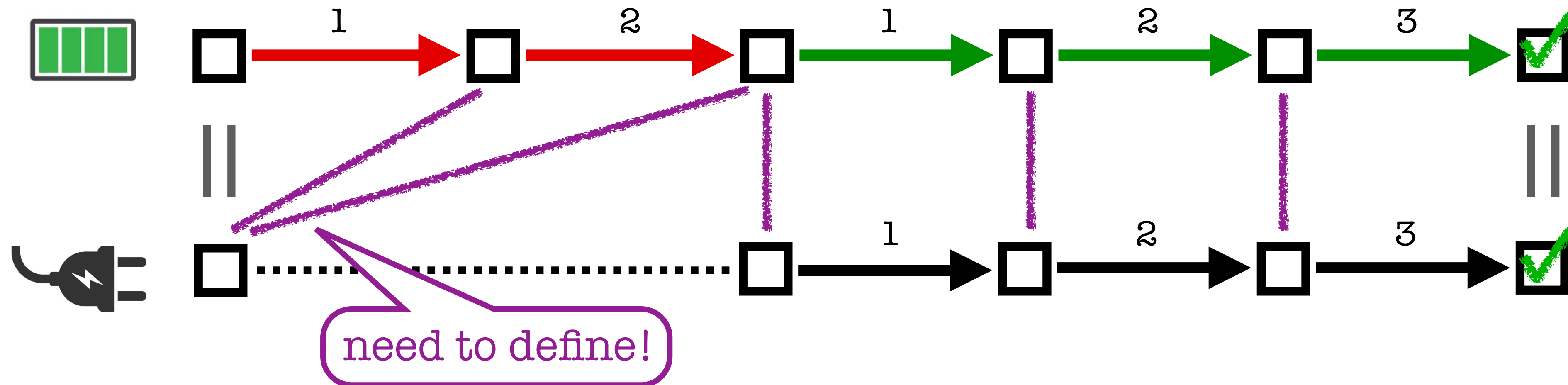


# Outline

- Intermittent computing
- Overview
- Type system
- **Logical relation**
- JIT mode
- Key theorems
- Conclusion

# Proving Correctness

Every intermittent execution of a **well-typed** program can be simulated by its continuous execution.



# Binary Logical Relation

Every intermittent execution of a **well-typed** program can be simulated by its continuous execution.

---


$$\begin{array}{c}
 \left( \begin{array}{c} \text{🔋} \\ \text{INV} \mid V \mid c_1 \end{array}, \begin{array}{c} \text{🔌} \\ \text{INV} \mid V \mid c_2 \end{array} \right) \in \text{__} \text{ } \overset{\# \text{ crashes } \text{👁👁}}{\text{[C}_{Unit}\text{]}^m} \\
 \begin{array}{ccc}
 \text{Intermittent execution} & \text{Continuous execution} & \text{Crash type}
 \end{array}
 \end{array}$$

# Term Relation

$$(\text{🔋} \text{ INV } | V | \underline{c_1}, \text{🔌} \text{ INV } | V | c_2) \in \underline{\mathcal{E}} [\mathbf{C}_{Unit}]^m$$


---

where  $c_1$  is...

$x := y$

$c_1; c_2$

if  $v$  then  $c_1$  else  $c_2$

let  $x = e$  in  $c$

# Value Relation

$$(\text{🔋} \mid \text{INV} \mid V \mid \underline{v_1}, \text{🔌} \mid \text{NV} \mid V \mid c_2) \in \underline{\mathcal{V}}[\mathbf{C}_{Unit}]^m$$


---

where  $v_1$  is...

n

false

↓  (↑ c )

↑ c

true

skip

 (↑ c )

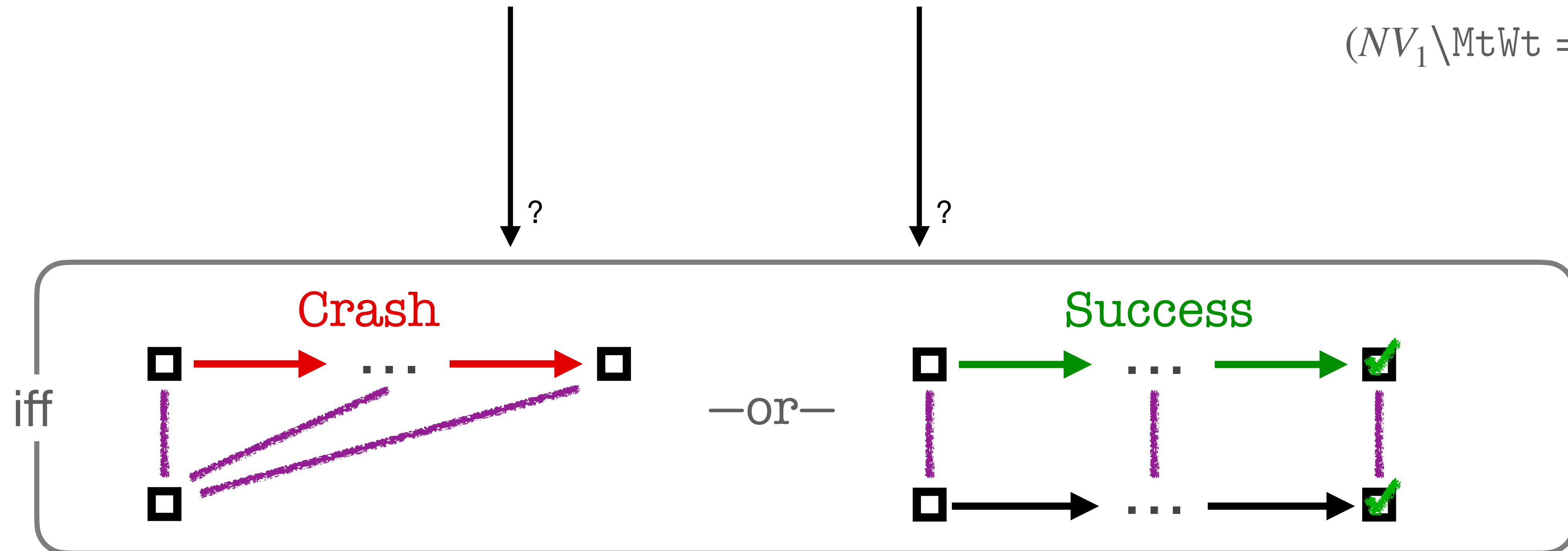
# No remaining power failures

$$\left( \begin{array}{c} \text{🔋} \\ \text{I NV I V I } c, \end{array} \begin{array}{c} \text{🔌} \\ \text{I NV I V I } c \end{array} \right) \in \mathcal{E} \llbracket C_{Unit} \rrbracket^{\text{10}}$$

# A power failure is possible!

$$\left( \begin{array}{c} \text{Battery Icon} \\ \text{NV}_1 \mid V \mid c \end{array}, \begin{array}{c} \text{Power Plug Icon} \\ \text{NV}_2 \mid V \mid c \end{array} \right) \in \mathcal{E} \llbracket C_{Unit} \rrbracket^{k+1}$$

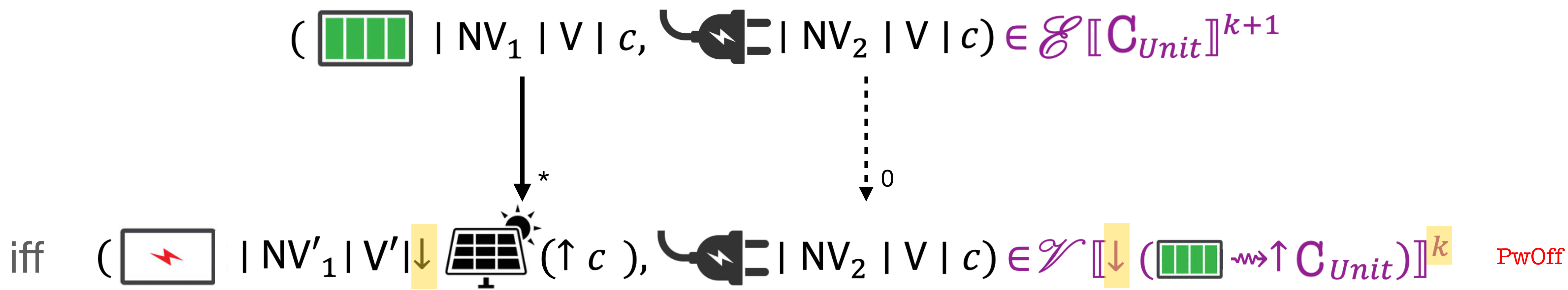
(NV<sub>1</sub> \setminus MtWt = NV<sub>2</sub> \setminus MtWt)



# If there is a power failure...

$$( \text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c ) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

# Device powers off



# Harvest energy from the environment



# Execution state is restored

$$(\text{[Full Battery]} \mid NV_1 \mid V \mid c, \text{[Plugged]} \mid NV_2 \mid V \mid c) \in \mathcal{E} \llbracket C_{Unit} \rrbracket^{k+1}$$



$$\text{iff } (\text{[Empty Battery]} \mid NV'_1 \mid V' \mid \downarrow, \text{[Plugged]} \mid NV_2 \mid V \mid c) \in \mathcal{V} \llbracket \downarrow (\text{[Full Battery]} \rightsquigarrow \uparrow C_{Unit}) \rrbracket^k \quad \text{PwOff}$$

$$\text{iff } (\text{[Empty Battery]} \mid NV'_1 \mid \text{[Solar Panel]} \mid (\uparrow c), \text{[Plugged]} \mid NV_2 \mid V \mid c) \in \mathcal{V} \llbracket \text{[Full Battery]} \rightsquigarrow \uparrow C_{Unit} \rrbracket^k \quad \text{Harvest}$$

$$\text{iff } (\text{[Full Battery]} \mid NV'_1 \mid \text{[Up Arrow]} \mid c, \text{[Plugged]} \mid NV_2 \mid V \mid c) \in \mathcal{V} \llbracket \text{[Up Arrow]} C_{Unit} \rrbracket^k \quad \text{Restore}$$

# Prepare for re-execution

$$(\text{[Battery Icon]} \mid NV_1 \mid V \mid c, \text{[Plug Icon]} \mid NV_2 \mid V \mid c) \in \mathcal{E} \llbracket C_{Unit} \rrbracket^{k+1}$$

$$\begin{aligned} & \downarrow^* \quad \downarrow^0 \\ \text{iff } & (\text{[Lightning Bolt Icon]} \mid NV'_1 \mid V' \mid \downarrow \text{[Solar Panel Icon]} (\uparrow c), \text{[Plug Icon]} \mid NV_2 \mid V \mid c) \in \mathcal{V} \llbracket \downarrow (\text{[Battery Icon]} \rightsquigarrow \uparrow C_{Unit}) \rrbracket^k && \text{PwOff} \\ \text{iff } & (\text{[Lightning Bolt Icon]} \mid NV'_1 \mid \text{[Solar Panel Icon]} (\uparrow c), \text{[Plug Icon]} \mid NV_2 \mid V \mid c) \in \mathcal{V} \llbracket \text{[Battery Icon]} \rightsquigarrow \uparrow C_{Unit} \rrbracket^k && \text{Harvest} \\ \text{iff } & (\text{[Battery Icon]} \mid \underset{\text{Wtn}}{NV'_1} \mid \uparrow c, \text{[Plug Icon]} \mid NV_2 \mid V \mid c) \in \mathcal{V} \llbracket \uparrow C_{Unit} \rrbracket^k && \text{Restore} \\ \text{iff } & (\text{[Battery Icon]} \mid \underset{\text{MtWt}}{NV''_1} \mid V \mid c, \text{[Plug Icon]} \mid NV_2 \mid V \mid c) \in \mathcal{E} \llbracket C_{Unit} \rrbracket^k && \text{Re-execution} \end{aligned}$$

V restored

$$(NV'_1 \setminus \text{MtWt} = NV_2 \setminus \text{MtWt})$$

# If there is no power failure...

$$(\text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbf{C}_{Unit}]^{k+1}$$

# Stable values are committed

$$( \boxed{\text{||||}} \mid NV_1 \mid V \mid c , \text{⚡} \mid NV_2 \mid V \mid c ) \in \mathcal{E} [\mathbf{C}_{Unit}]^{k+1}$$

↓<sub>*n*</sub>

↓<sub>*n*</sub>

iff

$$( \boxed{\text{||||}} \mid NV'_1 \mid V' \mid \text{skip} , \text{⚡} \mid NV'_2 \mid V' \mid \text{skip} ) \in \mathcal{V} [\downarrow \uparrow unit]^k$$

Commit

# We are done!

$$(\text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbf{C}_{Unit}]^{k+1}$$

↓<sub>*n*</sub>

↓<sub>*n*</sub>

iff

$$(\text{🔋} \mid NV'_1 \mid V' \mid \text{skip}, \text{🔌} \mid NV'_2 \mid V' \mid \text{skip}) \in \mathcal{V}[\downarrow \uparrow unit]^k$$

Commit

iff

$$(\text{🔋} \mid NV''_1 \mid V' \mid \text{skip}, \text{🔌} \mid NV''_2 \mid V' \mid \text{skip}) \in \mathcal{V}[\uparrow unit]^k$$

Success!  
( $NV''_1 = NV''_2$ )

# Outline

- Intermittent computing
- Overview
- Type system
- Logical relation
- **JIT mode**
- Key theorems
- Conclusion

# Real programs don't always use Ckpt

- intermittent systems default to JIT mode
- checkpoints everything “just-in-time”
- no re-execution
- hybrid JIT+Ckpt programs

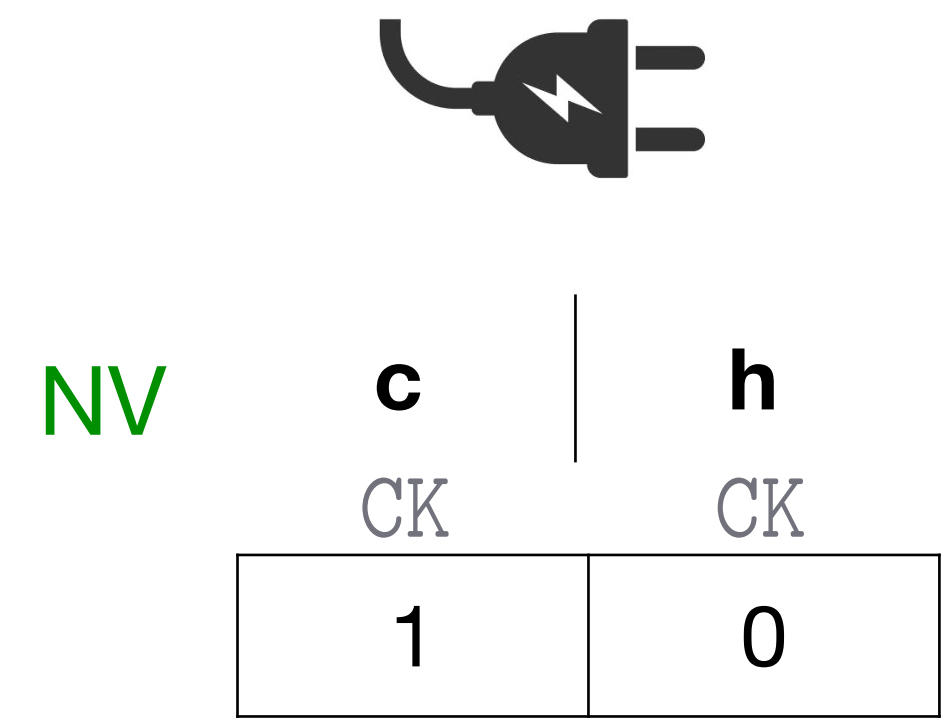
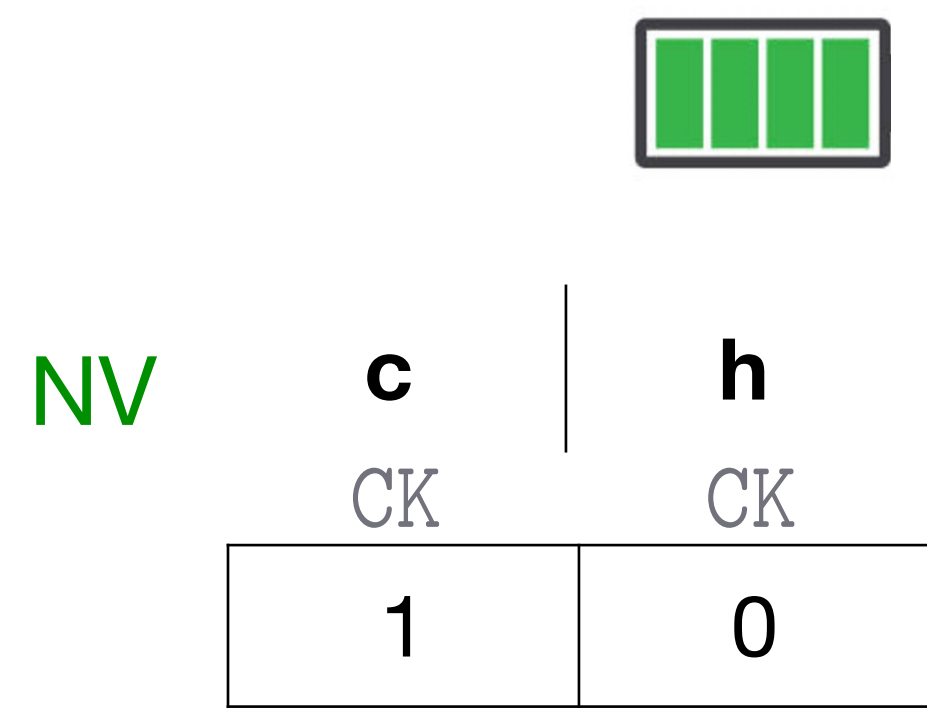
```
Ckpt(y)
  x := y;
  y := z;
  w := x + y;
```



```
let x = 5 in
  c := x + 1;
  h := c
```

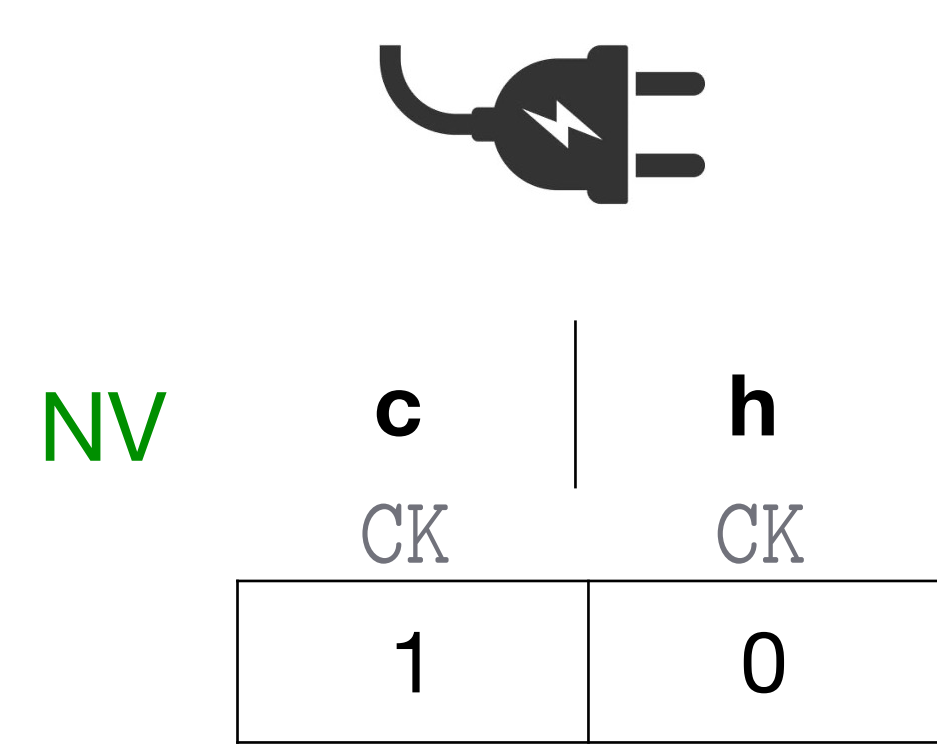
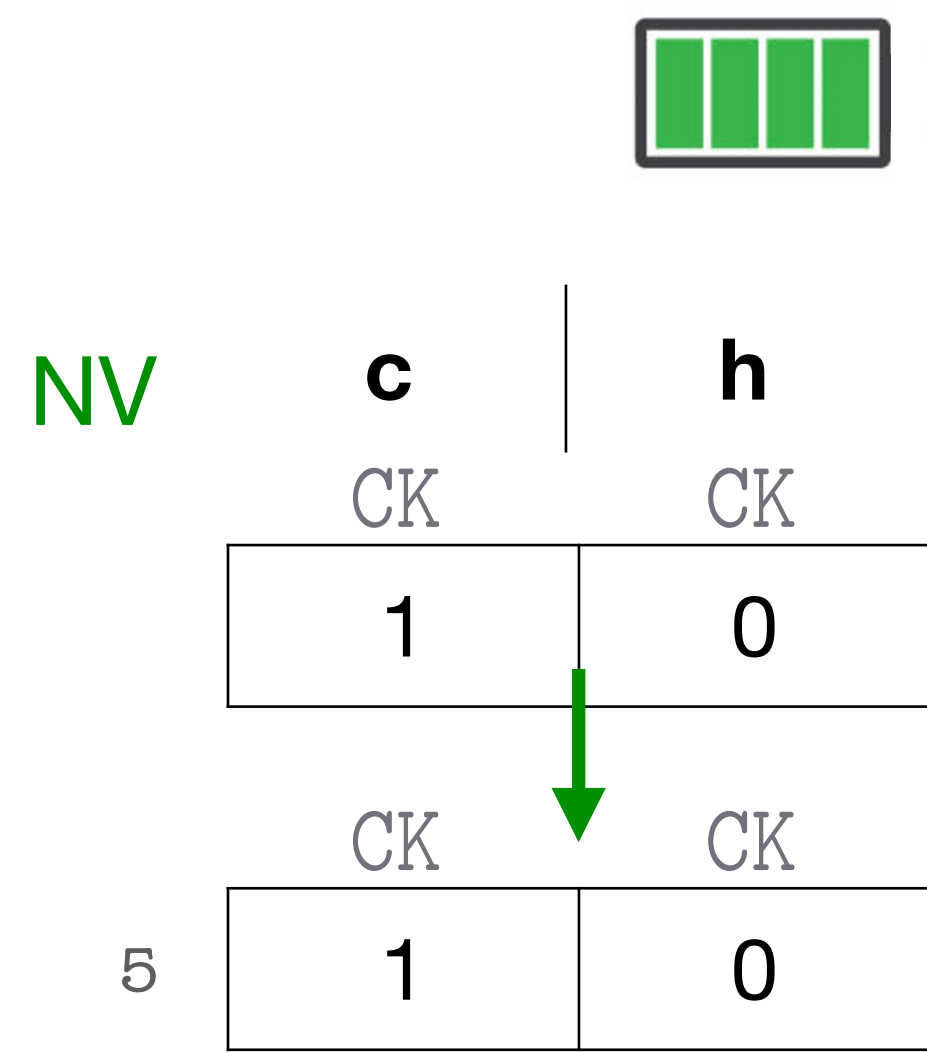
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



```

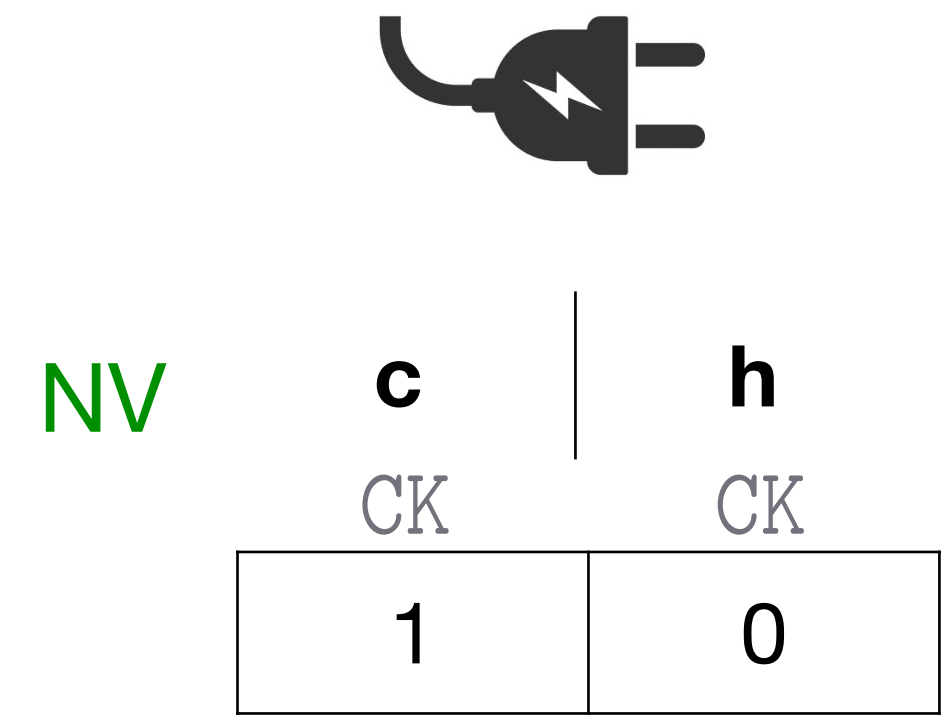
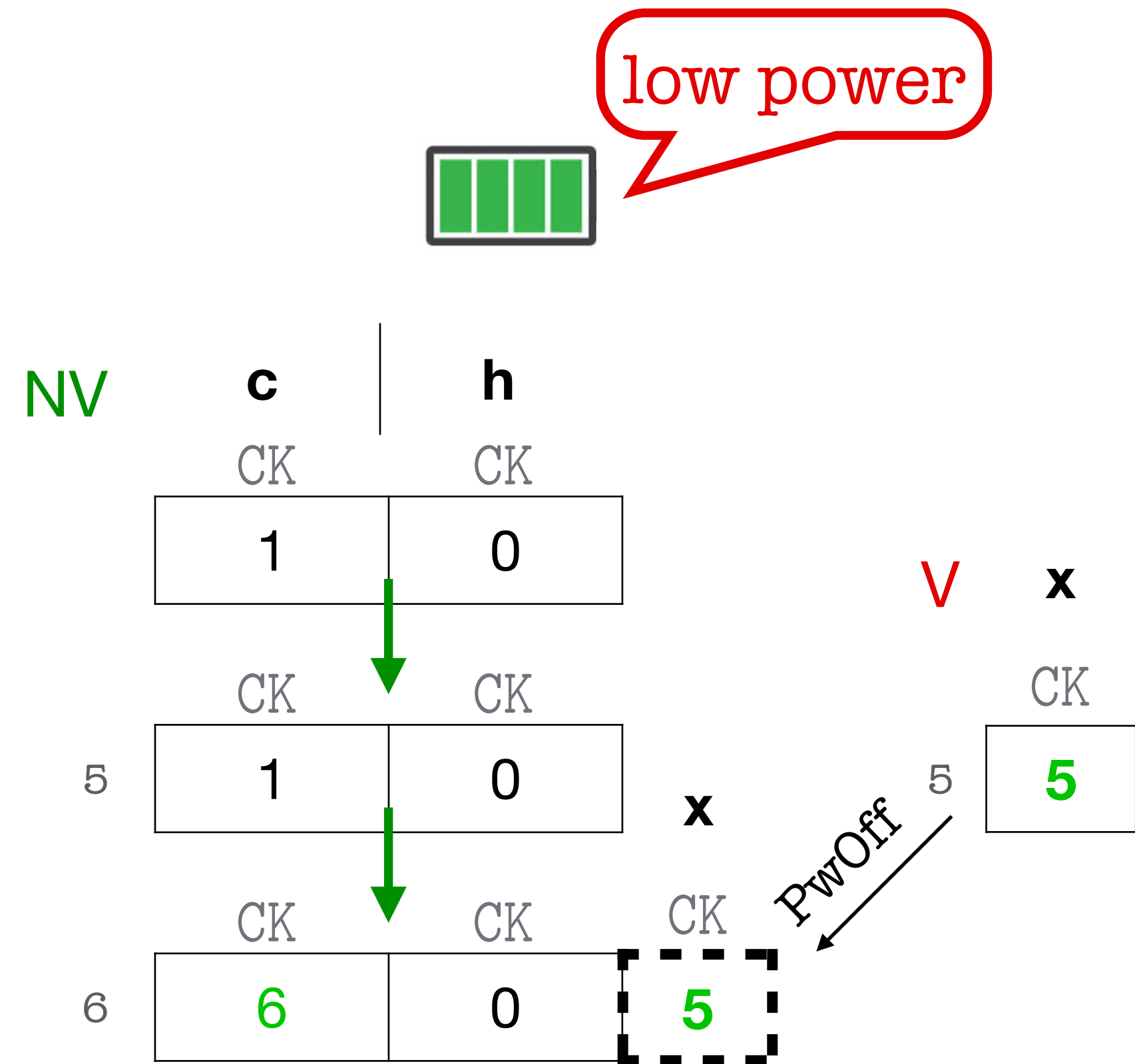
5  let x = 5 in
6      c := x + 1;
7  h := c

```



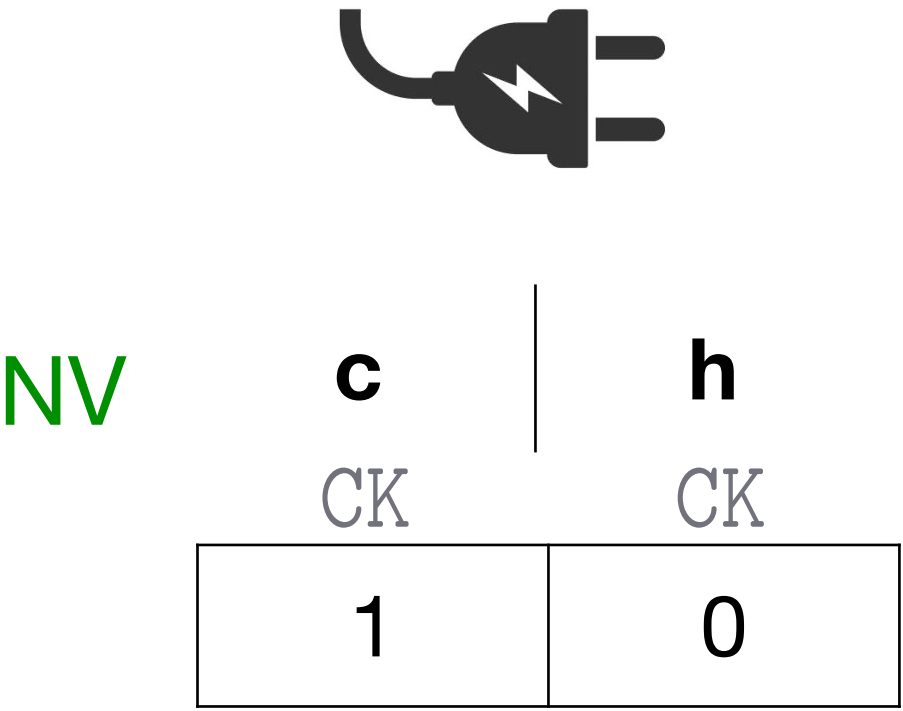
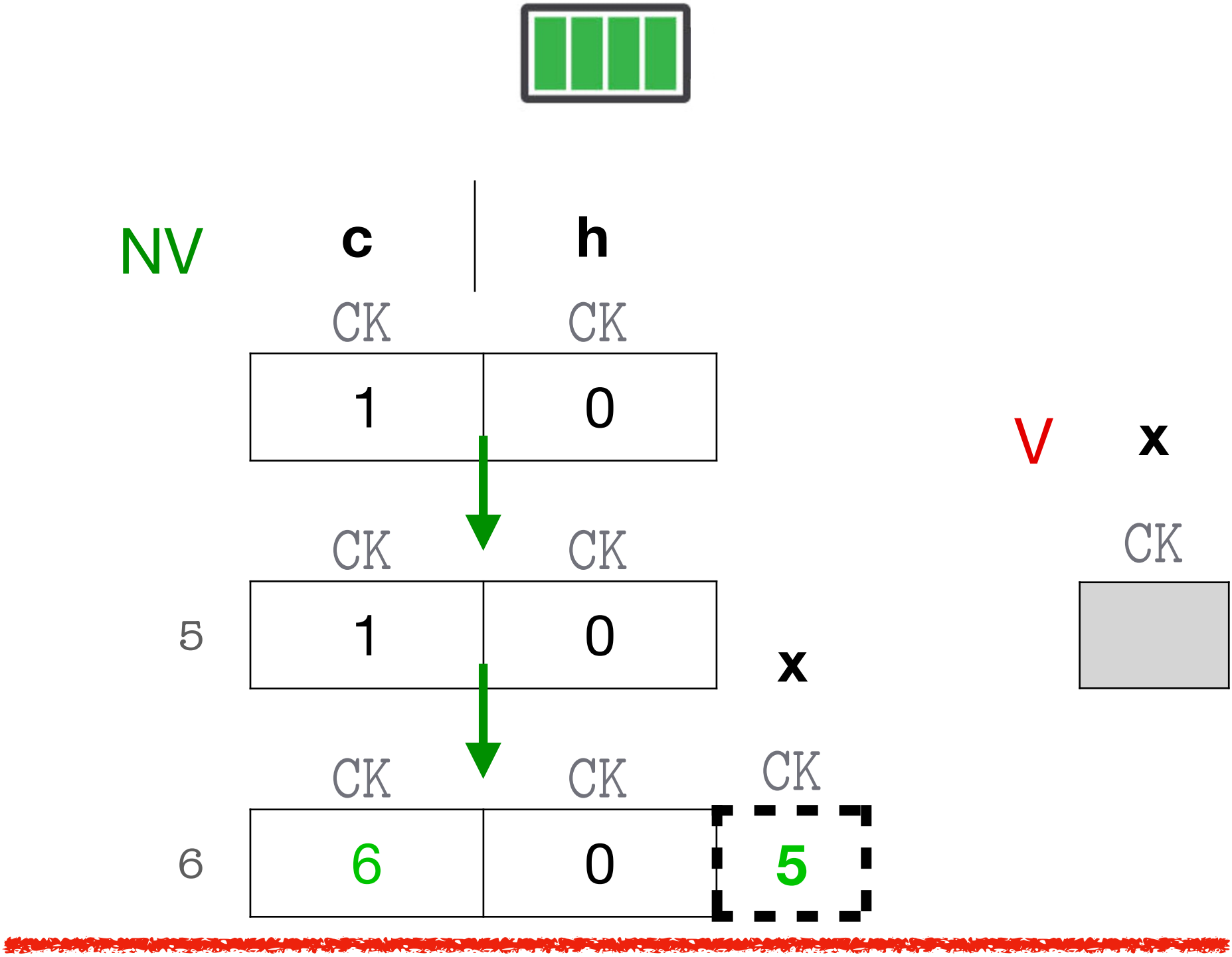
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



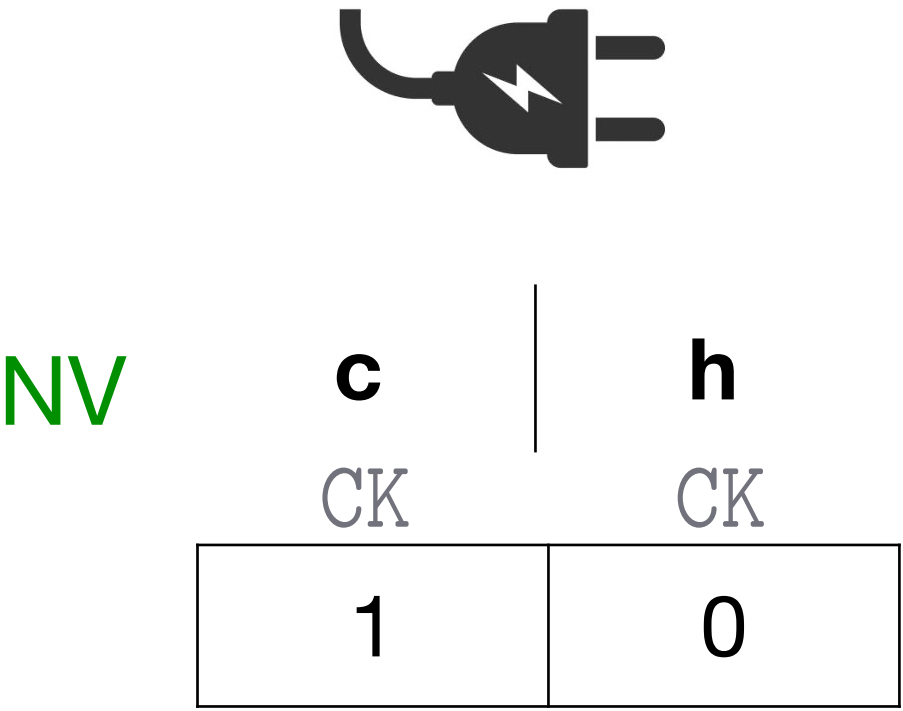
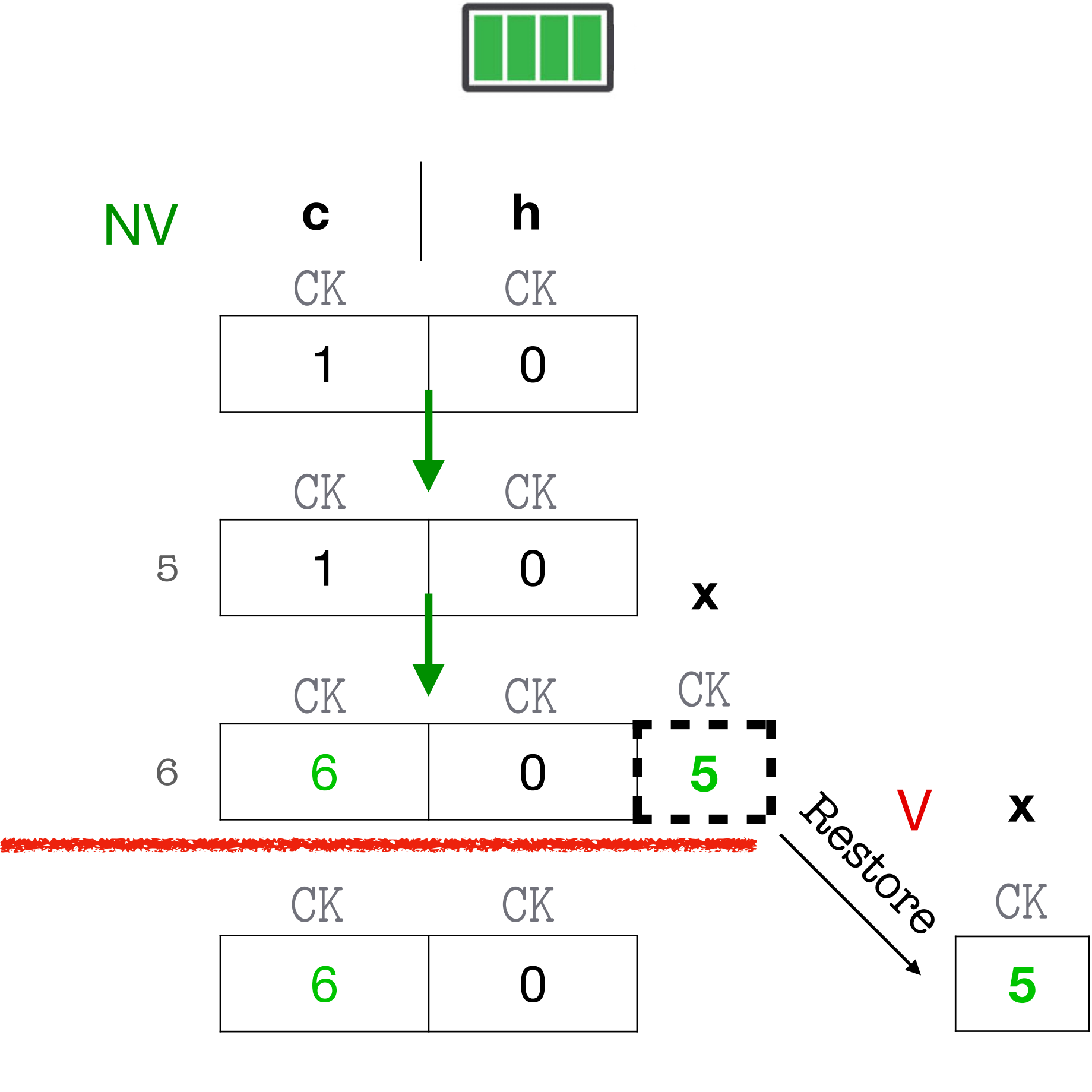
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



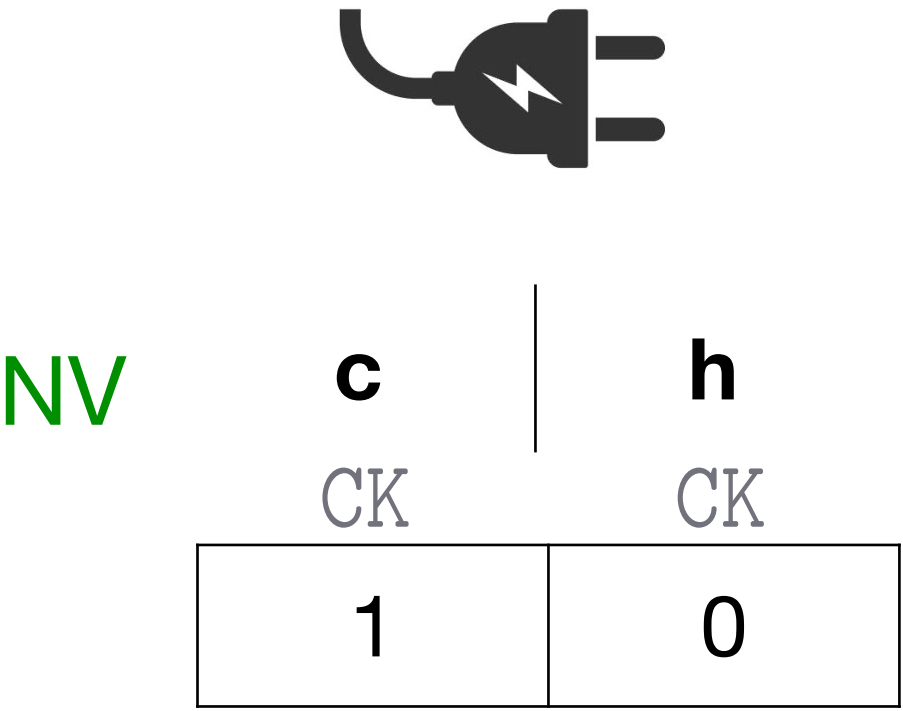
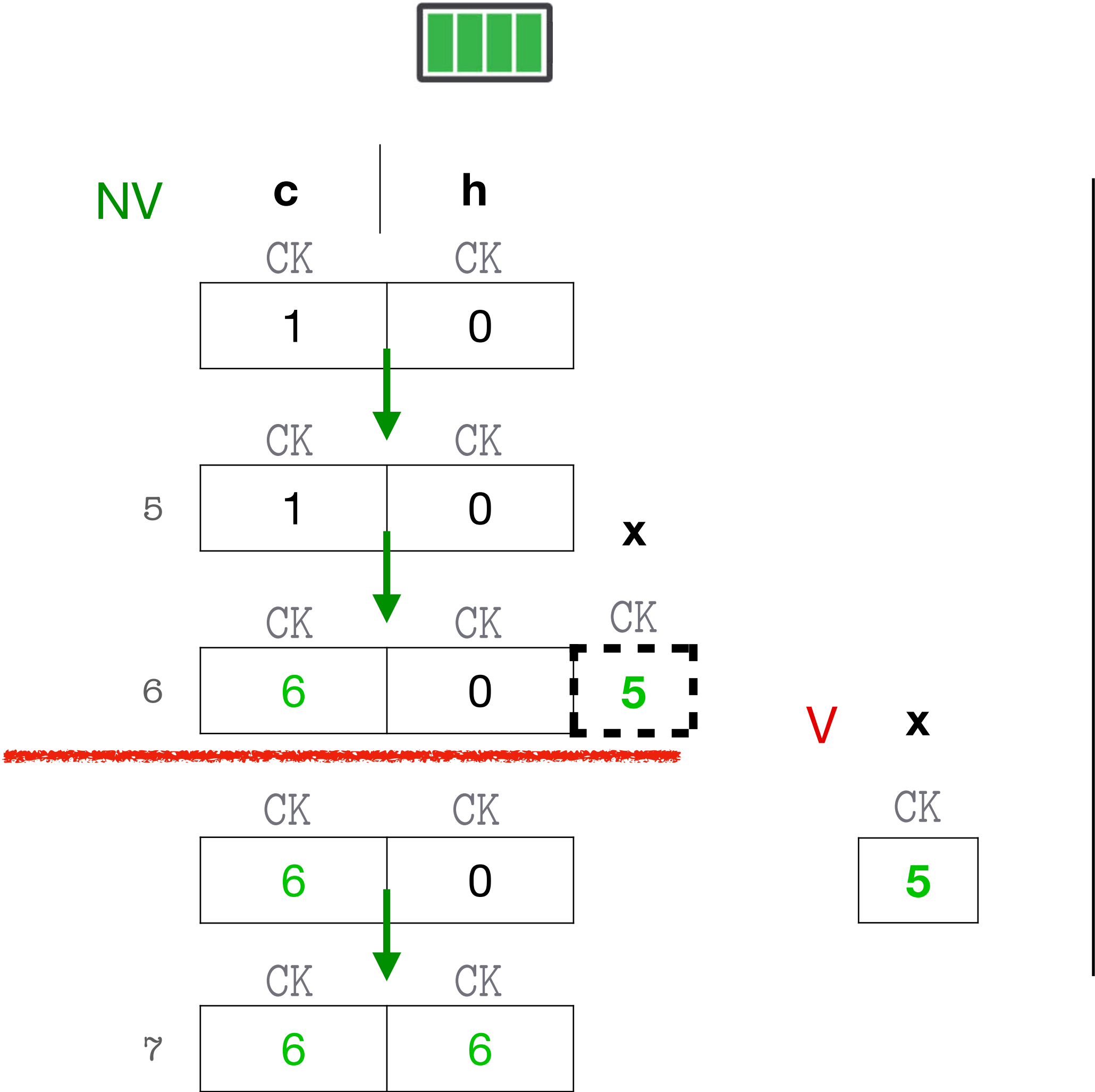
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



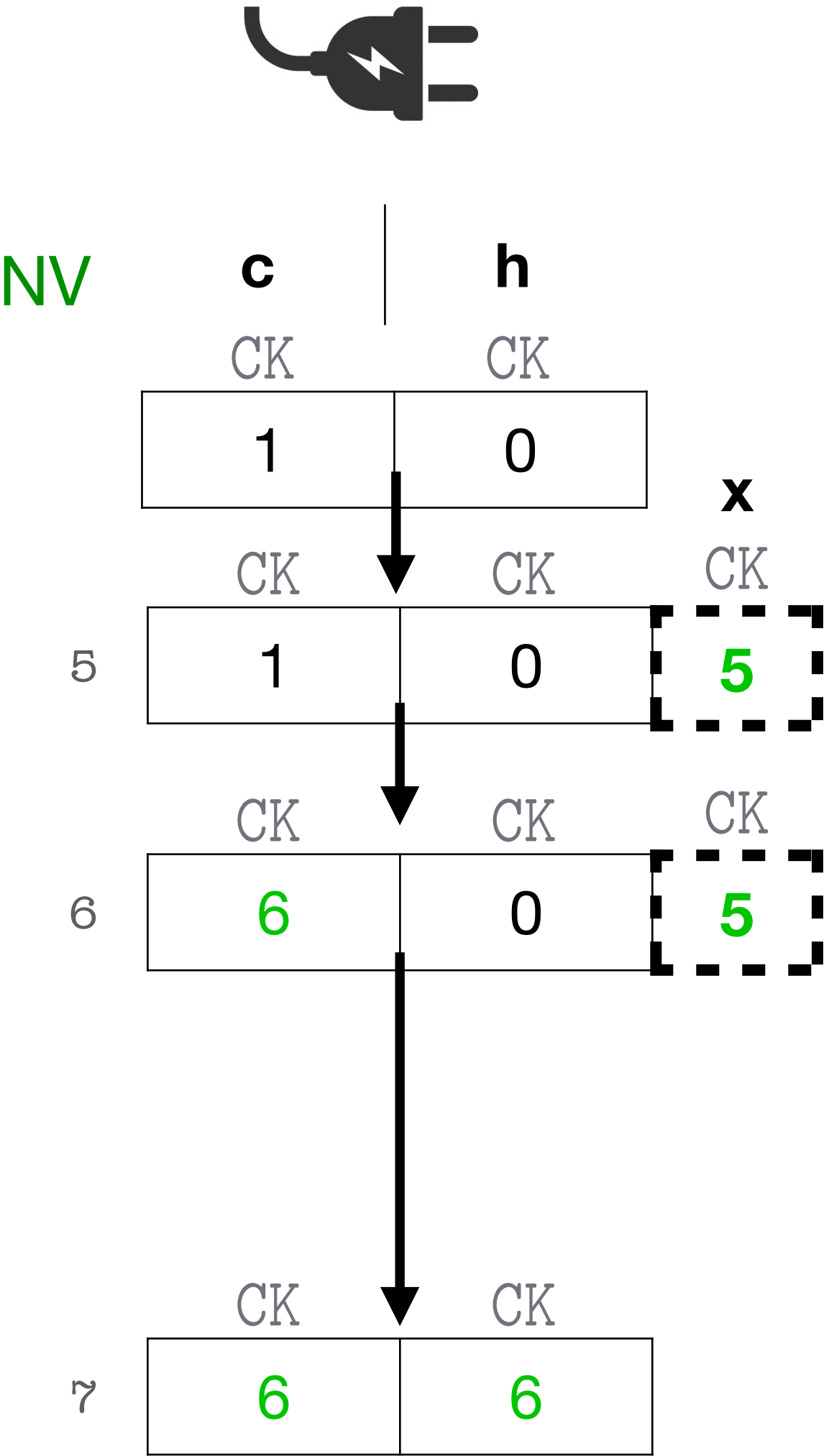
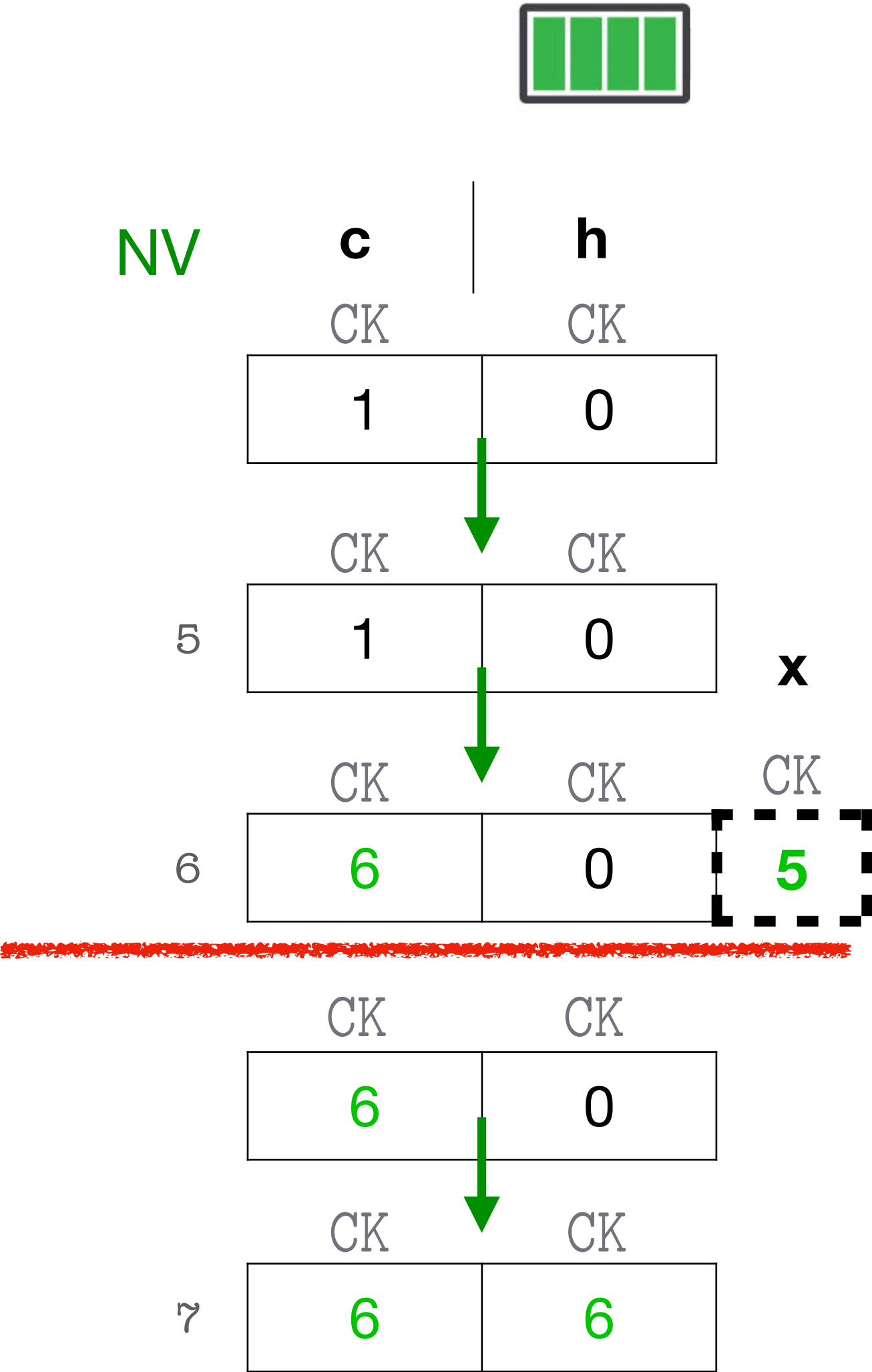
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



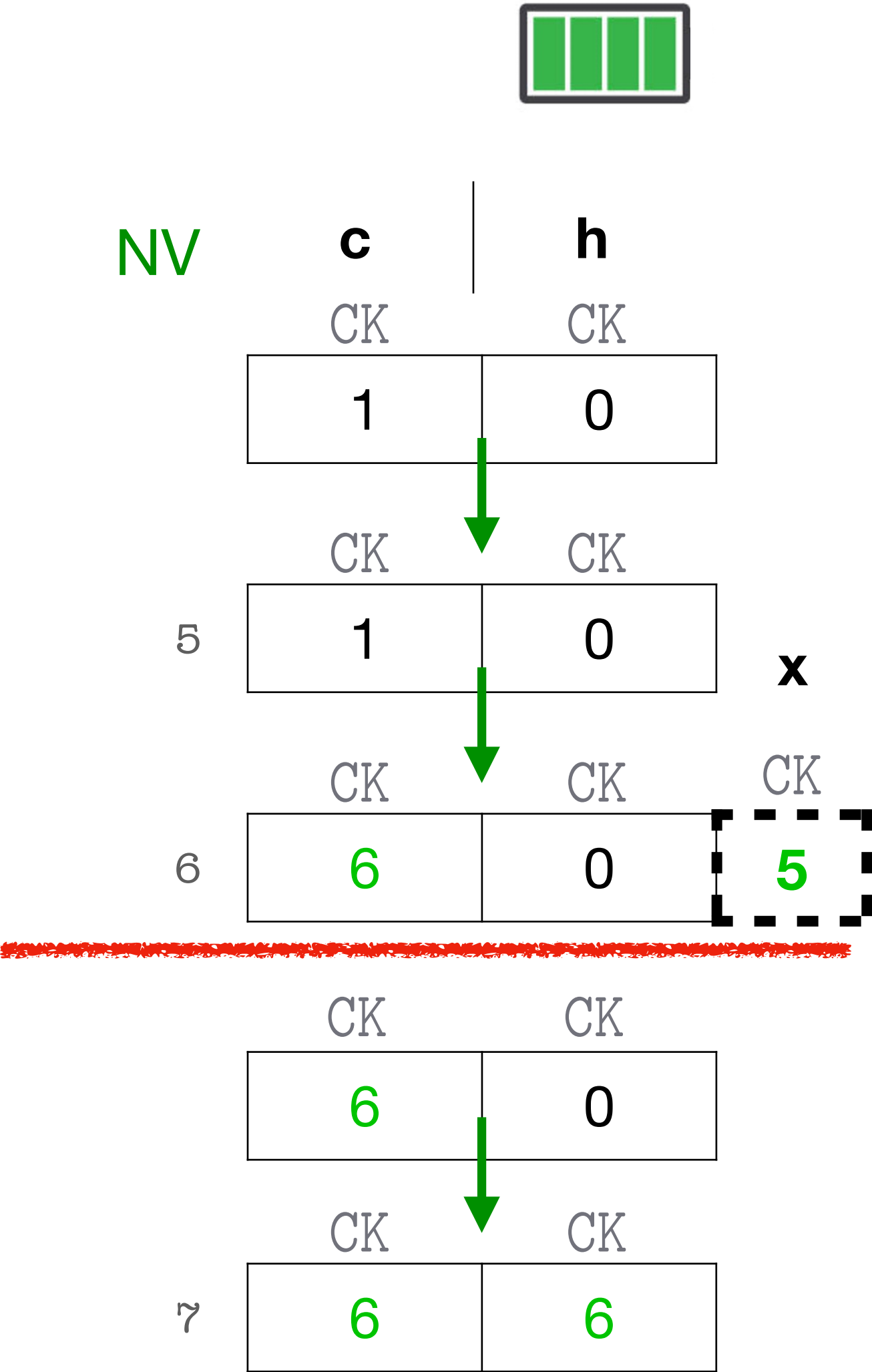
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



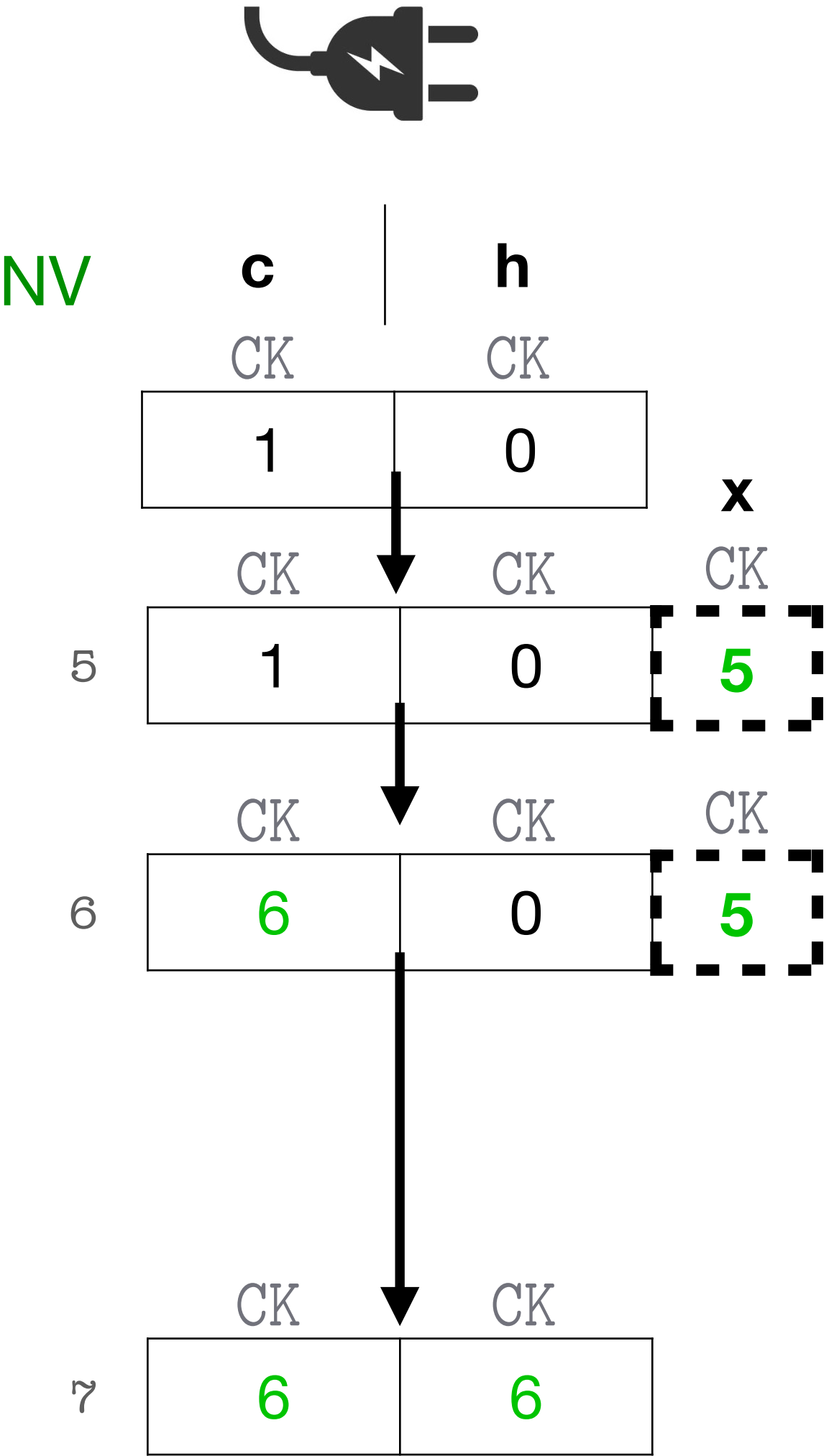
# Example

```
5 let x = 5 in
6   c := x + 1;
7   h := c
```



=

=



=

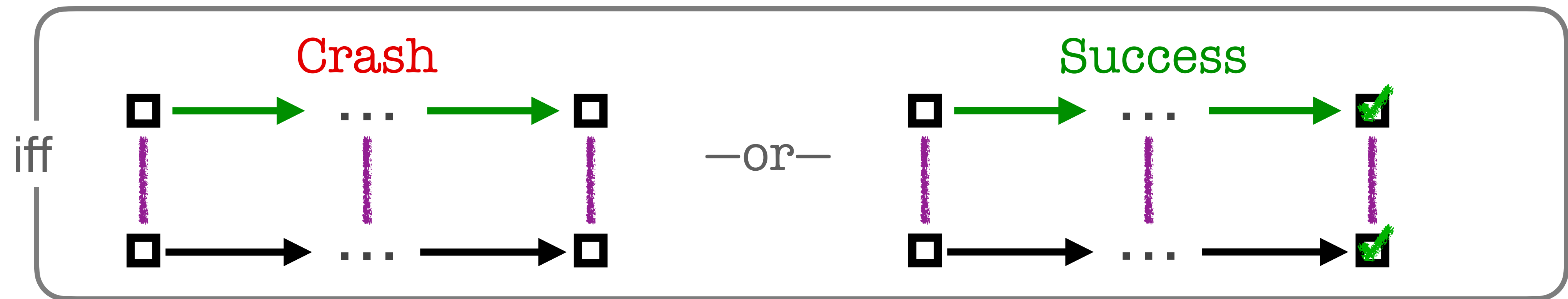
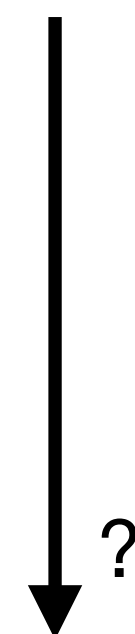
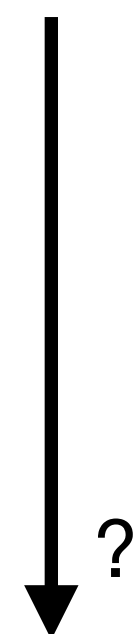
# Logical Relation for JIT

$$( \text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c ) \in \mathcal{E} [\mathbf{C}_{Unit}]^{k+1}$$

Same great structure,  
different **PwOff** and **Restore**!

# Logical Relation for JIT

$$( \text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c ) \in \mathcal{E} [\mathbf{C}_{Unit}]^{k+1}$$

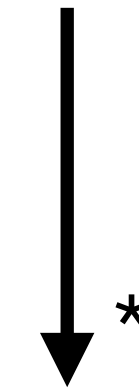
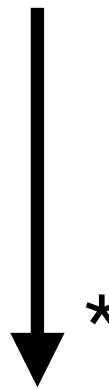


# If there is a power failure...

$$( \text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c ) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

# Device powers off

$$(\text{[Battery Full Icon]} \mid NV_1 \mid V \mid c, \text{[Plug Icon]} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathcal{C}_{Unit}]^{k+1}$$



iff  $(\text{[Battery Low Icon]} \mid NV'_1 \mid V' \mid \downarrow, \text{[Monitor Icon]} \mid (\uparrow c'), \text{[Plug Icon]} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\downarrow (\text{[Battery Full Icon]} \rightsquigarrow \uparrow \mathcal{C}_{Unit})]^k \quad \text{PwOff}$

# Harvest energy from the environment

$$(\text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

$$\begin{aligned} & \downarrow^* \qquad \qquad \downarrow^* \\ \text{iff } & (\text{⚡} \mid NV'_1 \mid V' \mid \downarrow \text{🌞} (\uparrow c'), \text{🔌} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\downarrow (\text{🔋} \rightsquigarrow \uparrow \mathbb{C}_{Unit})]^k \quad \text{PwOff} \\ \text{iff } & (\text{⚡} \mid NV''_1 \mid \text{🌞} (\uparrow c'), \text{🔌} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\text{🔋} \rightsquigarrow \uparrow \mathbb{C}_{Unit}]^k \quad \begin{array}{l} \text{Harvest} \\ \text{(for all } \text{🔋} \text{)} \end{array} \end{aligned}$$

# Execution state is restored

$$(\text{[Full Battery]} \mid NV_1 \mid V \mid c, \text{[Plugged]} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

$$\begin{aligned} & \downarrow^* \qquad \downarrow^* \\ \text{iff } & (\text{[Empty Battery]} \mid NV'_1 \mid V' \mid \downarrow \text{[Solar Panel]} (\uparrow c'), \text{[Plugged]} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\downarrow (\text{[Full Battery]} \rightsquigarrow \uparrow \mathbb{C}_{Unit})]^k && \text{PwOff} \\ \text{iff } & (\text{[Empty Battery]} \mid NV''_1 \mid \text{[Solar Panel]} (\uparrow c'), \text{[Plugged]} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\text{[Full Battery]} \rightsquigarrow \uparrow \mathbb{C}_{Unit}]^k && \text{Harvest} \\ \text{iff } & (\text{[Full Battery]} \mid NV''_1 \mid \uparrow c', \text{[Plugged]} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\uparrow \mathbb{C}_{Unit}]^k && \text{Restore} \end{aligned}$$

# Prepare for re-execution

$$(\text{🔋} \mid NV_1 \mid V \mid c, \text{🔌} \mid NV_2 \mid V \mid c) \in \mathcal{E}[\mathbb{C}_{Unit}]^{k+1}$$

$$\begin{array}{c} \downarrow^* \qquad \qquad \qquad \downarrow^* \\ \text{iff } (\text{⚡} \mid NV'_1 \mid V' \mid \downarrow \text{🖥️}(\uparrow c'), \text{🔌} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\downarrow (\text{🔋} \rightsquigarrow \uparrow \mathbb{C}_{Unit})]^k \quad \text{PwOff} \end{array}$$

$$\text{iff } (\text{⚡} \mid NV''_1 \mid \text{🖥️}(\uparrow c'), \text{🔌} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\text{🔋} \rightsquigarrow \uparrow \mathbb{C}_{Unit}]^k \quad \text{Harvest}$$

$$\text{iff } (\text{🔋} \mid NV''_1 \mid \uparrow c', \text{🔌} \mid NV'_2 \mid V' \mid c') \in \mathcal{V}[\uparrow \mathbb{C}_{Unit}]^k \quad \text{Restore}$$

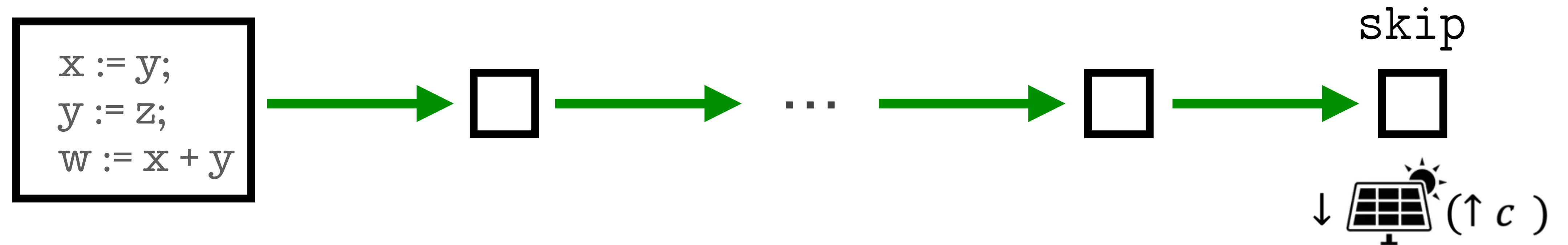
$$\text{iff } (\text{🔋} \mid NV''_1 \mid V' \mid c', \text{🔌} \mid NV'_2 \mid V' \mid c') \in \mathcal{E}[\mathbb{C}_{Unit}]^k \quad \text{Re-execution}$$

$(NV''_1 = NV'_2)$

# Outline

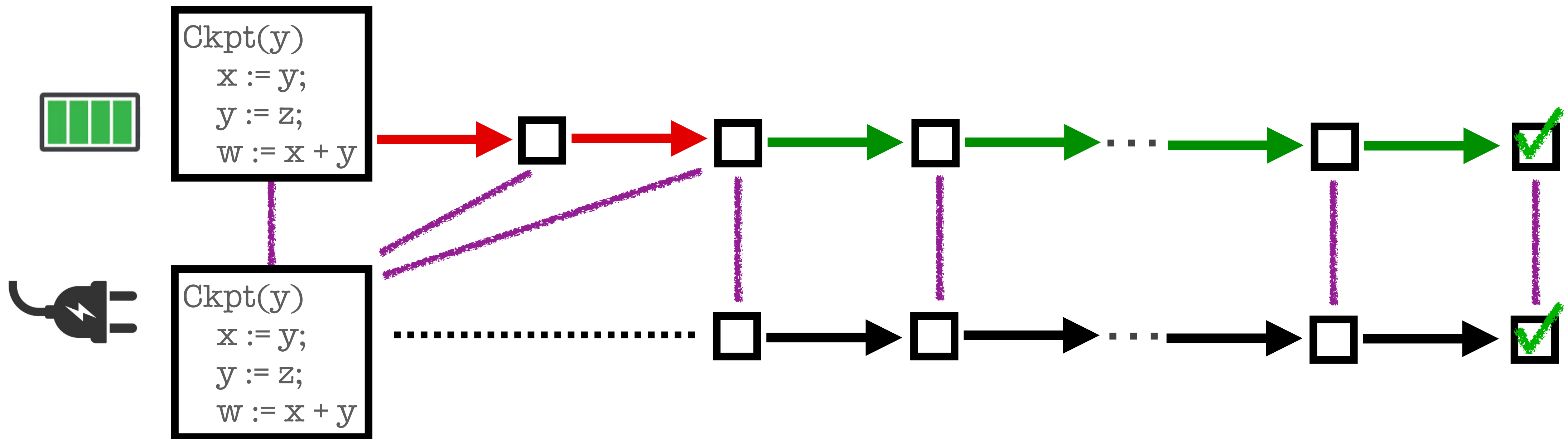
- Intermittent computing
- Overview
- Type system
- Logical relation
- JIT mode
- **Key theorems**
- Conclusion

# Progress and Preservation



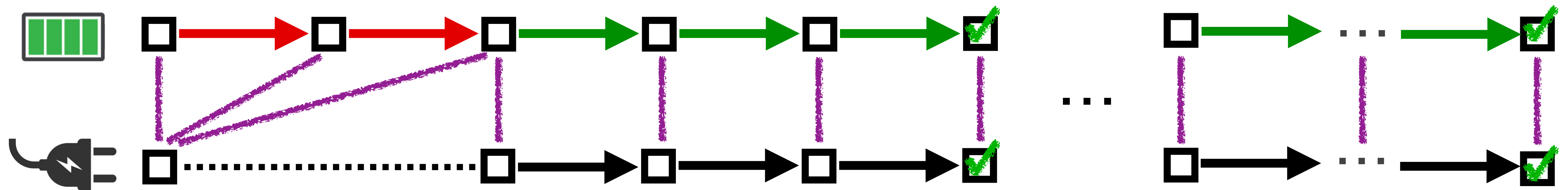
**Well-typed code doesn't get stuck and stays well-typed**

# Fundamental Theorem of Logical Relation



**Well-typed Atomic and JIT regions are self-related**

# Adequacy



**Every intermittent execution of a well-typed program can be simulated by its continuous execution**

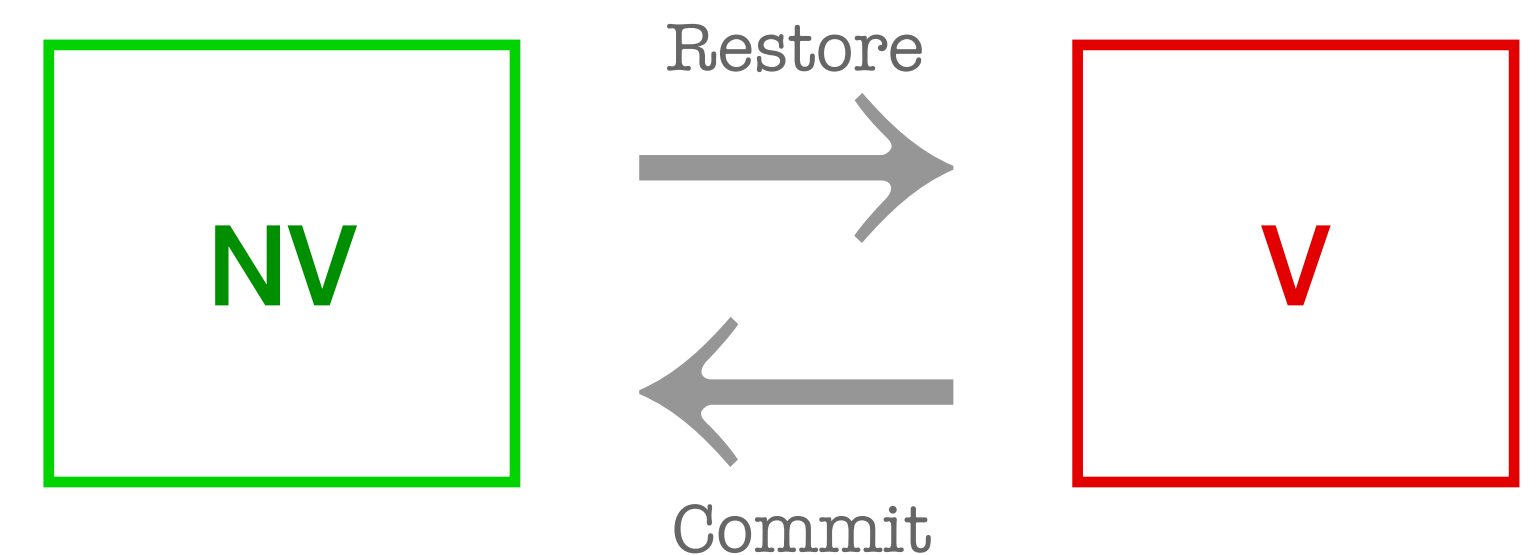


# Outline

- Intermittent computing
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- Key theorems
- **Conclusion**

# In this work, we developed...

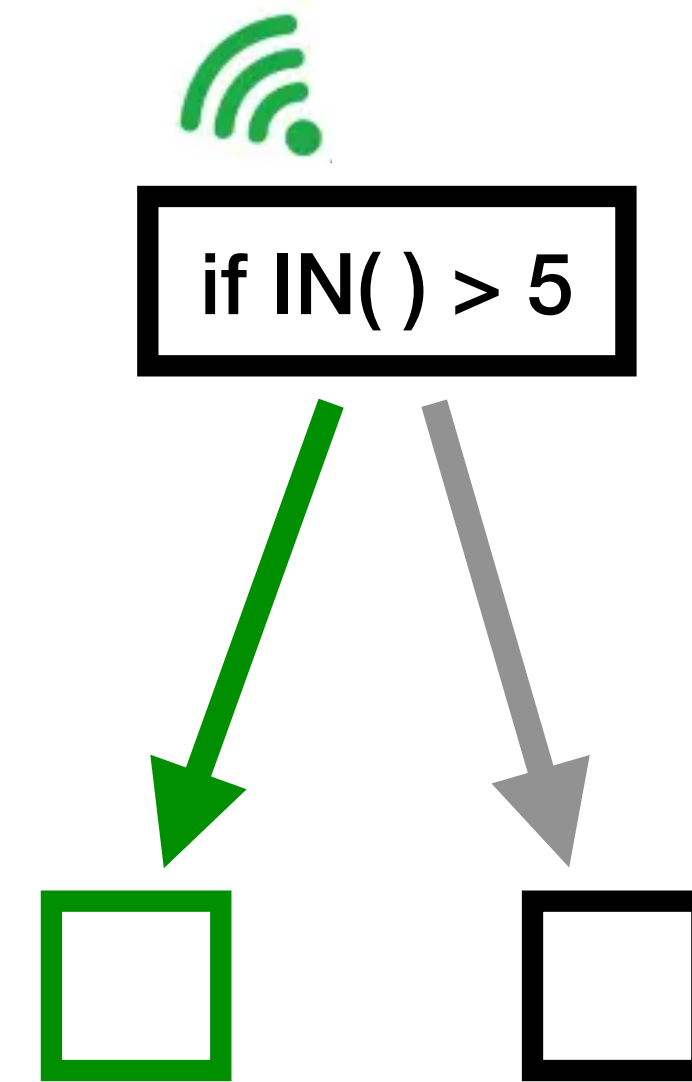
- One of the first type systems for intermittent computing
- First logical interpretation of key operations of intermittent execution
- A calculus for Crash types with type soundness
- A novel logical relation to characterize correctness



$$C = \downarrow \uparrow \text{unit } v \downarrow (nat \rightsquigarrow \uparrow C)$$

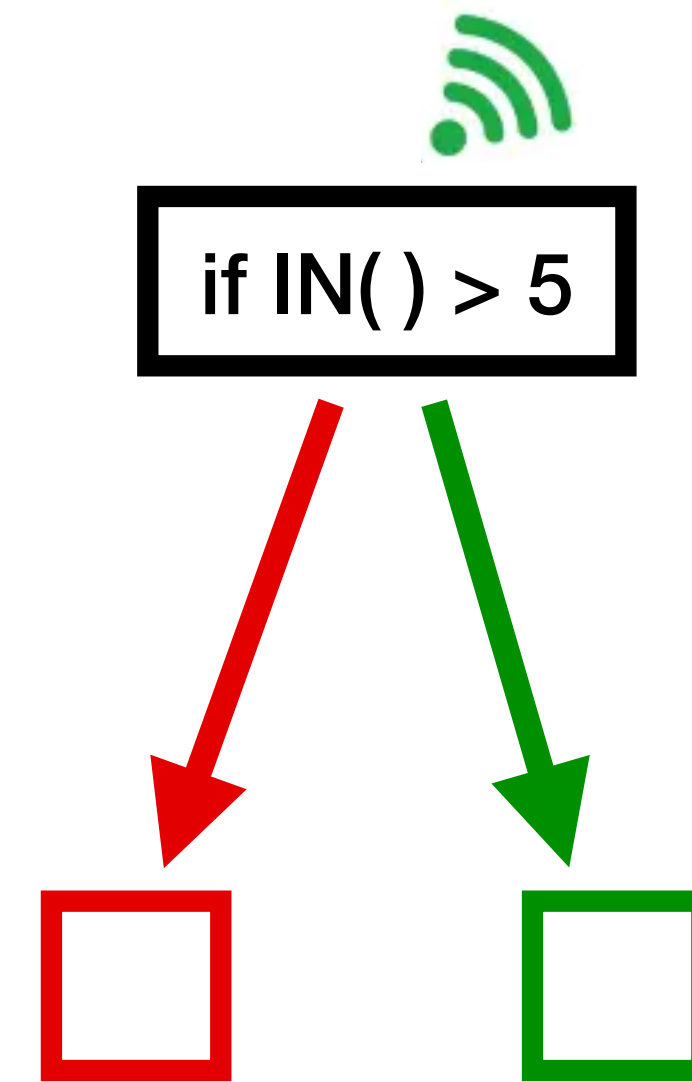
# Future work

- Repeated I/O bugs



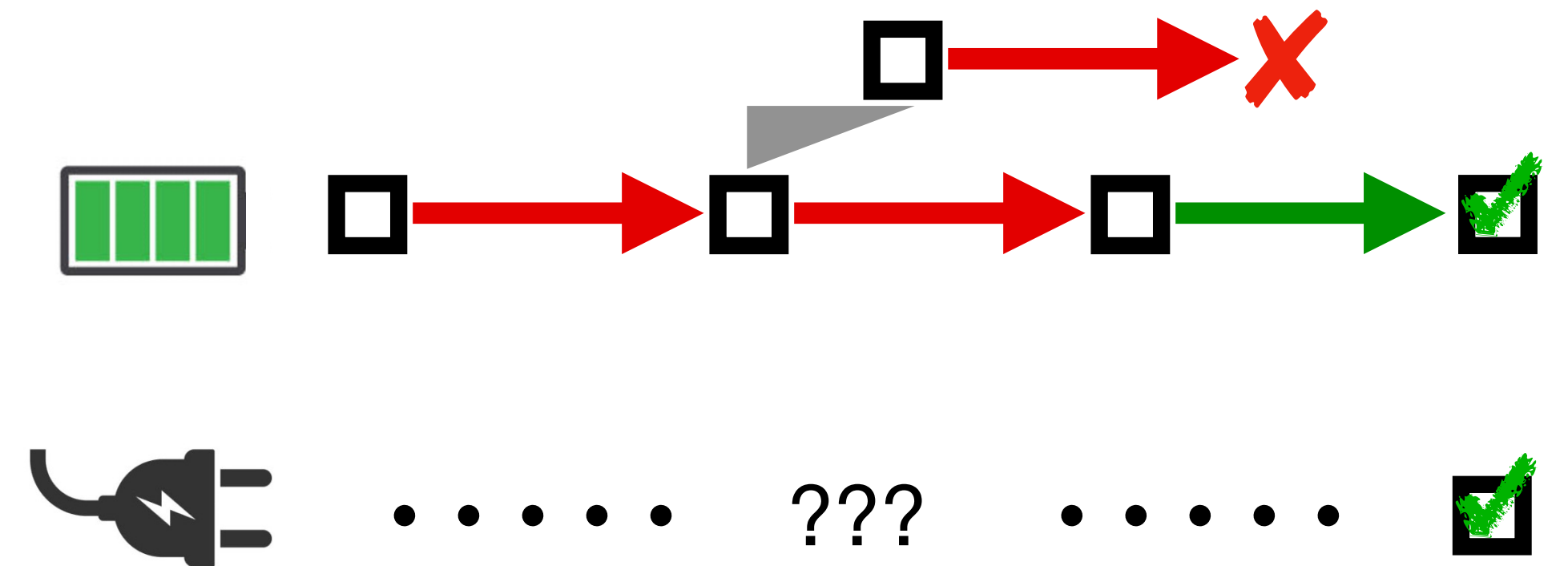
# Future work

- Repeated I/O bugs



# Future work

- Repeated I/O bugs
- Shared memory concurrency



# Future work

- Repeated I/O bugs
- Shared memory concurrency
- Other systems crash too!

$$C = \underset{\text{Commit}}{\downarrow} \underset{\text{PwOff}}{\uparrow} \text{unit } v \underset{\text{Restore}}{\downarrow} (\text{[||||]} \rightsquigarrow \uparrow C)$$

# Modal Crash Types for Intermittent Computing

**Myra Dotzel**  
**PhD student, CSD, CMU**

**Joint work with Farzaneh Derakhshan,  
Milijana Surbatovich, and Limin Jia**

